

LECTURE NOTES 20

Static Magnetic Fields in Matter II

We summarize here the relations that we have obtained thus far for the macroscopic magnetic vector potential $\vec{A}(\vec{r})$ and the magnetic field $\vec{B}(\vec{r}) = \vec{\nabla} \times \vec{A}(\vec{r})$ associated with magnetic materials in terms of steady filamentary/line, surface and volume free and bound current densities, and with the two Maxwell's equations:

(1) No magnetic charges: $\vec{\nabla} \cdot \vec{B}(\vec{r}) = 0$

(2) Ampere's Law: $\vec{\nabla} \times \vec{B}(\vec{r}) = \mu_o \vec{J}_{TOT}(\vec{r}) = \mu_o \vec{J}_{free}(\vec{r}) + \mu_o \vec{J}_{Bound}(\vec{r})$.

Using the Principle of Linear Superposition:

Filamentary/Line Currents:	$I_{TOT} = I_{free} + I_{bound}$	(Amps)
Surface Current Densities:	$\vec{K}_{TOT} = \vec{K}_{free} + \vec{K}_{Bound}$	(Amps/m) $I = \int_{C_{\perp}} \vec{K} \cdot \hat{n}_{\perp} d\ell_{\perp}$
Volume Current Densities:	$\vec{J}_{TOT} = \vec{J}_{free} + \vec{J}_{Bound}$	(Amps/m ²) $I = \int_{S_{\perp}} \vec{J} \cdot d\vec{a} \quad d\vec{a} = \hat{n} da$

Filamentary/Line Currents:	$\vec{A}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{C'} \frac{\vec{I}_{TOT}(\vec{r}') d\ell'}{r}$ $= \left(\frac{\mu_o}{4\pi} \right) I_{TOT} \int_{C'} \frac{d\vec{\ell}'(\vec{r}')}{r}$ (If $I_{TOT} \neq \text{fcn}(\vec{r}')$)	$\vec{B}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{C'} \frac{\vec{I}_{TOT}(\vec{r}') d\ell' \times \hat{r}}{r^2}$ $= \left(\frac{\mu_o}{4\pi} \right) I_{TOT} \int_{C'} \frac{d\vec{\ell}'(\vec{r}') \times \hat{r}}{r^2}$ (If $I_{TOT} \neq \text{fcn}(\vec{r}')$)
Surface Current Densities:	$\vec{A}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{S'} \frac{\vec{K}_{TOT}(\vec{r}')}{r} da'$	$\vec{B}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{S'} \frac{\vec{K}_{TOT}(\vec{r}') \times \hat{r}}{r^2} da'$
Volume Current Densities:	$\vec{A}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{V'} \frac{\vec{J}_{TOT}(\vec{r}')}{r} d\tau'$	$\vec{B}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{V'} \frac{\vec{J}_{TOT}(\vec{r}') \times \hat{r}}{r^2} d\tau'$

SI Units of \vec{B} = Tesla = Newtons/(Ampere-meter) and since $\vec{B} = \vec{\nabla} \times \vec{A}$, then:

SI Units of \vec{A} = Tesla-meters = Newtons/Ampere (= force/unit current).

The Magnetic Field $\vec{B}(\vec{r})$ Inside a Magnetized Material with Macroscopic Magnetization (Magnetic Dipole Moment Per Unit Volume) $\vec{M}(\vec{r})$

In the previous P435 Lecture Notes 19 (page 8), we derived the magnetic vector potential $\vec{A}(\vec{r})$ associated with a magnetized material with macroscopic magnetization (*a.k.a.* magnetic dipole moment per unit volume) $\vec{M}(\vec{r})$:

$$\vec{A}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{v'} \frac{\vec{M}(\vec{r}') \times \hat{r}}{r^2} d\tau'$$

The corresponding magnetic field $\vec{B}(\vec{r})$ associated with this magnetic vector potential $\vec{A}(\vec{r})$ is:

$$\vec{B}(\vec{r}) = \vec{\nabla} \times \vec{A}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{v'} \vec{\nabla} \times \left(\frac{\vec{M}(\vec{r}') \times \hat{r}}{r^2} \right) d\tau' = \left(\frac{\mu_o}{4\pi} \right) \int_{v'} \vec{\nabla} \times \left(\vec{M}(\vec{r}') \times \left(\frac{\hat{r}}{r^2} \right) \right) d\tau'$$

Using Griffiths Product Rule # 8: $\vec{\nabla} \times \vec{A} \times \vec{B} = \vec{A}(\vec{\nabla} \cdot \vec{B}) - \vec{B}(\vec{\nabla} \cdot \vec{A}) + \vec{B} \cdot (\vec{\nabla} \vec{A}) - \vec{A} \cdot (\vec{\nabla} \vec{B})$

where: $\vec{A} \equiv \vec{M}(\vec{r}')$ (Note: $\vec{M}(\vec{r}') \neq \text{fcn}(\vec{r})$, it is = fcn(\vec{r}') only !!!)

and: $\vec{B} \equiv \frac{\hat{r}}{r^2} = \frac{\vec{r}}{r^3}$ ($= \frac{r\hat{r}}{r^3}$) with: $\vec{r} = \vec{r} - \vec{r}'$ and: $r = |\vec{r} - \vec{r}'|$

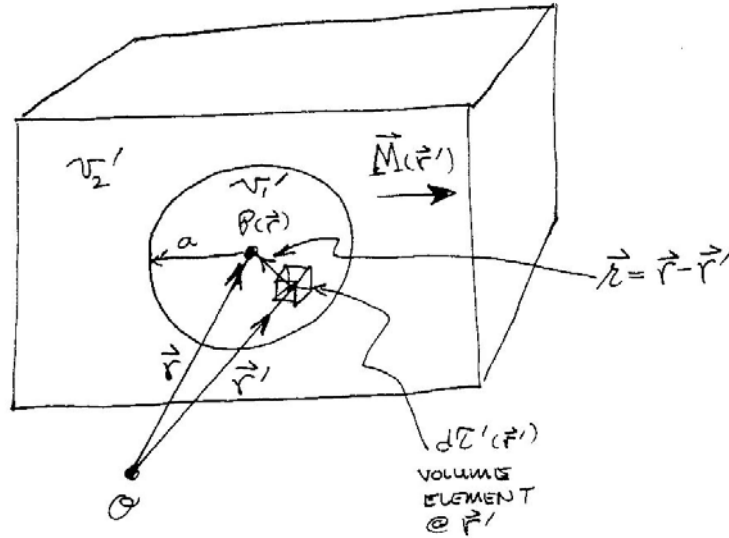
then both: $\left\{ \begin{array}{l} \vec{\nabla} \cdot \vec{A} = 0 \\ \vec{\nabla} \vec{A} = 0 \end{array} \right\}$ because: $\left\{ \begin{array}{l} \vec{\nabla} \cdot \vec{M}(\vec{r}') = 0 \\ \vec{\nabla} \vec{M}(\vec{r}') = 0 \end{array} \right\}$ since: $\left\{ \begin{array}{l} \vec{\nabla} = \text{fcn}(\vec{r}) \text{ only, and} \\ \vec{M}(\vec{r}') = \text{fcn}(\vec{r}') \text{ only} \end{array} \right\}$

