

## LECTURE NOTES 24

### MAXWELL'S EQUATIONS

Thus far, we have the following four Maxwell equations (in differential form):

|  |   |  |
|--|---|--|
| Divergence and curl<br>of both $\vec{E}$ and $\vec{B}$<br>specified $\Rightarrow$<br>nature of $\vec{E}$ and $\vec{B}$<br>is fully defined | } | $\vec{\nabla} \cdot \vec{E}(\vec{r}) = \frac{1}{\epsilon_0} \rho_{\text{Tot}}(\vec{r}) \quad (\text{Gauss' Law})$ $\vec{\nabla} \cdot \vec{B}(\vec{r}) = 0 \quad \left\{ \begin{array}{l} \text{no magnetic monopoles} \\ \text{no magnetic charges} \end{array} \right.$ $\vec{\nabla} \times \vec{E}(\vec{r}) = -\frac{\partial \vec{B}(\vec{r})}{\partial t} \quad (\text{Faraday's Law})$ $\vec{\nabla} \times \vec{B}(\vec{r}) = \mu_0 \vec{J}_{\text{Tot}}(\vec{r}) \quad (\text{Ampere's Law})$ |
|--|---|--|

However, there is a problem with this set of equations...

Recall that  $\vec{\nabla} \cdot (\vec{\nabla}(\vec{r}) \times \vec{F}(\vec{r})) = 0$  always for an arbitrary vector field,  $\vec{F}(\vec{r})$ .

Apply this to Faraday's Law:

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{E}) = \vec{\nabla} \cdot \left( -\frac{\partial \vec{B}}{\partial t} \right) = -\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{B}) = 0 \quad \underline{\text{OK}}$$

Apply this to Ampere's Law:

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J}_{\text{Tot}}) = \mu_0 (\vec{\nabla} \cdot \vec{J}_{\text{Tot}})$$

For steady total currents:  $(\vec{\nabla} \cdot \vec{J}_{\text{Tot}}) = 0$  because  $\frac{\partial \rho_{\text{Tot}}}{\partial t} = 0$

However, for time-varying situations the continuity equation (total charge conservation)

$$\vec{\nabla} \cdot \vec{J}_{\text{Tot}} = -\frac{\partial \rho_{\text{Tot}}}{\partial t} \neq 0 \quad \text{BIG PROBLEM!!!}$$

Let us investigate Ampere's Law (in integral form) for the case of a parallel-plate capacitor:

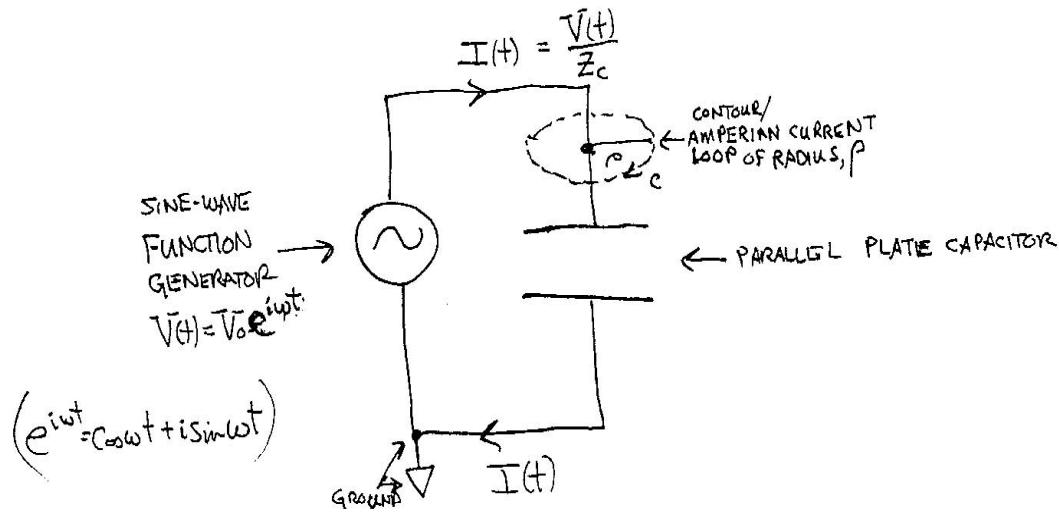
$$\int_S (\vec{\nabla} \times \vec{B}) \cdot d\vec{a} = \oint_C \vec{B} \cdot d\vec{\ell} = \mu_0 \int_S \vec{J} \cdot d\vec{a} = \mu_0 I_{\text{enclosed}}$$

$$\oint_C \vec{B} \cdot d\vec{\ell} = \mu_0 I_{\text{enclosed}}$$

Suppose we have an electric circuit consisting of sine wave function generator that supplies/generates a time dependent voltage  $V(t) = V_0 e^{i\omega t}$  and a parallel-plate capacitor:

Complex impedance of a capacitor:  $Z_C = \frac{1}{i\omega C}$      $\omega = 2\pi f$      $i \equiv \sqrt{-1}$      $\begin{pmatrix} i^* - i = +1 \\ i^* i = -1 \end{pmatrix}$

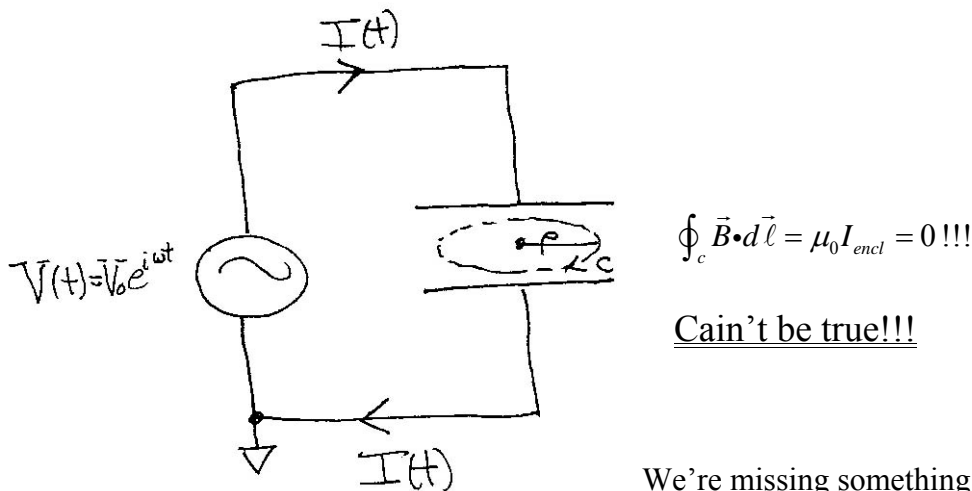
Complex form of Ohm's law:  $V(t) = I(t) Z_C$  n.b.  $V(t)$ ,  $I(t)$  and  $Z_C$  are complex quantities.



For contour loop shown in above figure:  $\oint_c \vec{B} \cdot d\vec{\ell} = \mu_0 I_{encl} = \mu_0 I$

Get:  $B(\rho) = \frac{\mu_0 I}{2\pi\rho}$  as usual – so no problem with this...

What about the following contour loop:



$$\oint_c \vec{B} \cdot d\vec{\ell} = \mu_0 I_{encl} = 0!!!$$

Cain't be true!!!

We're missing something! Energy flows across the gap between plates of parallel-plate capacitor... - virtual photons associated with electric field of ||-plate capacitor!

Let's look again at the continuity equation:

$$\vec{\nabla} \cdot \vec{J}_{ToT}(\vec{r}, t) = -\frac{\partial \rho_{ToT}(\vec{r}, t)}{\partial t}$$

But:  $\rho_{ToT}(\vec{r}, t) = \epsilon_0 \vec{\nabla} \cdot \vec{E}(\vec{r}, t)$  (Gauss' Law)

$$\therefore -\frac{\partial \rho_{ToT}(\vec{r}, t)}{\partial t} = -\epsilon_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}(\vec{r}, t)) = -\epsilon_0 \vec{\nabla} \cdot \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$$

or: 
$$\vec{\nabla} \cdot \vec{J}_{ToT}(\vec{r}, t) = -\epsilon_0 \vec{\nabla} \cdot \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$$

⇒ If we combine  $\epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$  with  $\vec{J}_{ToT}(\vec{r}, t)$  this “cures” the problem with Ampere's Law:

$$\vec{\nabla} \times \vec{B}(\vec{r}, t) = \mu_0 \left( \vec{J}_{ToT}(\vec{r}, t) + \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} \right) = \mu_0 \vec{J}_{ToT}(\vec{r}, t) + \epsilon_0 \mu_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$$

Then: 
$$\begin{aligned} \vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}(\vec{r}, t)) &= \mu_0 (\vec{\nabla} \cdot \vec{J}_{ToT}(\vec{r}, t)) + \epsilon_0 \mu_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}(\vec{r}, t)) \\ &= \mu_0 \left( -\frac{\partial \rho_{ToT}(\vec{r}, t)}{\partial t} \right) + \epsilon_0 \mu_0 \frac{\partial}{\partial t} \left[ \left( \frac{1}{\epsilon_0} \right) \rho_{ToT}(\vec{r}, t) \right] \\ &= -\mu_0 \frac{\partial \rho_{ToT}(\vec{r}, t)}{\partial t} + \mu_0 \frac{\partial \rho_{ToT}(\vec{r}, t)}{\partial t} = \mathbf{0!!!} \quad \text{YES INDEED!!} \end{aligned}$$

Note the aesthetic/pleasing symmetry:

If  $\vec{J}_{ToT}(\vec{r}, t) = 0$ , then 
$$\vec{\nabla} \times \vec{B}(\vec{r}, t) = \epsilon_0 \mu_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} = \frac{1}{c^2} \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$$
 “new” Ampere's Law

$$\vec{\nabla} \times \vec{E}(\vec{r}, t) = -\frac{\partial \vec{B}(\vec{r}, t)}{\partial t} \quad \text{(Faraday's Law)}$$

⇒ A changing electric field produces a magnetic field!

⇒ A changing magnetic field produces a electric field!

New term is known as Maxwell's displacement current: 
$$\vec{J}_D(\vec{r}, t) \equiv \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$$

New Ampere's Law:

$$\begin{aligned} \vec{\nabla} \times \vec{B}(\vec{r}, t) &= \mu_0 \vec{J}_{ToT}(\vec{r}, t) + \mu_0 \vec{J}_D(\vec{r}, t) \\ &= \mu_0 \vec{J}_{ToT}(\vec{r}, t) + \mu_0 \left( \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} \right) \end{aligned}$$

For the ||-plate capacitor, the electric field  $E(t) = \frac{\sigma(t)}{\epsilon_0}$

Where:  $\sigma(t) = Q(t)/A$  where  $A =$  area of one plate

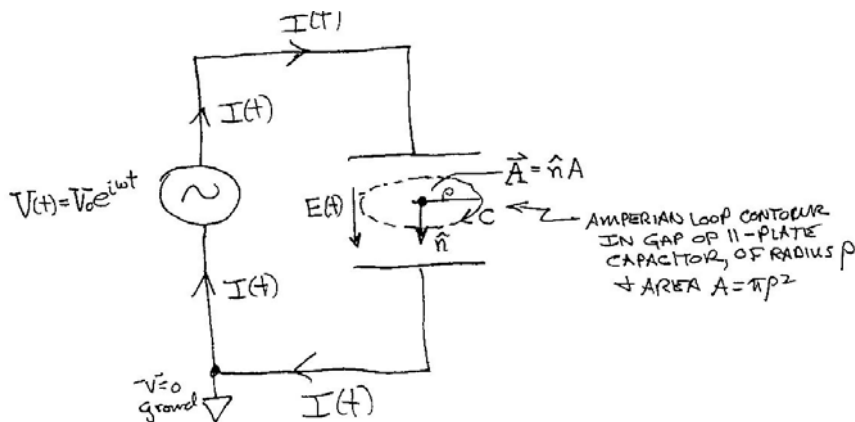
Thus:  $E(t) = \frac{\sigma(t)}{\epsilon_0} = \frac{Q(t)}{\epsilon_0 A}$

Thus:  $\frac{\partial E(t)}{\partial t} = \frac{1}{\epsilon_0 A} \frac{\partial Q(t)}{\partial t} = \frac{1}{\epsilon_0 A} I(t)$  where  $I(t) \equiv \frac{\partial Q(t)}{\partial t}$

Then:  $\int_S (\vec{\nabla} \times \vec{B}) \cdot d\vec{a} = \oint_C \vec{B} \cdot d\vec{\ell} = \mu_0 \int_S \vec{J}_{TOT} \cdot d\vec{a} + \mu_0 \int_S \vec{J}_D \cdot d\vec{a}$

Thus:  $\oint_C \vec{B} \cdot d\vec{\ell} = \mu_0 I_{TOT}^{encl} + \mu_0 \epsilon_0 \int_S \frac{\partial \vec{E}}{\partial t} \cdot d\vec{a}$

For ||-plate capacitor circuit with contour  $C$  taken inside the gap of the ||-plate capacitor:



$$\oint_C \vec{B} \cdot d\vec{\ell} = \mu_0 \overset{=0}{I_{TOT}^{encl}} + \mu_0 \epsilon_0 \int_S \frac{\partial \vec{E}}{\partial t} \cdot d\vec{a}$$

$$\vec{B}_{in\ gap}(\rho) = \frac{\mu_0}{2\mu} \left( \frac{1}{\epsilon_0 A} I(t) * A \right) = \frac{\mu_0}{2\pi\rho} I(t) \leftarrow \text{Same answer!!!}$$

Thus the four “new” Maxwell equations are:

$$\vec{\nabla} \cdot \vec{E}(\vec{r}, t) = \frac{1}{\epsilon_0} \rho_{\text{Tot}}(\vec{r}, t) \quad (\text{Gauss' Law})$$

$$\vec{\nabla} \cdot \vec{B}(\vec{r}, t) = 0 \quad (\text{no magnetic monopoles/magnetic charges})$$

$$\vec{\nabla} \times \vec{E}(\vec{r}, t) = -\frac{\partial \vec{B}(\vec{r}, t)}{\partial t} \quad (\text{Faraday's Law})$$

$$\begin{aligned} \vec{\nabla} \times \vec{B}(\vec{r}, t) &= \mu_0 \vec{J}_{\text{Tot}}(\vec{r}, t) + \mu_0 \vec{J}_D(\vec{r}, t) \\ &= \mu_0 \vec{J}_{\text{Tot}}(\vec{r}, t) + \mu_0 \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} \end{aligned} \quad (\text{Ampere's new Law})$$

Where:  $\vec{J}_D(\vec{r}, t) = \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$  (Maxwell's displacement current)

Force Law:  $\vec{F}_{\text{Tot}}(\vec{r}, t) = \vec{F}_E(\vec{r}, t) + \vec{F}_m(\vec{r}, t) = q\vec{E}(\vec{r}, t) + q\vec{v}(\vec{r}, t) \times \vec{B}(\vec{r}, t)$

Continuity equation:  $\vec{\nabla} \cdot \vec{J}_{\text{Tot}}(\vec{r}, t) = -\frac{\partial \rho_{\text{Tot}}(\vec{r}, t)}{\partial t}$   $\Leftarrow$  can now be derived from Maxwell's eqns!!  
(charge conservation)

Note that *if* magnetic charges  $g_m$  existed, then Maxwell's equations would become more “symmetrical”:

$$\vec{\nabla} \cdot \vec{E}(\vec{r}, t) = \frac{1}{\epsilon_0} \rho_{\text{Tot}}^E(\vec{r}, t) \quad (\text{Gauss' Law for electric charges})$$

$$\vec{\nabla} \cdot \vec{B}(\vec{r}, t) = \mu_0 \rho_{\text{Tot}}^m(\vec{r}, t) \quad (\text{Gauss' Law for magnetic charges})$$

$$\vec{\nabla} \times \vec{E}(\vec{r}, t) = -\mu_0 \vec{J}_{\text{Tot}}^m(\vec{r}, t) - \frac{\partial \vec{B}(\vec{r}, t)}{\partial t} \quad (\text{Faraday's Law})$$

$$\vec{\nabla} \times \vec{B}(\vec{r}, t) = \mu_0 \vec{J}_{\text{Tot}}^E(\vec{r}, t) + \underbrace{\mu_0 \epsilon_0}_{\frac{1}{c^2}} \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} \quad (\text{Ampere's Law})$$

$$\vec{F}_{\text{Tot}}^E(\vec{r}, t) = q \left( \vec{E}(\vec{r}, t) + \vec{v}(\vec{r}, t) \times \vec{B}(\vec{r}, t) \right)$$

$$\vec{F}_{\text{Tot}}^m(\vec{r}, t) = g_m \left( \vec{B}(\vec{r}, t) - \frac{1}{c^2} \vec{v}(\vec{r}, t) \times \vec{E}(\vec{r}, t) \right)$$

Please see/read Phy435 lecture notes #18 for more details about magnetic monopoles....

## Maxwell's Equations in Matter

In dielectric and magnetic media we have:

Electric polarization  $\vec{P}$  = electric dipole moment per unit volume.

Magnetization  $\vec{M}$  = magnetic dipole moment per unit volume.