So therefore here: $\vec{\nabla} \times \vec{A} \times \vec{B} = \vec{A}(\vec{\nabla} \cdot \vec{B}) - \vec{B}(\vec{\nabla} \cdot \vec{A}) + \vec{B} \cdot (\vec{\nabla} \vec{A}) - \vec{A} \cdot (\vec{\nabla} \vec{B}) = \vec{A}(\vec{\nabla} \cdot \vec{B}) - \vec{A} \cdot (\vec{\nabla} \vec{B})$

Then: $\vec{\nabla} \times \left(\vec{M}(\vec{r}') \times \left(\frac{\hat{r}}{r^2} \right) \right) = \vec{M}(\vec{r}') \left[\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) \right] - \left(\vec{M}(\vec{r}') \cdot \vec{\nabla} \left(\frac{\hat{r}}{r^2} \right) \right)$

Thus: $\vec{B}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{v'} \vec{M}(\vec{r}') \left[\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' - \left(\frac{\mu_o}{4\pi} \right) \int_{v'} \left(\vec{M}(\vec{r}') \cdot \vec{\nabla} \left(\frac{\hat{r}}{r^2} \right) \right) d\tau'$

Let us now divide the volume v' of the magnetized magnetic material into two regions. A very small spherical region v'_1 of radius a , and a surrounding region of volume v'_2 . Then $v' = v'_1 + v'_2$. We locate the observation / field point $P(\vec{r})$ at the center of spherical volume v'_1 as shown in figure below:



Then:

$$\begin{aligned} \vec{B}^{inside}(\vec{r}) &= \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \vec{M}(\vec{r}') \left[\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' - \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\vec{M}(\vec{r}') \cdot \vec{\nabla} \left(\frac{\hat{r}}{r^2} \right) \right) d\tau' \\ &= \stackrel{(1)}{\left(\frac{\mu_o}{4\pi}\right) \int_{v'_1} \vec{M}(\vec{r}') \left[\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau'} - \stackrel{(2)}{\left(\frac{\mu_o}{4\pi}\right) \int_{v'_1} \left(\vec{M}(\vec{r}') \cdot \vec{\nabla} \left(\frac{\hat{r}}{r^2} \right) \right) d\tau'} \\ &+ \stackrel{(3)}{\left(\frac{\mu_o}{4\pi}\right) \int_{v'_2} \vec{M}(\vec{r}') \left[\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau'} - \stackrel{(4)}{\left(\frac{\mu_o}{4\pi}\right) \int_{v'_2} \left(\vec{M}(\vec{r}') \cdot \vec{\nabla} \left(\frac{\hat{r}}{r^2} \right) \right) d\tau'} \end{aligned}$$

Recall that:

$$\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) = \vec{\nabla} \cdot \left(\frac{\vec{r}}{r^3} \right) = \vec{\nabla} \cdot \left(\frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) = -\vec{\nabla}' \cdot \left(\frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) = -\vec{\nabla}' \cdot \left(\frac{\vec{r}}{r^3} \right) = -\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right)$$

Or:

$$\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) = -\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right)$$

Then terms (1) and (3) become:

$$\begin{aligned} \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \vec{M}(\vec{r}') \left[\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' &= \stackrel{(1)}{\left(\frac{\mu_o}{4\pi}\right) \int_{v'_1} \vec{M}(\vec{r}') \left[\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau'} + \stackrel{(3)}{\left(\frac{\mu_o}{4\pi}\right) \int_{v'_2} \vec{M}(\vec{r}') \left[\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau'} \\ &= -\left(\frac{\mu_o}{4\pi}\right) \int_{v'} \vec{M}(\vec{r}') \left[\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' = -\stackrel{(1)}{\left(\frac{\mu_o}{4\pi}\right) \int_{v'_1} \vec{M}(\vec{r}') \left[\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau'} - \stackrel{(3)}{\left(\frac{\mu_o}{4\pi}\right) \int_{v'_2} \vec{M}(\vec{r}') \left[\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau'} \end{aligned}$$

Now note that:

$$\int_{v'} \left[\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' = \int_{v'} \left[\vec{\nabla}' \cdot \frac{(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \right] d\tau' = - \int_{S'} \left[\frac{(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \cdot \hat{n} \right] da' = - \int_{S'} \left[\frac{(\hat{r} - \hat{r}')}{|\vec{r} - \vec{r}'|^2} \cdot \hat{n} \right] da' = - \int_{S'} \left[\left(\frac{\hat{r}}{r^2} \right) \cdot \hat{n} \right] da'$$

$$= - \int_{S'} \left(\frac{\hat{r} \cdot \hat{n}}{r^2} \right) da' = - \int_{\Omega'} d\Omega' \Leftarrow \text{solid} \not\Leftarrow \text{looking inside!!!}$$

Recall also that: $\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) = -\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) = 4\pi\delta^3(\vec{r})$, i.e. $\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) = -4\pi\delta^3(\vec{r})$ thus:

$$\int_{v'} \left[\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' = \int_{v'} \left[\vec{\nabla}' \cdot \frac{(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \right] d\tau' = -4\pi \int_{v'} \delta^3(\vec{r}) d\tau' = - \int_{\Omega'} d\Omega' = \begin{cases} -4\pi & \text{if } \vec{r} \text{ in volume } v' \\ 0 & \text{if } \vec{r} \text{ not in volume } v' \end{cases}$$

Similarly, we also see that for an arbitrary scalar point function $f(\vec{r}')$ that:

$$\int_{v'} f(\vec{r}') \left[\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' = -4\pi \int_{v'} f(\vec{r}') \delta^3(\vec{r}) d\tau' = \begin{cases} -4\pi f(\vec{r}) & \text{if } \vec{r} \text{ is in volume } v' \\ 0 & \text{if } \vec{r} \text{ not in volume } v' \end{cases}$$

$$= - \int_{S'} f(\vec{r}') \left(\frac{\hat{r} \cdot \hat{n}}{r^2} \right) da' = - \int_{\Omega'} f(\vec{r}') d\Omega'$$

Likewise, we also see that for an arbitrary vector point function $\vec{A}(\vec{r}')$ that:

$$\int_{v'} \vec{A}(\vec{r}') \left[\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' = -4\pi \int_{v'} \vec{A}(\vec{r}') \delta^3(\vec{r}) d\tau' = \begin{cases} -4\pi \vec{A}(\vec{r}) & \text{if } \vec{r} \text{ is in volume } v' \\ 0 & \text{if } \vec{r} \text{ not in volume } v' \end{cases}$$

$$= - \int_{S'} \vec{A}(\vec{r}') \left(\frac{\hat{r} \cdot \hat{n}}{r^2} \right) da' = - \int_{\Omega'} \vec{A}(\vec{r}') d\Omega'$$

However, note that the observation/field point $P(\vec{r})$, located at \vec{r} is not contained within the volume v'_2 - it is located at the center of spherical volume v'_1 (see/refer to picture on page 3)!!