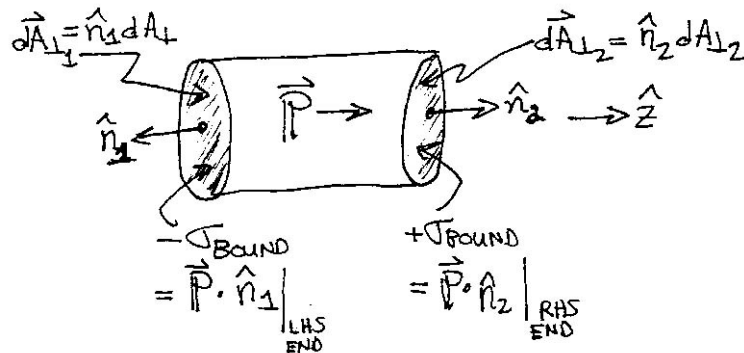
For static fields:

$$\rho_{bound}(\vec{r}) = -\vec{\nabla} \cdot \vec{P}(\vec{r})$$

$$\vec{J}_{bound}(\vec{r}) = \vec{\nabla} \times \vec{M}(\vec{r})$$

For non-static fields, a change in electric polarization  $\Delta\vec{P}$  has associated with it a flow (i.e. a current) of bound charge – a bound polarization current density  $\vec{J}_p(\vec{r})$  which must be included in the total current,  $I_{TOT}$ .

Consider a tiny chunk/block of polarized dielectric material



The electric polarization  $\vec{P}$  induces bound surface charge densities

$$-\sigma_{bound} = \vec{P} \cdot \hat{n}_1 \Big|_{LHS\ END} \quad \text{and} \quad +\sigma_{bound} = \vec{P} \cdot \hat{n}_2 \Big|_{RHS\ END}$$

If the electric polarization  $\vec{P}$  increases an infinitesimal amount  $\Delta\vec{P}$  in time  $\Delta t$ , then the bound surface charges on each end also increase accordingly, giving a net Polarization bound current:

$$\Delta I_{P_{bound}} = \frac{\Delta\sigma_{bound}}{\Delta t} dA_{\perp} = \frac{\Delta\vec{P}}{\Delta t} \cdot d\vec{A}_{\perp}$$

OR:

$$dI_{P_{bound}} = \frac{\partial\sigma_{bound}}{\partial t} dA_{\perp} = \frac{\partial\vec{P}}{\partial t} \cdot d\vec{A}_{\perp} = \vec{J}_{P_{bound}} \cdot d\vec{A}_{\perp}$$

$$\boxed{\vec{J}_{P_{bound}}(\vec{r}, t) = \vec{J}_p(\vec{r}, t) \equiv \frac{\partial\vec{P}(\vec{r}, t)}{\partial t}} = \text{electric polarization current density (SI units: Amps/m}^2\text{)}$$

Must not be confused with:  $\vec{J}_{m_{bound}}(\vec{r}, t) \equiv \vec{\nabla} \times \vec{M}(\vec{r}, t) =$  bound magnetic current density!!!

Because charge is charge is charge, there (of course) exists a continuity equation (expressing electric charge conservation) for bound electric polarization current density  $\vec{J}_{P_{bound}}(\vec{r}, t)$ :

$$\boxed{\vec{\nabla} \cdot \vec{J}_p = \vec{\nabla} \cdot \frac{\partial\vec{P}}{\partial t} = \frac{\partial}{\partial t}(\vec{\nabla} \cdot \vec{P}) = -\frac{\partial\rho_{bound}^E}{\partial t}} \quad \vec{J}_p \text{ is essential to conservation of overall electric charge...}$$

Total electric charge density:  $\rho_{Tot}^E(\vec{r}, t) = \rho_{free}^E(\vec{r}, t) + \rho_{bound}^E(\vec{r}, t) = \rho_{free}^E(\vec{r}, t) - \vec{\nabla} \cdot \vec{P}(\vec{r}, t)$

Total electric current density:  $\vec{J}_{Tot}^E(\vec{r}, t) = \vec{J}_{free}^E(\vec{r}, t) + \vec{J}_{bound}^m(\vec{r}, t) + \vec{J}_{bound}^E(\vec{r}, t)$   
 $= \vec{J}_{free}^E(\vec{r}, t) + \vec{\nabla} \times \vec{M}(\vec{r}, t) + \frac{\partial \vec{P}}{\partial t}(\vec{r}, t)$

Then Gauss' Law becomes:  $\vec{\nabla} \cdot \vec{E}(\vec{r}, t) = \frac{1}{\epsilon_0} \rho_{Tot}(\vec{r}, t) = \frac{1}{\epsilon_0} (\rho_{free}(\vec{r}, t) + \rho_{bound}(\vec{r}, t))$   
 $= \frac{1}{\epsilon_0} \rho_{free}^E(\vec{r}, t) - \frac{1}{\epsilon_0} \vec{\nabla} \cdot \vec{P}(\vec{r}, t)$

$$\vec{\nabla} \cdot \vec{D}(\vec{r}, t) \equiv \epsilon_0 \vec{\nabla} \cdot \vec{E}(\vec{r}, t) + \vec{\nabla} \cdot \vec{P}(\vec{r}, t) = \vec{\nabla} \cdot (\epsilon_0 \vec{E}(\vec{r}, t) + \vec{P}(\vec{r}, t))$$

$$\vec{\nabla} \cdot \vec{D}(\vec{r}, t) = \rho_{free}(\vec{r}, t) \quad \text{and} \quad \vec{D}(\vec{r}, t) \equiv \epsilon_0 \vec{E}(\vec{r}, t) + \vec{P}(\vec{r}, t)$$

(New) Ampere's Law (with Maxwell's displacement current term)

$$\vec{\nabla} \times \vec{B}(\vec{r}, t) = \mu_0 \vec{J}_{Tot}(\vec{r}, t) + \mu_0 \vec{J}_D(\vec{r}, t)$$

$$= \mu_0 (\vec{J}_{free}^E(\vec{r}, t) + \vec{J}_{bound}^m(\vec{r}, t) + \vec{J}_{bound}^E(\vec{r}, t)) + \mu_0 \left( \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} \right)$$

$$= \mu_0 \left( \vec{J}_{free}^E(\vec{r}, t) + \vec{\nabla} \times \vec{M}(\vec{r}, t) + \frac{\partial \vec{P}(\vec{r}, t)}{\partial t} \right) + \mu_0 \left( \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} \right)$$

$$= \mu_0 (\vec{J}_{free}^E(\vec{r}, t) + \vec{\nabla} \times \vec{M}(\vec{r}, t)) + \mu_0 \left( \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} + \frac{\partial \vec{P}(\vec{r}, t)}{\partial t} \right)$$

$$= \mu_0 (\vec{J}_{free}^E(\vec{r}, t) + \vec{\nabla} \times \vec{M}(\vec{r}, t)) + \mu_0 \left( \frac{\partial}{\partial t} \underbrace{[\epsilon_0 \vec{E}(\vec{r}, t) + \vec{P}(\vec{r}, t)]}_{\equiv \vec{D}(\vec{r}, t)} \right)$$

$$\vec{\nabla} \times \vec{B}(\vec{r}, t) = \mu_0 (\vec{J}_{free}^E(\vec{r}, t) - \vec{\nabla} \times \vec{M}(\vec{r}, t)) + \mu_0 \frac{\partial \vec{D}(\vec{r}, t)}{\partial t}$$

Then:  $\vec{\nabla} \times \vec{H}(\vec{r}, t) \equiv \left[ \frac{1}{\mu_0} \vec{\nabla} \times \vec{B}(\vec{r}, t) - \vec{\nabla} \times \vec{M}(\vec{r}, t) \right] = \mu_0 \vec{J}_{free}^E(\vec{r}, t) + \frac{\partial \vec{D}(\vec{r}, t)}{\partial t}$

$$\vec{\nabla} \times \vec{H}(\vec{r}, t) = \mu_0 \vec{J}_{free}^E(\vec{r}, t) + \frac{\partial \vec{D}(\vec{r}, t)}{\partial t} \quad \text{and} \quad \vec{H}(\vec{r}, t) \equiv \frac{1}{\mu_0} \vec{B}(\vec{r}, t) - \vec{M}(\vec{r}, t)$$

Faraday's Law:  $\vec{\nabla} \times \vec{E}(\vec{r}, t) = -\frac{\partial \vec{B}(\vec{r}, t)}{\partial t}$  and  $\vec{\nabla} \cdot \vec{B}(\vec{r}, t) = 0$  (no magnetic monopoles)

are unaffected by separation of electric charge and electric current into free and bound parts.

The four Maxwell's Equations for free charges and free currents only:

|                              |   |  |                       |
|------------------------------|---|--|-----------------------|
| free charges & currents only | } | $\vec{\nabla} \cdot \vec{D}(\vec{r}, t) = \rho_{free}(\vec{r}, t)$   | (Gauss' Law)          |
|                              |   | $\vec{\nabla} \cdot \vec{B}(\vec{r}, t) = 0$   | (no magnetic charges) |
|                              |   | $\vec{\nabla} \times \vec{E}(\vec{r}, t) = -\frac{\partial \vec{B}(\vec{r}, t)}{\partial t}$                             | (Faraday's Law)       |
|                              |   | $\vec{\nabla} \times \vec{H}(\vec{r}, t) = \vec{J}_{free}(\vec{r}, t) + \frac{\partial \vec{D}(\vec{r}, t)}{\partial t}$ | (Ampere's Law)        |

The four Maxwell equations for matter (i.e. dielectric and magnetic materials) are:

Gauss' Law:  $\vec{\nabla} \cdot \vec{E}(\vec{r}, t) = \frac{1}{\epsilon_0} \rho_{Tot}^E(\vec{r}, t) = \frac{1}{\epsilon_0} \rho_{free}^E(\vec{r}, t) + \rho_{bound}^E(\vec{r}, t)$        $\rho_{bound}^E(\vec{r}, t) \equiv -\vec{\nabla} \cdot \vec{P}(\vec{r}, t)$

Auxilliary Relation:  $\vec{D}(\vec{r}, t) \equiv \epsilon_0 \vec{E}(\vec{r}, t) + \vec{P}(\vec{r}, t)$   
 $\vec{\nabla} \cdot \vec{D}(\vec{r}, t) = \epsilon_0 \vec{\nabla} \cdot \vec{E}(\vec{r}, t) + \vec{\nabla} \cdot \vec{P}(\vec{r}, t) = \rho_{free}^E(\vec{r}, t)$

No magnetic monopoles:  $\vec{\nabla} \cdot \vec{B}(\vec{r}, t) = 0$

Faraday's Law:  $\vec{\nabla} \times \vec{E}(\vec{r}, t) = -\frac{\partial \vec{B}(\vec{r}, t)}{\partial t}$

Ampere's Law:  $\vec{\nabla} \times \vec{B}(\vec{r}, t) = \mu_0 (\vec{J}_{Tot}(\vec{r}, t) + \vec{J}_D(\vec{r}, t))$   
 $= \mu_0 (\vec{J}_{free}^E(\vec{r}, t) + \vec{J}_{bound}^m(\vec{r}, t) + \vec{J}_{P_{bound}}(\vec{r}, t) + \vec{J}_D(\vec{r}, t))$   
 $= \mu_0 \left( \vec{J}_{free}^E(\vec{r}, t) + \vec{\nabla} \times \vec{M}(\vec{r}, t) + \frac{\partial \vec{P}(\vec{r}, t)}{\partial t} + \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} \right)$

With  $\vec{J}_D(\vec{r}, t) \equiv \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$  and  $\vec{J}_{bound}^m(\vec{r}, t) \equiv \vec{\nabla} \times \vec{M}(\vec{r}, t)$  and  $\vec{J}_{P_{bound}}(\vec{r}, t) \equiv \frac{\partial \vec{P}(\vec{r}, t)}{\partial t}$

Auxilliary Relation:  $\vec{H}(\vec{r}, t) \equiv \frac{1}{\mu_0} \vec{B}(\vec{r}, t) - \vec{M}(\vec{r}, t)$   
 $\vec{\nabla} \times \vec{H}(\vec{r}, t) = \mu_0 \left( \vec{J}_{free}(\vec{r}, t) + \frac{\partial \vec{D}(\vec{r}, t)}{\partial t} \right)$

For linear dielectric and/or magnetic media:

|   |  |
|---|--|
| $\vec{P}(\vec{r}, t) = \epsilon_0 \chi_e \vec{E}(\vec{r}, t)$ | $\vec{M}(\vec{r}, t) = \chi_m \vec{H}(\vec{r}, t)$ |
| $\epsilon = \epsilon_0 (1 + \chi_e)$                          | $\mu = \mu_0 (1 + \chi_m)$                         |
| $K_e \equiv \epsilon / \epsilon_0 = (1 + \chi_e)$             | $K_m \equiv \mu / \mu_0 = (1 + \chi_m)$            |
| $\vec{D}(\vec{r}, t) = \epsilon \vec{E}(\vec{r}, t)$          | $\vec{H}(\vec{r}, t) = \vec{B}(\vec{r}, t) / \mu$  |



## Maxwell's Equations and Boundary Conditions at Interfaces in Matter

As we have seen previously, in order to obtain relations between normal (i.e. perpendicular) and tangential (i.e. parallel) components of  $\{\vec{E}, \vec{D}, \vec{P}\}$  and/or  $\{\vec{B}, \vec{H}, \vec{M}\}$  at an interface/boundary between dielectric and/or magnetic media, we must use the integral form(s) of Maxwell's equations, because spatial derivatives of  $\{\vec{E}, \vec{D}, \vec{P}\}$  and/or  $\{\vec{B}, \vec{H}, \vec{M}\}$  are not defined at an interface/boundary, for Maxwell's equations in differential form:

Gauss' Law:

$$\int_V \vec{\nabla} \cdot \vec{E}(\vec{r}, t) d\tau' = \frac{1}{\epsilon_0} \int_V \rho_{Tot}^E(\vec{r}, t) d\tau' = \frac{1}{\epsilon_0} \int_V (\rho_{free}^E(\vec{r}, t) + \rho_{bound}^E(\vec{r}, t)) d\tau'$$

$$= \oint_S \vec{E}(\vec{r}, t) \cdot d\vec{a} = \frac{1}{\epsilon_0} Q_{ToT}^{enclosed}(t) = \frac{1}{\epsilon_0} (Q_{free}^{enclosed}(t) + Q_{bound}^{enclosed}(t))$$

$$\oint_S \vec{D}(\vec{r}, t) \cdot d\vec{a} = Q_{free}^{enclosed}(t) \quad \oint_S \vec{P}(\vec{r}, t) \cdot d\vec{a} \equiv -Q_{bound}^{enclosed}(t)$$

Auxiliary Relation:

$$\vec{D}(\vec{r}, t) = \epsilon_0 \vec{E}(\vec{r}, t) + \vec{P}(\vec{r}, t)$$

$$\rho_{Bound}(\vec{r}, t) \equiv -\vec{\nabla} \cdot \vec{P}(\vec{r}, t)$$

$$\sigma_{Bound}(\vec{r}, t) \equiv \vec{P}(\vec{r}, t) \cdot \hat{n}|_{inf}$$

No Magnetic Monopoles:

$$\int_V \vec{\nabla} \cdot \vec{B}(\vec{r}, t) d\tau' = \oint_S \vec{B}(\vec{r}, t) \cdot d\vec{a} = 0$$

Faraday's Law:

$$\int_S \vec{\nabla} \times \vec{E}(\vec{r}, t) \cdot d\vec{a} = \oint_C \vec{E}(\vec{r}, t) \cdot d\vec{\ell} = - \int_S \frac{\partial \vec{B}(\vec{r}, t)}{\partial t} \cdot d\vec{a} = - \frac{d}{dt} \left[ \int_S \vec{B}(\vec{r}, t) \cdot d\vec{a} \right]$$

$$emf \ \epsilon(t) \equiv \oint_C \vec{E}(\vec{r}, t) \cdot d\vec{\ell} = - \frac{d}{dt} \left[ \int_S \vec{B}(\vec{r}, t) \cdot d\vec{a} \right] = - \frac{d\Phi_M^{enclosed}(t)}{dt}$$

Ampere's Law:

$$\int_S \vec{\nabla} \times \vec{B}(\vec{r}, t) \cdot d\vec{a} = \oint_C \vec{B}(\vec{r}, t) \cdot d\vec{\ell} = \mu_0 \int_S (\vec{J}_{ToT}(\vec{r}, t) + \vec{J}_D(\vec{r}, t)) \cdot d\vec{a}$$

$$= \oint_C \vec{B}(\vec{r}, t) \cdot d\vec{\ell} = \mu_0 (I_{ToT}^{encl}(t) + I_D^{encl}(t)) = \mu_0 \left( I_{free}^{encl}(t) + I_{bound}^{encl}(t) + I_{P_{bound}}^{encl}(t) + I_D^{encl}(t) \right)$$

Auxiliary Relation:

$$\vec{H}(\vec{r}, t) = \frac{1}{\mu_0} \vec{B}(\vec{r}, t) - \vec{M}(\vec{r}, t)$$

$$\vec{J}_{bound}^m(\vec{r}, t) \equiv \vec{\nabla} \times \vec{M}(\vec{r}, t)$$

$$\vec{K}_{bound}^m(\vec{r}, t) \equiv \vec{M}(\vec{r}, t) \times \hat{n}|_{inf}$$