Thus, we see that term (3) vanishes, i.e. $\int_{v'_2} \vec{M}(\vec{r}') \left[\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' = 0$ and that term (1)

$$\left(\frac{\mu_o}{4\pi} \right) \int_{v'} \vec{M}(\vec{r}') \left[\vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' = - \left(\frac{\mu_o}{4\pi} \right) \int_{v'_1} \vec{M}(\vec{r}') \left[\vec{\nabla}' \cdot \left(\frac{\hat{r}}{r^2} \right) \right] d\tau' = \left(\frac{\mu_o}{4\pi} \right) \cancel{4\pi} \vec{M}(\vec{r}) = \mu_o \vec{M}(\vec{r})$$

What about terms (2) and (4)??

$$-\left(\frac{\mu_o}{4\pi}\right)\int_{v'}\left(\vec{M}(\vec{r}')\cdot\vec{\nabla}\left(\frac{\hat{r}}{r^2}\right)\right)d\tau' = -\quad^{(2)}\quad\left(\frac{\mu_o}{4\pi}\right)\int_{v'_1}\left(\vec{M}(\vec{r}')\cdot\vec{\nabla}\left(\frac{\hat{r}}{r^2}\right)\right)d\tau' - \quad^{(4)}\quad\left(\frac{\mu_o}{4\pi}\right)\int_{v'_2}\left(\vec{M}(\vec{r}')\cdot\vec{\nabla}\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'$$

Note that: $\vec{\nabla}\left(\vec{M}(\vec{r}')\cdot\left(\frac{\hat{r}}{r^2}\right)\right) = \vec{M}(\vec{r}')\cdot\vec{\nabla}\left(\frac{\hat{r}}{r^2}\right) + \vec{M}(\vec{r}')\times\left(\vec{\nabla}\times\left(\frac{\hat{r}}{r^2}\right)\right) = \vec{M}(\vec{r}')\cdot\vec{\nabla}\left(\frac{\hat{r}}{r^2}\right)$

The 2nd term vanishes because: $\vec{\nabla}\times\left(\frac{\hat{r}}{r^2}\right) = -\vec{\nabla}\times\vec{\nabla}\left(\frac{1}{r}\right) = 0$ {since: $\vec{\nabla}\times\vec{\nabla}f = \vec{\nabla}\times\vec{\nabla}\left(\frac{1}{r-r'}\right) = 0$ }

Thus:

$$\begin{aligned} &-\left(\frac{\mu_o}{4\pi}\right)\int_{v'}\left(\vec{M}(\vec{r}')\cdot\vec{\nabla}\left(\frac{\hat{r}}{r^2}\right)\right)d\tau' = -\left(\frac{\mu_o}{4\pi}\right)\vec{\nabla}\left[\int_{v'}\left(\vec{M}(\vec{r}')\cdot\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'\right] \\ &= -\quad^{(2)}\quad\left(\frac{\mu_o}{4\pi}\right)\vec{\nabla}\left[\int_{v'_1}\left(\vec{M}(\vec{r}')\cdot\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'\right] - \quad^{(4)}\quad\left(\frac{\mu_o}{4\pi}\right)\vec{\nabla}\left[\int_{v'_2}\left(\vec{M}(\vec{r}')\cdot\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'\right] \end{aligned}$$

We now define a magnetic *scalar* potential $V_m(\vec{r})$ for use with magnetic materials:

$$V_m(\vec{r}) \equiv \left(\frac{\mu_o}{4\pi}\right)\int_{v'}\left(\vec{M}(\vec{r}')\cdot\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'$$

Then we see that:

$$\begin{aligned} &-\left(\frac{\mu_o}{4\pi}\right)\int_{v'}\left(\vec{M}(\vec{r}')\cdot\vec{\nabla}\left(\frac{\hat{r}}{r^2}\right)\right)d\tau' = -\left(\frac{\mu_o}{4\pi}\right)\vec{\nabla}\left[\int_{v'}\left(\vec{M}(\vec{r}')\cdot\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'\right] = -\vec{\nabla}V_m(\vec{r}) \\ &= -\quad^{(2)}\quad\left(\frac{\mu_o}{4\pi}\right)\vec{\nabla}\left[\int_{v'_1}\left(\vec{M}(\vec{r}')\cdot\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'\right] - \quad^{(4)}\quad\left(\frac{\mu_o}{4\pi}\right)\vec{\nabla}\left[\int_{v'_2}\left(\vec{M}(\vec{r}')\cdot\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'\right] = -\vec{\nabla}V_m^{(2)[v'_1]}(\vec{r}) - \vec{\nabla}V_m^{(4)[v'_2]}(\vec{r}) \end{aligned}$$

Putting this all together now, finally we obtain:

$$\vec{B}^{inside}(\vec{r}) = \underbrace{\left(\frac{\mu_o}{4\pi}\right)\int_{v'}\vec{M}(\vec{r}')\left[\vec{\nabla}\cdot\left(\frac{\hat{r}}{r^2}\right)\right]d\tau'}_{=\mu_o\vec{M}(\vec{r})} - \underbrace{\left(\frac{\mu_o}{4\pi}\right)\int_{v'}\left(\vec{M}(\vec{r}')\cdot\vec{\nabla}\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'}_{=-\vec{\nabla}V_m(\vec{r})}$$

i.e. $\vec{B}^{inside}(\vec{r}) = \mu_o\vec{M}(\vec{r}) - \vec{\nabla}V_m(\vec{r})$ where $V_m(\vec{r}) \equiv \left(\frac{\mu_o}{4\pi}\right)\int_{v'}\left(\vec{M}(\vec{r}')\cdot\left(\frac{\hat{r}}{r^2}\right)\right)d\tau'$

Note that there are in fact *two* contributions to the magnetic scalar potential – one contribution arises from the integral (2) over the small, spherical region v'_1 (containing the “near” magnetic dipoles), the other contribution arises from the integral (4) over region v'_2 (containing the “far” magnetic dipoles):

$$\begin{aligned}
 V_m(\vec{r}) &= V_m^{(2)[v_1]}(\vec{r}) + V_m^{(4)[v_2]}(\vec{r}) \\
 V_m(\vec{r}) &\equiv \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\vec{M}(\vec{r}') \cdot \frac{\hat{r}}{r^2}\right) d\tau' = {}^{(2)} \left(\frac{\mu_o}{4\pi}\right) \int_{v_1} \left(\vec{M}(\vec{r}') \cdot \left(\frac{\hat{r}}{r^2}\right)\right) d\tau' + {}^{(4)} \left(\frac{\mu_o}{4\pi}\right) \int_{v_2} \left(\vec{M}(\vec{r}') \cdot \left(\frac{\hat{r}}{r^2}\right)\right) d\tau'
 \end{aligned}$$

and:

$$\begin{aligned}
 -\nabla V_m(\vec{r}) &= -\nabla \left[V_m^{(2)[v_1]}(\vec{r}) + V_m^{(4)[v_2]}(\vec{r}) \right] = -\nabla V_m^{(2)[v_1]}(\vec{r}) - \nabla V_m^{(4)[v_2]}(\vec{r}) \\
 &\equiv -\left(\frac{\mu_o}{4\pi}\right) \nabla \left[\int_{v'} \left(\vec{M}(\vec{r}') \cdot \frac{\hat{r}}{r^2}\right) d\tau' \right] = -{}^{(2)} \left(\frac{\mu_o}{4\pi}\right) \nabla \left[\int_{v_1} \left(\vec{M}(\vec{r}') \cdot \left(\frac{\hat{r}}{r^2}\right)\right) d\tau' \right] - {}^{(4)} \left(\frac{\mu_o}{4\pi}\right) \nabla \left[\int_{v_2} \left(\vec{M}(\vec{r}') \cdot \left(\frac{\hat{r}}{r^2}\right)\right) d\tau' \right]
 \end{aligned}$$

Note that the SI units for the above-defined magnetic scalar potential $V_m(\vec{r})$ are Tesla-meters (= Newtons/Ampere) which are the same units as that for the magnetic vector potential $\vec{A}(\vec{r})$:

$$\boxed{\vec{B}(\text{Teslas}) \sim -\vec{\nabla} V_m(\text{Teslas})} \Rightarrow \boxed{V_m(\text{Tesla-meters})}$$

$$\begin{aligned}
 &= \left(\frac{N}{A \cdot m}\right) & & = \left(\frac{N}{A \cdot m}\right) & & = \frac{N}{A \cdot m} \neq \frac{N}{A}
 \end{aligned}$$

Note that *this* magnetic scalar potential, $V_m(\vec{r})$ (SI units = Tesla-meters = Newtons/Ampere) as defined *here* for use with magnetic materials is *different* than the “*other*” magnetic scalar potential $\Phi_m(\vec{r})$ (SI units = Tesla-meters²) that we had previously introduced (and defined) in P435 Lecture Notes 16 (page 2) in the context of gauge transformations and the arbitrary nature of the magnetic vector potential: $\vec{A}'(\vec{r}) \equiv \vec{A}(\vec{r}) + \vec{\Delta}(\vec{r}) = \vec{A}(\vec{r}) + \vec{\nabla} \Phi_m(\vec{r})$ i.e. $\vec{\Delta}(\vec{r}) = \vec{\nabla} \Phi_m(\vec{r})$.

Use(s) of the Magnetic Scalar Potential $V_m(\vec{r})$

Surface & Volume Densities of Magnetic Pole Strength (i.e. Bound Magnetic Charge Densities)
 $\sigma_m(\vec{r})$ and $\rho_m(\vec{r})$

Inside a magnetic material with macroscopic magnetization (magnetic dipole moment per unit volume) $\vec{M}(\vec{r})$ we have the constitutive relation:

$$\vec{H}^{inside}(\vec{r}) = \frac{1}{\mu_o} \vec{B}^{inside}(\vec{r}) - \vec{M}(\vec{r})$$

i.e. $\vec{B}^{inside}(\vec{r}) = \mu_o \vec{H}^{inside}(\vec{r}) + \mu_o \vec{M}(\vec{r})$ or: $\vec{B}^{inside}(\vec{r}) = \mu_o \vec{M}(\vec{r}) + \mu_o \vec{H}^{inside}(\vec{r})$.

However, we also have just derived:

$$\vec{B}^{inside}(\vec{r}) = \mu_o \vec{M}(\vec{r}) - \vec{\nabla} V_m(\vec{r})$$

Thus we see that $\vec{H}^{inside}(\vec{r}) = -\vec{\nabla} V_m(\vec{r}) / \mu_o$.

However, we also need to consider here the previously-derived constraints:

$\vec{\nabla} \cdot \vec{H}^{inside}(\vec{r}) = -\vec{\nabla} \cdot \vec{M}(\vec{r})$, obtained from $\vec{\nabla} \cdot \vec{B}^{inside}(\vec{r}) = 0$, and also that associated with

Ampere's law for $\vec{H}^{inside}(\vec{r})$, namely: $\vec{\nabla} \times \vec{H}^{inside}(\vec{r}) = \vec{J}_{free}^{inside}(\vec{r})$.

But if $\vec{H}^{inside}(\vec{r}) = -\vec{\nabla}V_m(\vec{r})/\mu_o$, then: $\vec{\nabla} \times \vec{H}^{inside}(\vec{r}) = -\underbrace{\vec{\nabla} \times \vec{\nabla}V_m(\vec{r})}_{=0 \text{ always!!!}}/\mu_o = 0$

Thus, we see that the (proper) use of the magnetic scalar potential $V_m(\vec{r})$ restricts us to use it only in cases where there are no free currents contained anywhere within the source volume v' , i.e. we must have (i.e. we demand that) $\vec{J}_{free}^{inside}(\vec{r}) = 0$ everywhere within the source volume v' , in order to be able to (properly/correctly) use the magnetic scalar potential $V_m(\vec{r})$.