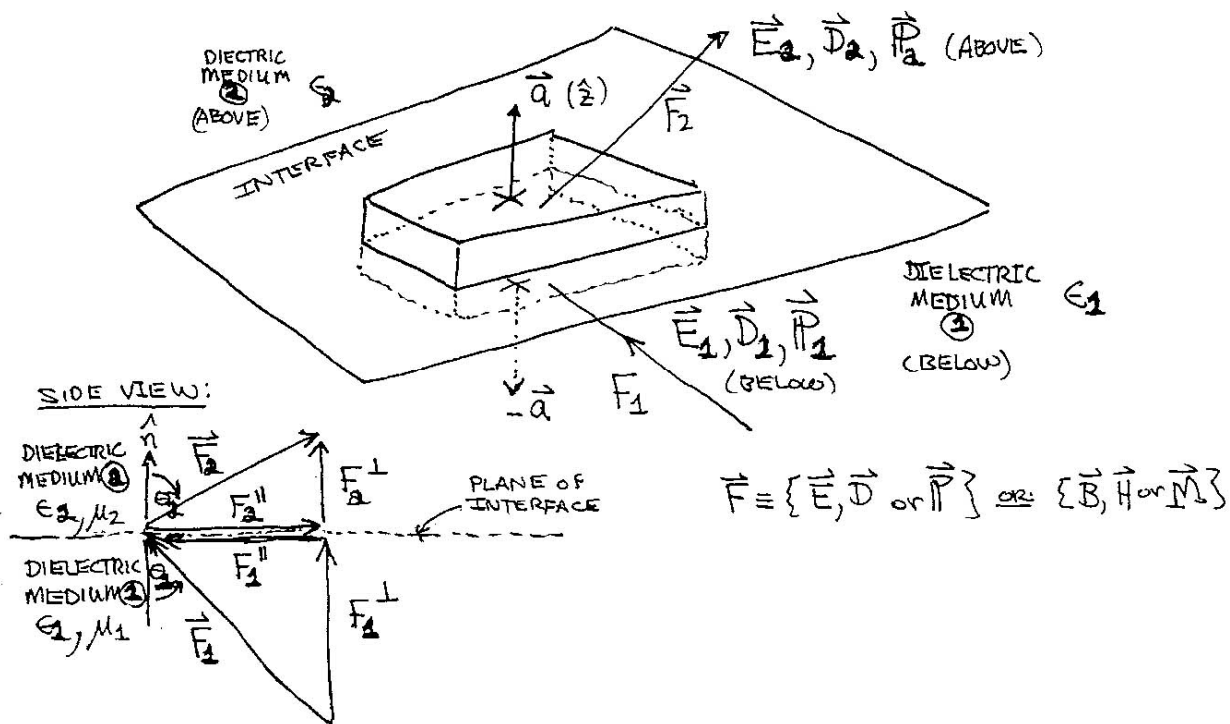
$$\vec{J}_{P_{bound}}(\vec{r}, t) \equiv \frac{\partial \vec{P}(\vec{r}, t)}{\partial t}$$

$$\rho_m^{Bound}(\vec{r}, t) \equiv -\vec{\nabla} \cdot \vec{M}(\vec{r}, t)$$

$$\sigma_m^{Bound}(\vec{r}, t) \equiv \vec{M}(\vec{r}, t) \cdot \hat{n}|_{inf}$$

$$\int_S \vec{\nabla} \times \vec{H}(\vec{r}, t) \cdot d\vec{a} = \oint_C \vec{H}(\vec{r}, t) \cdot d\vec{\ell} = I_{free}^{enclosed}(t) + \int_S \frac{\partial \vec{D}(\vec{r}, t)}{\partial t} \cdot d\vec{a} = I_{free}^{enclosed}(t) + \frac{d}{dt} \left[ \int_S \vec{D}(\vec{r}, t) \cdot d\vec{a} \right]$$

1) Apply the integral form of Gauss' Law at a dielectric interface/boundary using infinitesimally thin Gaussian pillbox extending slightly into dielectric material on either side of interface:



$$\oint_S \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} Q_{\text{ToT}}^{\text{enclosed}} = \frac{1}{\epsilon_0} Q_{\text{free}}^{\text{enclosed}} + \frac{1}{\epsilon_0} Q_{\text{bound}}^{\text{enclosed}} = \frac{1}{\epsilon_0} \oint_S \sigma_{\text{free}} da + \frac{1}{\epsilon_0} \oint_S \sigma_{\text{bound}} da$$

Gives:  $\vec{E}_2 \cdot \vec{a} - \vec{E}_1 \cdot \vec{a} = \frac{1}{\epsilon_0} \sigma_{\text{free}} a + \frac{1}{\epsilon_0} \sigma_{\text{bound}} a = \frac{1}{\epsilon_0} \sigma_{\text{ToT}} a$  (at interface)

or: 
$$E_2^{\perp} - E_1^{\perp} = \frac{1}{\epsilon_0} \sigma_{\text{ToT}} = \frac{1}{\epsilon_0} (\sigma_{\text{free}} + \sigma_{\text{bound}})$$
 (at interface)

Here, the positive direction is from medium 2 (below) to medium 1 (above)

$$\oint_S \vec{D} \cdot d\vec{a} = Q_{\text{free}}^{\text{enclosed}} = \oint_S \sigma_{\text{free}} da \Rightarrow D_2^{\perp} - D_1^{\perp} = \sigma_{\text{free}}$$
 (at interface)

Likewise:

$$\oint_S \vec{P} \cdot d\vec{a} = Q_{\text{bound}}^{\text{enclosed}} = -\oint_S \sigma_{\text{bound}} da \Rightarrow P_2^{\perp} - P_1^{\perp} = \sigma_{\text{bound}}$$
 (at interface)

Since:  $\vec{E} \equiv -\vec{\nabla}V$

$$\left( \frac{\partial V_2^{\text{above}}}{\partial n} - \frac{\partial V_1^{\text{below}}}{\partial n} \right)_{\text{interface}} = -\frac{1}{\epsilon_0} \sigma_{\text{ToT}} = -\frac{1}{\epsilon_0} (\sigma_{\text{free}} + \sigma_{\text{bound}})$$
 (at interface)

Since:  $\vec{D} = \epsilon \vec{E} = -\epsilon \vec{\nabla} V$

$$\left( \epsilon_2 \frac{\partial V_2^{above}}{\partial n} - \epsilon_1 \frac{\partial V_1^{below}}{\partial n} \right) \Big|_{\text{interface}} = -\sigma_{free} \quad (\text{at interface})$$

2) Similarly, for  $\int_V \vec{\nabla} \cdot \vec{B} d\tau' = \oint_S \vec{B} \cdot d\vec{a} = 0$  (no magnetic monopoles), then at an interface:

$$\vec{B}_2^{above} \cdot \vec{a} - \vec{B}_1^{above} \cdot \vec{a} = 0 \Rightarrow \boxed{B_2^{\perp} - B_1^{\perp} = 0} \quad \text{or:} \quad \boxed{B_2^{\perp} = B_1^{\perp}} \quad (\text{at interface})$$

Since:  $\vec{H} = \left( \frac{1}{\mu_0} \right) \vec{B} - \vec{M}$  Then:  $\vec{B} = \mu_0 (\vec{H} + \vec{M})$

$$\oint_S \vec{B} \cdot d\vec{a} = \mu_0 \oint_S (\vec{H} + \vec{M}) \cdot d\vec{a} = 0 \quad \text{or:} \quad \oint_S \vec{H} \cdot d\vec{a} = -\oint_S \vec{M} \cdot d\vec{a}$$

Then:  $\vec{H}_2^{above} \cdot \vec{a} - \vec{H}_1^{below} \cdot \vec{a} = -(\vec{M}_2^{above} \cdot \vec{a} - \vec{M}_1^{below} \cdot \vec{a})$  (at interface)

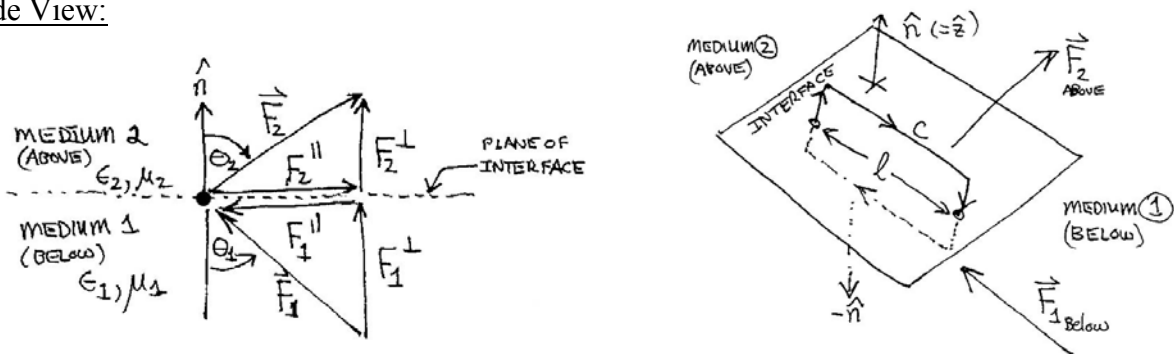
$$\text{Or:} \quad \left( \begin{array}{cc} H_2^{\perp} & -H_1^{\perp} \\ \text{above} & \text{below} \end{array} \right) = - \left( \begin{array}{cc} M_2^{\perp} & -M_1^{\perp} \\ \text{above} & \text{below} \end{array} \right) = -\sigma_{magnetic}^{bound} \quad (\text{at interface})$$

*Effective* bound magnetic charge at interface

3) For Faraday's Law: EMF,  $\epsilon = \oint_C \vec{E} \cdot d\vec{\ell} = -\frac{d}{dt} \left( \oint_S \vec{B} \cdot d\vec{a} \right) = -\frac{d\Phi_m}{dt}$  at an interface / boundary between two different media, taking a closed contour  $C$  of width  $l$  extending slightly (i.e. infinitesimally) into the material on either side of interface, as shown below:

$$\vec{F} \equiv \{ \vec{E}, \vec{D} \text{ or } \vec{P} \} \quad \text{or:} \quad \{ \vec{B}, \vec{H} \text{ or } \vec{M} \}$$

Side View:




$$\vec{E}_2^{above} \cdot \vec{\ell} - \vec{E}_1^{below} \cdot \vec{\ell} = -\frac{d}{dt} \oint_S \vec{B} \cdot d\vec{a} = 0 \quad (\text{in limit area of contour loop} \rightarrow 0, \text{ magnetic flux enclosed} \rightarrow 0)$$

$$\text{Thus:} \quad \boxed{E_2^{\parallel} - E_1^{\parallel} = 0} \quad (\text{at interface}) \quad \text{or:} \quad \boxed{E_2^{\parallel} = E_1^{\parallel}} \quad (\text{at interface})$$

Since:  $\vec{D} = \epsilon_o \vec{E} + \vec{P}$  And:  $\epsilon_o \vec{E} = \vec{D} - \vec{P}$

Thus:  $(\vec{E}_2^{above} \cdot \vec{\ell} - \vec{E}_1^{below} \cdot \vec{\ell}) = (\vec{D}_2^{above} \cdot \vec{\ell} - \vec{D}_1^{below} \cdot \vec{\ell}) - (\vec{P}_2^{above} \cdot \vec{\ell} - \vec{P}_1^{below} \cdot \vec{\ell}) = 0$

In limit area of contour loop  $\rightarrow 0$  magnetic flux enclosed  $\rightarrow 0$  

$$\Rightarrow \left( \begin{array}{cc} \vec{D}_2^{above} & - \vec{D}_1^{below} \\ \vec{P}_2^{above} & - \vec{P}_1^{below} \end{array} \right) = \left( \begin{array}{cc} \vec{P}_2^{above} & - \vec{P}_1^{below} \end{array} \right) \quad (\text{at interface})$$

4) Finally, for Ampere's Law:  $\oint_C \vec{B} \cdot d\vec{\ell} = \mu_o (I_{TOT}^{encl} + I_D^{encl})$   $I_D^{encl} = \int_S \vec{J}_D \cdot d\vec{a} = \epsilon_o \int_S \frac{\partial \vec{E}}{\partial t} \cdot d\vec{a}$

$$\vec{B}_2^{above} \cdot \vec{\ell} - \vec{B}_1^{below} \cdot \vec{\ell} = \mu_o I_{TOT}^{encl} + \mu_o I_D^{encl} \quad I_{TOT}^{encl} = I_{free}^{encl} + I_{bound}^{encl} + I_{P_{bound}}^{encl}$$

- Where  $I_{TOT}^{encl} = TOTAL$  current (free + bound + polarization)  $I_{P_{bound}}^{encl} = \int_S \vec{J}_{P_{bound}} \cdot d\vec{a} = \int_S \frac{\partial \vec{P}}{\partial t} \cdot d\vec{a}$   
 passing through enclosing Amperian loop contour C  $I_{bound}^{encl} = \int_S \vec{J}_m^{bound} \cdot d\vec{a} = \int_S \vec{\nabla} \times \vec{M} \cdot d\vec{a}$

- No volume current density  $\vec{J}_{TOT}$ ,  $\vec{J}_{free}$ ,  $\vec{J}_{bound}^m$  or  $\vec{J}_P$  contributes to  $I_{TOT}^{encl}$  in the limit area of contour loop  $\rightarrow 0$ , however a surface current  $\vec{K}_{TOT}$ ,  $\vec{K}_{free}$ ,  $\vec{K}_{bound}^m = \vec{M} \times \hat{n}$  can contribute!

- In the limit that the enclosing Amperian loop contour C shrinks to zero height above/below interface, the enclosed area of loop contour  $\rightarrow 0$ , and

Then:  $I_D^{encl} = \epsilon_o \int_S \frac{\partial \vec{E}}{\partial t} \cdot d\vec{a} = \epsilon_o \frac{d}{dt} \left[ \int_S \vec{E} \cdot d\vec{a} \right] = \epsilon \frac{d\Phi_E}{dt} \rightarrow 0$   
 $(\Phi_E \equiv \int_S \vec{E} \cdot d\vec{a} = \text{enclosed flux of electric field lines})$

Similarly:  $I_{P_{bound}}^{encl} = \int_S \frac{\partial \vec{P}}{\partial t} \cdot d\vec{a} = \frac{d}{dt} \left[ \int_S \vec{P} \cdot d\vec{a} \right] = \frac{d\Phi_P}{dt} \rightarrow 0$   
 $(\Phi_P \equiv \int_S \vec{P} \cdot d\vec{a} = \text{enclosed flux of electric polarization field lines})$

- If  $\hat{n}$  is unit normal/perpendicular to interface (pointing from medium 1 (below) into medium 2 (above)), note that  $(\hat{n} \times \vec{\ell})$  is normal/perpendicular to plane of the Amperian loop contour.

Thus:

$$\left. \begin{array}{l} I_{TOT}^{encl} = \vec{K}_{TOT} \cdot (\hat{n} \times \vec{\ell}) = (\vec{K}_{TOT} \times \hat{n}) \cdot \vec{\ell} \\ I_{free}^{encl} = \vec{K}_{free} \cdot (\hat{n} \times \vec{\ell}) = (\vec{K}_{free} \times \hat{n}) \cdot \vec{\ell} \\ I_{bound}^{encl} = \vec{K}_{bound} \cdot (\hat{n} \times \vec{\ell}) = (\vec{K}_{bound}^m \times \hat{n}) \cdot \vec{\ell} \end{array} \right\} \text{Using: } \begin{array}{l} \vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{C} \times \vec{A}) \\ = \vec{C} \cdot (\vec{A} \times \vec{B}) \\ = (\vec{A} \times \vec{B}) \cdot \vec{C} \end{array}$$

$$I_{TOT} = I_{free} + I_{bound} \quad \vec{K}_{TOT} = \vec{K}_{free} + \vec{K}_{bound}$$

In the limit that the enclosing Amperian loop contour  $C$  (of width  $l$ ) shrinks to zero height above/below interface, causing area of enclosed loop contour  $\rightarrow 0$ , then:

$$\vec{B}_2^{above} \cdot \vec{\ell} - \vec{B}_1^{below} \cdot \vec{\ell} = \mu_o I_{TOT}^{encl} + \overbrace{\mu_o I_D^{encl}}^{=0} = \mu_o I_{TOT}^{encl} = (\vec{K}_{TOT} \times \hat{n}) \cdot \vec{\ell}$$

$$\Rightarrow \boxed{B_2^{above} - B_1^{below} = \mu_o \vec{K}_{TOT} \times \hat{n} = \mu_o (\vec{K}_{free} + \vec{K}_{bound}^m) \times \hat{n}} \quad \text{(at interface)}$$

Since:  $\vec{H} = \frac{1}{\mu_o} \vec{B} - \vec{M}$  and:  $\frac{1}{\mu_o} \vec{B} = \vec{H} + \vec{M}$  then:

$$\boxed{\frac{1}{\mu_o} (\vec{B}_2^{above} \cdot \vec{\ell} - \vec{B}_1^{below} \cdot \vec{\ell}) = (\vec{H}_2^{above} \cdot \vec{\ell} - \vec{H}_1^{below} \cdot \vec{\ell}) + (\vec{M}_2^{above} \cdot \vec{\ell} - \vec{M}_1^{below} \cdot \vec{\ell}) = [(\vec{K}_{free} \times \hat{n}) + (\vec{K}_{bound} \times \hat{n})]} \quad \text{(at interface)}$$

We also see that:  $\boxed{H_2^{above} - H_1^{below} = \vec{K}_{free} \times \hat{n}} \quad \text{(at interface)}$

and:  $\boxed{M_2^{above} - M_1^{below} = \vec{K}_{bound}^m \times \hat{n}} \quad \text{(at interface)}$