If the condition $\vec{J}_{free}^{inside}(\vec{r}) = 0$ is satisfied everywhere within the source volume v' , then we also see from $\vec{H}^{inside}(\vec{r}) = -\vec{\nabla}V_m(\vec{r})/\mu_o$, along with the condition $\vec{\nabla} \cdot \vec{H}^{inside}(\vec{r}) = -\vec{\nabla} \cdot \vec{M}(\vec{r})$ that $\vec{\nabla} \cdot \vec{H}^{inside}(\vec{r}) = -\vec{\nabla} \cdot \vec{\nabla}V_m(\vec{r})/\mu_o = -\nabla^2 V_m(\vec{r})/\mu_o = -\vec{\nabla} \cdot \vec{M}(\vec{r}) = \rho_m(\vec{r})$

i.e. we obtain (another kind of) Poisson's equation for this magnetic scalar potential $V_m(\vec{r})$ of the form: $\nabla^2 V_m(\vec{r}) = \mu_o \vec{\nabla} \cdot \vec{M}(\vec{r}) = -\mu_o \rho_m(\vec{r})$. Note that this also says that: $\rho_m(\vec{r}) = -\vec{\nabla} \cdot \vec{M}(\vec{r})$.

Again, we (already) know the form of the solutions to this magnetic Poisson's equation:

$$V_m(\vec{r}) = \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \frac{\rho_m^{Bound}(\vec{r}')}{r} d\tau' + \left(\frac{\mu_o}{4\pi}\right) \int_{S'} \frac{\sigma_m^{Bound}(\vec{r}')}{r} da'$$

where $\rho_m^{Bound}(\vec{r}')$ and $\sigma_m^{Bound}(\vec{r}')$ are effective bound volume and surface magnetic charge densities contained within the source volume v' and/or on the surface S' that encloses the volume v' .

What are the effective bound volume and surface magnetic charge densities $\rho_m^{Bound}(\vec{r}')$ and $\sigma_m^{Bound}(\vec{r}')$???

We have derived (i.e. defined) the magnetic scalar potential $V_m(\vec{r})$ as:

$$V_m(\vec{r}) \equiv \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\vec{M}(\vec{r}') \cdot \frac{\hat{r}}{r^2}\right) d\tau' = \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\vec{M}(\vec{r}') \cdot \vec{\nabla} \left(\frac{1}{r}\right)\right) d\tau' \quad \text{since} \quad \frac{\hat{r}}{r^2} = \vec{\nabla} \left(\frac{1}{r}\right)$$

But: $\vec{\nabla} \left(\frac{1}{r}\right) = \vec{\nabla} \left(\frac{1}{|\vec{r} - \vec{r}'|}\right) = -\vec{\nabla}' \left(\frac{1}{|\vec{r} - \vec{r}'|}\right) = -\vec{\nabla}' \left(\frac{1}{r}\right)$

Thus:

$$V_m(\vec{r}) \equiv \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\vec{M}(\vec{r}') \cdot \frac{\hat{r}}{r^2}\right) d\tau' = \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\vec{M}(\vec{r}') \cdot \vec{\nabla} \left(\frac{1}{r}\right)\right) d\tau' = -\left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\vec{M}(\vec{r}') \cdot \vec{\nabla}' \left(\frac{1}{r}\right)\right) d\tau'$$

However, from Griffiths Product Rule # 5: $\vec{\nabla} \cdot (f\vec{A}) = f(\vec{\nabla} \cdot \vec{A}) + \vec{A} \cdot (\vec{\nabla} f)$

then: $\vec{A} \cdot (\vec{\nabla} f) = \vec{\nabla} \cdot (f\vec{A}) - f(\vec{\nabla} \cdot \vec{A})$ thus if: $f = \left(\frac{1}{r}\right)$ and $\vec{A} = \vec{M}$ then we see that:

$$V_m(\vec{r}) = -\left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\vec{M}(\vec{r}') \cdot \vec{\nabla}' \left(\frac{1}{r} \right) \right) d\tau' = \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \vec{\nabla}' \cdot \left(\frac{\vec{M}(\vec{r}')}{r} \right) d\tau' - \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \frac{1}{r} (\vec{\nabla}' \cdot \vec{M}(\vec{r}')) d\tau'$$

$$= -\left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\frac{\vec{\nabla}' \cdot \vec{M}(\vec{r}')}{r} \right) d\tau' + \left(\frac{\mu_o}{4\pi}\right) \int_{s'} \left(\frac{\vec{M}(\vec{r}') \cdot \hat{n}}{r} \right) da'$$

We can therefore define:

- 1) An effective bound surface density of magnetic pole strength (= effective bound surface magnetic charge density):

$$\sigma_m^{Bound}(\vec{r}') \equiv \vec{M}(\vec{r}') \cdot \hat{n} \Big|_{surface} \quad \text{SI Units of } \sigma_m^{Bound} = \text{Magnetization } \vec{M} = \text{Amperes/meter}$$

Recall that the SI Units of magnetic charge $g_m = qv = \text{Ampere-Meters}$

$$\sigma_m^{Bound} = \frac{g_m}{\text{Area}, A} = \frac{\text{Ampere} - \text{meters}}{(\text{meters})^2} = \text{Amperes} / \text{meter}$$

- 2) The effective bound volume density of magnetic pole strength (= effective bound volume magnetic charge density):

$$\rho_m^{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{M}(\vec{r}') \quad \text{SI Units of } \rho_m^{Bound} = \text{Amperes} / \text{meter}^2$$

$$\rho_m^{Bound} = \frac{g_m}{\text{Volume}, V} = \frac{\text{Ampere} - \text{meters}}{\text{meters}^3} = \text{Amperes} / \text{meter}^2$$

Thus, we see that the magnetic scalar potential $V_m(\vec{r})$ can be written as:

$$V_m(\vec{r}) = -\left(\frac{\mu_o}{4\pi}\right) \int_{v'} \left(\frac{\vec{\nabla}' \cdot \vec{M}(\vec{r}')}{r} \right) d\tau' + \left(\frac{\mu_o}{4\pi}\right) \int_{s'} \left(\frac{\vec{M}(\vec{r}') \cdot \hat{n}}{r} \right) da'$$

$$V_m(\vec{r}) = \left(\frac{\mu_o}{4\pi}\right) \int_{v'} \frac{\rho_m^{Bound}(\vec{r}')}{r} d\tau' + \left(\frac{\mu_o}{4\pi}\right) \int_{s'} \frac{\sigma_m^{Bound}(\vec{r}')}{r} da'$$

with: $\rho_m^{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{M}(\vec{r}')$ and $\sigma_m^{Bound}(\vec{r}') \equiv \vec{M}(\vec{r}') \cdot \hat{n} \Big|_{surface}$

Important Note:

$\sigma_m^{Bound}(\vec{r}')$ and $\rho_m^{Bound}(\vec{r}')$ are fixed/immovable bound magnetic charge densities!!!

The above is analogous to the electrostatic scalar potential $V_e(\vec{r})$ for dielectric materials:

$$\text{Electrostatic Scalar Potential: } V_e(\vec{r}) = -\frac{1}{4\pi\epsilon_o} \int_{v'} \left(\frac{\vec{\nabla}' \cdot \vec{P}(\vec{r}')}{r} \right) d\tau' + \frac{1}{4\pi\epsilon_o} \int_{s'} \left(\frac{\vec{P}(\vec{r}') \cdot \hat{n}}{r} \right) da'$$

$$V_e(\vec{r}) = \frac{1}{4\pi\epsilon_o} \int_{v'} \frac{\rho_{Bound}(\vec{r}')}{r} d\tau' + \frac{1}{4\pi\epsilon_o} \int_{s'} \frac{\sigma_{Bound}(\vec{r}')}{r} da'$$

$$\text{with: } \rho_{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{P}(\vec{r}') \quad \text{and} \quad \sigma_{Bound}(\vec{r}') \equiv \vec{P}(\vec{r}') \cdot \hat{n}|_{\text{surface}}$$

Thus for a magnetic material with macroscopic magnetization \vec{M} , the magnetic field inside such a material is given by:

$$\vec{B}^{inside}(\vec{r}) = \mu_o \vec{M}(\vec{r}) - \vec{\nabla} V_m(\vec{r}) \quad \text{with: } V_m(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{v'} \frac{\rho_m^{Bound}(\vec{r}')}{r} d\tau' + \left(\frac{\mu_o}{4\pi} \right) \int_{s'} \frac{\sigma_m^{Bound}(\vec{r}')}{r} da'$$

$$\text{and with: } \rho_m^{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{M}(\vec{r}') \quad \text{and} \quad \sigma_m^{Bound}(\vec{r}') \equiv \vec{M}(\vec{r}') \cdot \hat{n}|_{\text{surface}}$$

Therefore:

$$\vec{B}^{inside}(\vec{r}) = \mu_o \vec{M}(\vec{r}) - \vec{\nabla} V_m(\vec{r}) = \mu_o \vec{M}(\vec{r}) - \left(\frac{\mu_o}{4\pi} \right) \int_{v'} \vec{\nabla} \left(\frac{\rho_m^{Bound}(\vec{r}')}{r} \right) d\tau' - \left(\frac{\mu_o}{4\pi} \right) \int_{s'} \vec{\nabla} \left(\frac{\sigma_m^{Bound}(\vec{r}')}{r} \right) da'$$

Now: $\vec{\nabla} = \text{fcn}(\vec{r})$ only, $\rho_m = \text{fcn}(\vec{r}')$ only, $\sigma_m = \text{fcn}(\vec{r}')$ only.

$$\therefore \vec{B}^{inside}(\vec{r}) = \mu_o \vec{M}(\vec{r}) - \left(\frac{\mu_o}{4\pi} \right) \int_{v'} \rho_m^{Bound}(\vec{r}') \vec{\nabla} \left(\frac{1}{r} \right) d\tau' - \left(\frac{\mu_o}{4\pi} \right) \int_{s'} \sigma_m^{Bound}(\vec{r}') \vec{\nabla} \left(\frac{1}{r} \right) da'$$

$$\text{But again: } \vec{\nabla} \left(\frac{1}{r} \right) = -\vec{\nabla}' \left(\frac{1}{r} \right) = -\frac{\hat{r}}{r^2}$$

$$\therefore \vec{B}^{inside}(\vec{r}) = \mu_o \vec{M}(\vec{r}) + \frac{\mu_o}{4\pi} \int_{v'} \rho_m^{Bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) d\tau' + \frac{\mu_o}{4\pi} \int_{s'} \sigma_m^{Bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) da'$$

$$\text{with } \rho_m^{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{M}(\vec{r}') \quad \text{and} \quad \sigma_m^{Bound}(\vec{r}') \equiv \vec{M}(\vec{r}') \cdot \hat{n}|_{\text{surface}}$$

Similarly for a dielectric material, using $\vec{E}^{inside}(\vec{r})$ can be analogously shown to be:

$$\vec{E}^{inside}(\vec{r}) = -\frac{1}{\epsilon_o} \vec{P}(\vec{r}) - \vec{\nabla} V_e(\vec{r}) \quad (\text{Note that } \vec{E}^{inside} \text{ and } \vec{P} \text{ point in opposite directions})$$

$$\vec{E}^{inside}(\vec{r}) = -\frac{1}{\epsilon_o} \vec{P}(\vec{r}) - \frac{1}{4\pi\epsilon_o} \int_{v'} \vec{\nabla} \left(\frac{\rho_{Bound}(\vec{r}')}{r} \right) d\tau' - \frac{1}{4\pi\epsilon_o} \int_{s'} \vec{\nabla} \left(\frac{\sigma_{bound}(\vec{r}')}{r} \right) da'$$

Again: $\vec{\nabla} \left(\frac{1}{r} \right) = -\vec{\nabla}' \left(\frac{1}{r} \right) = -\frac{\hat{r}}{r^2}$ and $\vec{\nabla} = \text{fcn}(\vec{r})$ only, $\rho_{Bound} = \text{fcn}(\vec{r}')$ only, $\sigma_{Bound} = \text{fcn}(\vec{r}')$ only.

$$\vec{E}^{inside}(\vec{r}) = -\frac{1}{\epsilon_o} \vec{P}(\vec{r}) + \frac{1}{4\pi\epsilon_o} \int_{v'} \rho_{bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) d\tau' + \frac{1}{4\pi\epsilon_o} \int_{s'} \sigma_{bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) da'$$

$$\text{with } \rho_{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{P}(\vec{r}') \quad \text{and} \quad \sigma_{Bound}(\vec{r}') \equiv \vec{P}(\vec{r}') \cdot \hat{n}|_{\text{surface}}$$