- || - components of  $\vec{B}$  are discontinuous at interface by  $\mu_o \vec{K}_{TOT} \times \hat{n}$
- || - components of  $\vec{H}$  are discontinuous at interface by  $\vec{K}_{free} \times \hat{n}$
- || - components of  $\vec{M}$  are discontinuous at interface by  $\vec{K}_{bound}^m \times \hat{n}$

If  $\vec{B} = \vec{\nabla} \times \vec{A}$  where  $\vec{A}$  is the magnetic vector potential, then:

$$\left( \frac{1}{\mu_o} \right) \left[ B_2^{above} - B_1^{below} \right] = \vec{K}_{TOT} \times \hat{n} \quad \text{(at interface) is equivalent to:}$$

$$\left( \frac{1}{\mu_o} \right) \left( \frac{\partial \vec{A}_2^{above}}{\partial n} - \frac{\partial \vec{A}_1^{below}}{\partial n} \right) \Big|_{\text{interface}} = -\vec{K}_{TOT} \quad \text{(at interface)}$$

For linear magnetic media:  $\vec{B} = \mu \vec{H}$  or:  $\vec{H} = \frac{1}{\mu} \vec{B}$

Then:  $\boxed{H_2^{above} - H_1^{below} = \vec{K}_{free} \times \hat{n}} \quad \text{(at interface) is equivalent to:}$

$$\left( \frac{1}{\mu_2^{above}} \right) \frac{\partial \vec{A}_2^{above}}{\partial n} \Big|_{\text{interface}} - \left( \frac{1}{\mu_1^{below}} \right) \frac{\partial \vec{A}_1^{below}}{\partial n} \Big|_{\text{interface}} = -\vec{K}_{free} \quad \text{(at interface)}$$

**Summary of Maxwell's Equations In Differential and Integral Forms**  
**(Suppress Explicit  $(\vec{r}, t)$  Dependence)**

Gauss' Law: 
$$\vec{\nabla} \cdot \vec{E} = \frac{1}{\epsilon_o} \rho_{TOT} = \frac{1}{\epsilon_o} (\rho_{free} + \rho_{bound}) \quad \rho_{bound} \equiv -\vec{\nabla} \cdot \vec{P}$$

Use of the auxiliary relation: 
$$\vec{D} = \epsilon_o \vec{E} + \vec{P}$$

Yields: 
$$\vec{\nabla} \cdot \vec{D} = \epsilon_o \vec{\nabla} \cdot \vec{E} + \vec{\nabla} \cdot \vec{P} = \rho_{free}$$

No magnetic monopoles: 
$$\vec{\nabla} \cdot \vec{B} = 0$$

Faraday's Law: 
$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Ampere's Law: 
$$\vec{\nabla} \times \vec{B} = \mu_o (\vec{J}_{TOT} + \vec{J}_D) \quad \vec{J}_{TOT} = \vec{J}_{free} + \vec{J}_{bound}^m + \vec{J}_{Pbound}$$

Use of auxiliary relation: 
$$\vec{H} = \frac{1}{\mu_o} \vec{B} - \vec{M} \quad \text{with} \quad \vec{J}_D = \epsilon_o \frac{\partial \vec{E}}{\partial t}$$

Yields: 
$$\vec{\nabla} \times \vec{H} = \mu_o \vec{J}_{free} + \frac{\partial \vec{D}}{\partial t}$$

Gauss' Law: 
$$\int_v \vec{\nabla} \cdot \vec{E} d\tau' = \oint_S \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_o} Q_{tot}^{encl} = \frac{1}{\epsilon_o} [Q_{free}^{encl} + Q_{bound}^{encl}] \equiv \Phi_E \quad (\text{Electric Flux})$$

Use of the auxiliary relation: 
$$\vec{D} = \epsilon_o \vec{E} + \vec{P}$$

Yields: 
$$\int_v \vec{\nabla} \cdot \vec{D} d\tau' = \oint_S \vec{D} \cdot d\vec{a} = Q_{free}^{encl} \equiv \Phi_D \quad (\text{Electric Displacement Flux})$$

$$\int_v \vec{\nabla} \cdot \vec{P} d\tau' = \oint_S \vec{P} \cdot d\vec{a} = -Q_{bound}^{encl} \equiv \Phi_P \quad (\text{Electric Polarization Flux})$$

No magnetic monopoles: 
$$\int_v \vec{\nabla} \cdot \vec{B} d\tau' = \oint_S \vec{B} \cdot d\vec{a} = 0$$

Faraday's Law: 
$$EMF \quad \mathcal{E} = \int_S \vec{\nabla} \times \vec{E} \cdot d\vec{a} = \oint_C \vec{E} \cdot d\vec{\ell} = -\frac{d}{dt} \int_S \vec{B} \cdot d\vec{a} = -\frac{d\Phi_m^{encl}}{dt}$$

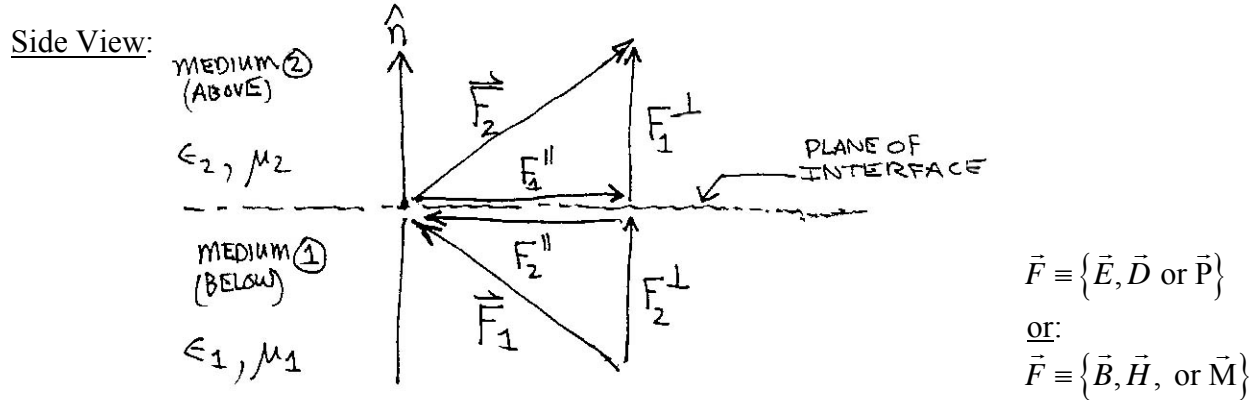
Ampere's Law: 
$$\int_S (\vec{\nabla} \cdot \vec{B}) \cdot d\vec{a} = \oint_C \vec{B} \cdot d\vec{\ell} = \mu_o \int_S (\vec{J}_{TOT} + \vec{J}_D) \cdot d\vec{a} \\ = \mu_o (I_{TOT}^{encl} + I_D^{encl}) = \mu_o (I_{free}^{encl} + I_{bound}^{encl} + I_{Pbound}^{encl} + I_D^{encl})$$

Use of auxiliary relation(s): 
$$\vec{H} = \frac{1}{\mu_o} \vec{B} - \vec{M} \quad \text{and} \quad \vec{D} = \epsilon_o \vec{E} + \vec{P}$$

Yields: 
$$\int_S (\vec{\nabla} \times \vec{H}) \cdot d\vec{a} = \oint_C \vec{H} \cdot d\vec{\ell} = I_{free}^{encl} + \frac{d}{dt} \left[ \int_S \vec{D} \cdot d\vec{a} \right]$$

## Summary of General Boundary Conditions Obtained from Integral Form(s) of Maxwell's Equations

Suppressing explicit  $(\vec{r}, t)$  dependence and defining  $\hat{n}$  (unit normal) pointing from medium 1 (below) into medium 2 (above) as shown in the figure below:



Then at the interface:

Gauss' Law:

$$E_{2 \text{ above}}^{\perp} - E_{1 \text{ below}}^{\perp} = \frac{1}{\epsilon_o} \sigma_{TOT} = \frac{1}{\epsilon_o} (\sigma_{free} + \sigma_{bound}) \quad \boxed{\vec{D} = \epsilon_o \vec{E} + \vec{P}}$$

$$D_{2 \text{ above}}^{\perp} - D_{1 \text{ below}}^{\perp} = \sigma_{free} \quad P_{2 \text{ above}}^{\perp} - P_{1 \text{ below}}^{\perp} = -\sigma_{bound}$$

$$\left( \frac{\partial V_2^{above}}{\partial n} - \frac{\partial V_1^{below}}{\partial n} \right) \Big|_{\text{interface}} = -\frac{1}{\epsilon_o} \sigma_{TOT} = -\frac{1}{\epsilon_o} (\sigma_{free} + \sigma_{bound})$$

$$\left( \epsilon_2 \frac{\partial V_2^{above}}{\partial n} - \epsilon_1 \frac{\partial V_1^{below}}{\partial n} \right) \Big|_{\text{interface}} = -\sigma_{free}$$