If additionally, there exist free volume and/or free surface charge densities $\rho_{free}(\vec{r}')$, $\sigma_{free}(\vec{r}')$ and free volume and/or surface current densities $\vec{J}_{free}(\vec{r}')$, $\vec{K}_{free}(\vec{r}')$ within the volume v' or residing on the enclosing surface S' , then the most general form(s) of $\vec{B}^{inside}(\vec{r})$ and $\vec{E}^{inside}(\vec{r})$ are given by:

$$\vec{B}^{inside}(\vec{r}) = \frac{\mu_o}{4\pi} \int_{v'} \frac{\vec{J}_{free}(\vec{r}') \times \hat{r}}{r^2} d\tau' + \mu_o \vec{M}(\vec{r}) - \vec{\nabla} V_m(\vec{r})$$

with:
$$-\vec{\nabla} V_m(\vec{r}) = \frac{\mu_o}{4\pi} \int_{v'} \rho_m^{Bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) d\tau' + \frac{\mu_o}{4\pi} \int_{S'} \sigma_m^{Bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) da'$$

and with:
$$\rho_m^{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{M}(\vec{r}') \quad \text{and} \quad \sigma_m^{Bound}(\vec{r}') \equiv \vec{M}(\vec{r}') \cdot \hat{n}|_{surface}$$

$$\vec{E}^{inside}(\vec{r}) = \frac{1}{4\pi\epsilon_o} \int_{v'} \rho_{free}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) d\tau' - \frac{1}{\epsilon_o} \vec{P}(\vec{r}) - \vec{\nabla} V_e(\vec{r})$$

with:
$$-\vec{\nabla} V_e(\vec{r}) = \frac{1}{4\pi\epsilon_o} \int_{v'} \rho_{bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) d\tau' + \frac{1}{4\pi\epsilon_o} \int_{S'} \sigma_{bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) da'$$

and with:
$$\rho_{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{P}(\vec{r}') \quad \text{and} \quad \sigma_{Bound}(\vec{r}') \equiv \vec{P}(\vec{r}') \cdot \hat{n}|_{surface}$$

- Thus, $\vec{B}^{inside}(\vec{r})$ can be determined if $\vec{M}(\vec{r})$ and $\vec{J}_{free}(\vec{r}')$ are specified at all points \vec{r}' in the source volume v' enclosed by the bounding surface S' .
- Similarly, $\vec{E}^{inside}(\vec{r})$ can be determined if $\vec{P}(\vec{r})$ and $\rho_{free}(\vec{r}')$ are specified at all points \vec{r}' in the source volume v' enclosed by the bounding surface S' .

However, in most problems, $\vec{J}_{free}(\vec{r}')$ (and $\rho_{free}(\vec{r}')$) are specified (or can be specified / are analytically known), but $\vec{M}(\vec{r})$ (and $\vec{P}(\vec{r})$) themselves depend on $\vec{B}^{inside}(\vec{r})$ (and $\vec{E}^{inside}(\vec{r})$) respectively.

→ Even if the functional form(s) of $\vec{M}(\vec{r})$ and $\vec{P}(\vec{r})$ are known, i.e. $\vec{M}(\vec{r}') = \text{fcn}(\vec{B}^{inside}(\vec{r}'))$ and $\vec{P}(\vec{r}') = \text{fcn}(\vec{E}^{inside}(\vec{r}'))$, we still have (at best) an integral equation to solve!!!

This is the motivation for introducing the auxiliary fields \vec{H} and \vec{D} thereby obtaining the constitutive relations:

\vec{H} = magnetic “displacement”	$\vec{H} = \frac{1}{\mu_o} \vec{B} - \vec{M} \Rightarrow \vec{B} = \mu_o (\vec{H} + \vec{M})$
\vec{D} = electric “displacement”	$\vec{D} = \epsilon_o \vec{E} + \vec{P} \Rightarrow \vec{E} = \frac{1}{\epsilon_o} (\vec{D} - \vec{P})$

From the above constitutive relations, we see that:

	$\vec{H}^{inside}(\vec{r}) = \frac{1}{4\pi} \int_{v'} \frac{\vec{J}_{free}(\vec{r}') \times \hat{r}}{r^2} d\tau' - \frac{1}{\mu_o} \vec{\nabla} V_m(\vec{r})$
with:	$-\vec{\nabla} V_m(\vec{r}) = \frac{\mu_o}{4\pi} \int_{v'} \rho_m^{Bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) d\tau' + \frac{\mu_o}{4\pi} \int_{s'} \sigma_m^{Bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) da'$
and with:	$\rho_m^{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{M}(\vec{r}') \quad \text{and} \quad \sigma_m^{Bound}(\vec{r}') \equiv \vec{M}(\vec{r}') \cdot \hat{n} _{surface}$
	$\vec{D}^{inside}(\vec{r}) = \frac{1}{4\pi} \int_{v'} \rho_{free}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) d\tau' - \epsilon_o \nabla V_e(\vec{r})$
with:	$-\epsilon_o \nabla V_e(\vec{r}) = \frac{1}{4\pi} \int_{v'} \rho_{bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) d\tau' + \frac{1}{4\pi} \int_{s'} \sigma_{bound}(\vec{r}') \left(\frac{\hat{r}}{r^2} \right) da'$
and with:	$\rho_{Bound}(\vec{r}') \equiv -\vec{\nabla}' \cdot \vec{P}(\vec{r}') \quad \text{and} \quad \sigma_{Bound}(\vec{r}') \equiv \vec{P}(\vec{r}') \cdot \hat{n} _{surface}$

The boundary conditions on B , H , E , D , M and P at interfaces/boundaries will constrain / determine $\vec{M}(\vec{r}')$ and $\vec{P}(\vec{r}')$ inside these materials, as well as the behavior of the fields inside/outside these materials.

Electrostatic Boundary Conditions

Magnetostatic Boundary Conditions

$$E_2^{\parallel} = E_1^{\parallel}$$

$$D_2^{\perp} - D_1^{\perp} = \sigma_{free}|_{surface}$$

$$E_2^{\perp} - E_1^{\perp} = \frac{1}{\epsilon_o} \sigma_{TOT} = \frac{1}{\epsilon_o} (\sigma_{free} + \sigma_{bound})|_{surface}$$

$$D_2^{\parallel} - D_1^{\parallel} = P_2^{\parallel} - P_1^{\parallel}$$

$$\epsilon_2 \frac{\partial V_2}{\partial n}|_{interface} - \epsilon_1 \frac{\partial V_1}{\partial n}|_{interface} = -\sigma_{free}$$

$$\epsilon_0 \left(\frac{\partial V_2}{\partial n}|_{interface} - \frac{\partial V_1}{\partial n}|_{interface} \right) = -\sigma_{TOT}$$

$$B_2^{\perp} = B_1^{\perp}$$

$$\vec{H}_2 - \vec{H}_1 = \vec{K}_{free} \times \hat{n}|_{surface}$$

$$\vec{B}_2 - \vec{B}_1 = \mu_o \vec{K}_{TOT} \times \hat{n}|_{surface} = \mu_o (\vec{K}_{free} + \vec{K}_{Bound}) \times \hat{n}|_{surface}$$

$$H_2^{\perp} - H_1^{\perp} = -(M_2^{\perp} - M_1^{\perp})$$

$$\frac{1}{\mu_2} \frac{\partial \vec{A}_2}{\partial n}|_{interface} - \frac{1}{\mu_1} \frac{\partial \vec{A}_1}{\partial n}|_{interface} = -\vec{K}_{free}$$

$$\frac{1}{\mu_o} \left(\frac{\partial \vec{A}_2}{\partial n}|_{interface} - \frac{\partial \vec{A}_1}{\partial n}|_{interface} \right) = -\vec{K}_{TOT}$$

In P435 Lecture Notes 20.5, we will explicitly show/work through a few examples of this.