No Magnetic Monopoles:

$$B_{2 \text{ above}}^{\perp} - B_{1 \text{ below}}^{\perp} = 0 \Rightarrow \left( H_{2 \text{ above}}^{\perp} - H_{1 \text{ below}}^{\perp} \right) = - \left( M_{2 \text{ above}}^{\perp} - M_{1 \text{ below}}^{\perp} \right) = -\sigma_{magnetic}^{bound}$$

$$\vec{H} = \left( \frac{1}{\mu_o} \right) \vec{B} - \vec{M}$$

Faraday's Law:

$$E_{2 \text{ above}}^{\parallel} - E_{1 \text{ below}}^{\parallel} = 0 \Rightarrow \left( D_{2 \text{ above}}^{\parallel} - D_{1 \text{ below}}^{\parallel} \right) = \left( P_{2 \text{ above}}^{\parallel} - P_{1 \text{ below}}^{\parallel} \right)$$

Ampere's Law:

$$B_{2 \text{ above}}^{\parallel} - B_{1 \text{ below}}^{\parallel} = \mu_o \vec{K}_{TOT} \times \hat{n} = \mu_o (\vec{K}_{free} + \vec{K}_{bound}^m) \times \hat{n} \quad \boxed{\vec{B} = \vec{\nabla} \times \vec{A}}$$

$$\Rightarrow \left( \frac{1}{\mu_o} \right) \left( \frac{\partial \vec{A}_2^{above}}{\partial n} - \frac{\partial \vec{A}_1^{below}}{\partial n} \right) \Big|_{\text{interface}} = -\vec{K}_{TOT}$$

$$H_{2 \text{ above}}^{\parallel} - H_{1 \text{ below}}^{\parallel} = \vec{K}_{free} \times \hat{n} \quad M_{2 \text{ above}}^{\parallel} - M_{1 \text{ below}}^{\parallel} = \vec{K}_{bound}^m \times \hat{n}$$

$$\Rightarrow \left( \frac{1}{\mu_2} \right) \frac{\partial \vec{A}_2}{\partial n} \Big|_{\text{interface above}} - \left( \frac{1}{\mu_1} \right) \frac{\partial \vec{A}_1}{\partial n} \Big|_{\text{interface below}} = -\vec{K}_{free}$$

**BC's Specific to *Linear Homogeneous Isotropic Dielectric and/or Magnetic Media*:**

$$\begin{array}{ccc}
 \boxed{\vec{P} = \epsilon_o \chi_e \vec{E}} & \boxed{\vec{M} = \chi_m \vec{H}} & \boxed{\vec{D} = \epsilon \vec{E} = \epsilon_o \vec{E} + \vec{P}} \\
 \boxed{\epsilon = \epsilon_o (1 + \chi_e)} & \boxed{\mu = \mu_o (1 + \chi_m)} & \boxed{\vec{B} = \mu \vec{H}} \text{ or } \boxed{\vec{H} = \frac{1}{\mu} \vec{B}} \\
 \boxed{K_e = \frac{\epsilon}{\epsilon_o} = 1 + \chi_e} & \boxed{K_m = \frac{\mu}{\mu_o} = (1 + \chi_m)} & \boxed{\vec{H} = \frac{1}{\mu_o} \vec{B} - \vec{M}}
 \end{array}$$

The boundary conditions at the interface between linear dielectric or magnetic media become:

Gauss' Law:

$$\begin{array}{l}
 \left( E_{2\text{ above}}^\perp - E_{1\text{ below}}^\perp \right) = \frac{1}{\epsilon_o} \sigma_{TOT} = \frac{1}{\epsilon_o} (\sigma_{free} + \sigma_{bound}) \\
 \Rightarrow \left( \frac{\partial V_2^{above}}{\partial n} - \frac{\partial V_1^{below}}{\partial n} \right) \Big|_{\text{interface}} = -\frac{1}{\epsilon_o} \sigma_{TOT} = -\frac{1}{\epsilon_o} (\sigma_{free} + \sigma_{bound}) \\
 \left( D_{2\text{ above}}^\perp - D_{1\text{ below}}^\perp \right) = \sigma_{free} \Rightarrow \left( \epsilon_2 E_{2\text{ above}}^\perp - \epsilon_1 E_{1\text{ below}}^\perp \right) = \sigma_{free} \\
 \left( P_{2\text{ above}}^\perp - P_{1\text{ below}}^\perp \right) = -\sigma_{bound} \Rightarrow \epsilon_o \left( \chi_{e_2} E_{2\text{ above}}^\perp - \chi_{e_1} E_{1\text{ below}}^\perp \right) = -\sigma_{bound} \\
 \epsilon_2 \frac{\partial V_2}{\partial n} \Big|_{\text{interface above}} - \epsilon_1 \frac{\partial V_1}{\partial n} \Big|_{\text{interface below}} = -\sigma_{free}
 \end{array}$$

No magnetic monopoles:

$$\begin{array}{l}
 \left( B_{2\text{ above}}^\perp - B_{1\text{ below}}^\perp \right) = 0 \Rightarrow \left( H_{2\text{ above}}^\perp - H_{1\text{ below}}^\perp \right) = - \left( M_{2\text{ above}}^\perp - M_{1\text{ below}}^\perp \right) = -\sigma_{magnetic}^{bound} \\
 = \left( \mu_2 H_{2\text{ above}}^\perp - \mu_1 H_{1\text{ below}}^\perp \right) = 0 \qquad = \left( \frac{1}{\mu_2} B_{2\text{ above}}^\perp - \frac{1}{\mu_1} B_{1\text{ below}}^\perp \right)
 \end{array}$$

Faraday's Law:

$$\begin{array}{l}
 \left( E_{2\text{ above}}^\parallel - E_{1\text{ below}}^\parallel \right) = 0 \Rightarrow \left( D_{2\text{ above}}^\parallel - D_{1\text{ below}}^\parallel \right) = \left( P_{2\text{ above}}^\parallel - P_{1\text{ below}}^\parallel \right) \\
 = \left( \frac{1}{\epsilon_2} D_{2\text{ above}}^\parallel - \frac{1}{\epsilon_1} D_{1\text{ below}}^\parallel \right) = 0 \Rightarrow \left( \epsilon_2 E_{2\text{ above}}^\parallel - \epsilon_1 E_{1\text{ below}}^\parallel \right) = -\epsilon_o \left( \chi_{e_2} E_{2\text{ above}}^\parallel - \chi_{e_1} E_{1\text{ below}}^\parallel \right)
 \end{array}$$

Ampere's Law:

$$\begin{array}{l}
 B_{2\text{ above}}^\parallel - B_{1\text{ below}}^\parallel = \mu_o \vec{K}_{TOT} \times \hat{n} = \mu_o \left( \vec{K}_{free} + \vec{K}_{bound}^m \right) \times \hat{n} \Rightarrow \left( \frac{1}{\mu_o} \right) \left( \frac{\partial A_2^{\rightarrow\text{above}}}{\partial n} - \frac{\partial A_1^{\rightarrow\text{below}}}{\partial n} \right) \Big|_{\text{interface}} = -\vec{K}_{TOT} \\
 = \left( \mu_2 H_{2\text{ above}}^\parallel - \mu_1 H_{1\text{ below}}^\parallel \right) \qquad \text{using } \boxed{\vec{B} = \vec{\nabla} \times \vec{A}}
 \end{array}$$



$$\begin{aligned}
 \boxed{H_2^{\parallel} \text{ above} - H_1^{\parallel} \text{ below}} &= \vec{K}_{free} \times \hat{n} \\
 = \frac{1}{\mu_2 \text{ above}} B_2^{\parallel} \text{ above} - \frac{1}{\mu_1 \text{ below}} B_1^{\parallel} \text{ below} & \quad \text{and} \quad \boxed{\begin{aligned}
 \left( M_2^{\parallel} \text{ above} - M_1^{\parallel} \text{ below} \right) &= \vec{K}_{bound}^m \times \hat{n} \\
 = \left( \chi_{m_2} \text{ above} H_2^{\parallel} \text{ above} - \chi_{m_1} \text{ below} H_1^{\parallel} \text{ below} \right) \\
 = \left( \frac{\chi_{m_2} \text{ above}}{\mu_2 \text{ above}} B_2^{\parallel} \text{ above} - \frac{\chi_{m_1} \text{ below}}{\mu_1 \text{ below}} B_1^{\parallel} \text{ below} \right)
 \end{aligned}}
 \end{aligned}$$

$$\boxed{\left( \frac{1}{\mu_2} \right) \frac{\partial \vec{A}_2}{\partial n} \Big|_{\text{above interface}} - \left( \frac{1}{\mu_1} \right) \frac{\partial \vec{A}_1}{\partial n} \Big|_{\text{below interface}}} = -\vec{K}_{free} \quad \text{using} \quad \boxed{\vec{B} = \vec{\nabla} \times \vec{A}}$$