The Langevin Equation for Paramagnetic Materials

** n.b. See / refer to P435 Lecture Notes #12 for a more complete derivation of the Langevin equation, for the case of polar dielectric materials.

A paramagnetic material is analogous to a polar dielectric in that it has permanent atomic / molecular magnetic dipole moments \vec{m}_{mol} uniformly / randomly oriented (due to thermal internal energy / energy fluctuations $\sim k_B T$) in the absence of an externally applied magnetic field \vec{B}_{ext} . Thermal energy in the magnetic material (and fluctuations thereof) is responsible for macroscopically depolarizing the atomic / molecular magnetic dipole moments.

When a paramagnetic material is placed in an external \vec{B} -field, a partial macroscopic alignment of the atomic / molecular magnetic dipoles results, which is temperature dependent.

The (macroscopic) magnetic polarization – the magnetization (= magnetic dipole moment per unit volume) \vec{M} of a paramagnetic material is well-described by the Langevin equation (as we found for the case of polar dielectrics, i.e. dielectric materials with permanent atomic / molecular electric dipole moments \vec{p}_{mol}) The same analogous physics applies - for the electrostatics case, the energy of an electric dipole in the macroscopic, space-and-time-averaged local electric field is $W_E = \vec{p} \cdot \vec{E} = -\vec{p}_{mol} \cdot \langle \vec{E}_{loc} \rangle$ (see P435 Lecture Notes 12 for details on $\langle \vec{E}_{loc} \rangle$), thus the energy of an atomic/molecular magnetic dipole with magnetic dipole moment \vec{m}_{mol} in the macroscopic, space-and-time-averaged local magnetic field $\langle \vec{B}_{loc} \rangle$ associated with a paramagnetic material is $W_M = \vec{m} \cdot \vec{B} = -\vec{m}_{mol} \cdot \langle \vec{B}_{loc} \rangle$. The derivation of the Langevin equation for paramagnetic materials exactly parallels that for polar dielectrics, so we will not repeat this here – we'll just give the results:

$$\boxed{\vec{M} = n_{mol} m_{mol} \left(\coth u - \frac{1}{u} \right) = n_{mol} m_{mol} \left[\coth \left(\frac{m_{mol} \langle B_{loc} \rangle}{k_B T} \right) - \left(\frac{k_B T}{m_{mol} \langle B_{loc} \rangle} \right) \right]}$$

where:

n_{mol} = # density of magnetic dipoles = # of magnetic dipole moments per unit volume

$u \equiv \frac{m_{mol} \langle B_{loc} \rangle}{k_B T}$ k_B = Boltzmann's constant = 1.381×10^{-23} Joules / Kelvin

T = absolute temperature (Kelvin degrees)

At room temperature, $T \sim 300$ K:

$u \equiv \frac{m_{mol} \langle B_{loc} \rangle}{k_B T} \approx 2.5 \times 10^{-3} \ll 1$ for typical paramagnetic materials with

e.g. $|\langle \vec{B}_{loc} \rangle| \sim 0.1$ Tesla (= 1 K Gauss) (10^4 Gauss = 1 Tesla)

i.e. $k_B T \left(\approx \frac{1}{40} eV @ T = 300 K \right) \gg m_{mol} \langle B_{loc} \rangle$ unless e.g. B_{ext} is very large.

For $u \ll 1$ we have $\coth(u) \approx \frac{1}{u} + \frac{u}{3} - \frac{u^3}{45} + \frac{2u^5}{945} + \dots$ and thus: $M(\vec{r}) \approx \frac{n_{mol} m_{mol}^2}{3k_B T} \langle B_{loc}(\vec{r}) \rangle$

Curie's Law for paramagnetic materials (valid only when $u \ll 1$) is: $M(\vec{r}) = \frac{C}{T} \langle B_{loc}(\vec{r}) \rangle$

where the Curie constant C of the paramagnetic material is: $C \approx \frac{n_{mol} m_{mol}^2}{3k_B}$

For $u \equiv \frac{m_{mol} \langle B_{loc} \rangle}{k_B T} \ll 1$ then if $M(\vec{r}) = \chi_m \vec{H}(\vec{r})$ or, since $\chi_m > 0$ for a paramagnetic material:

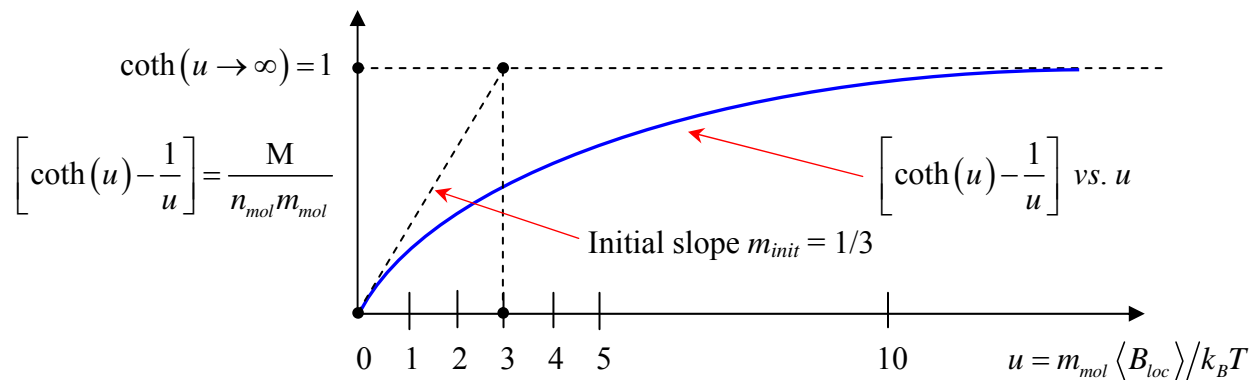
$$\chi_m = \frac{|\vec{M}(\vec{r})|}{|\vec{H}(\vec{r})|} = \mu \frac{|\vec{M}(\vec{r})|}{|\vec{B}(\vec{r})|} \approx \mu_o \frac{|\vec{M}(\vec{r})|}{\langle \vec{B}_{loc}(\vec{r}) \rangle} \approx \mu_o \frac{n_{mol} m_{mol}^2}{3k_B T}$$

$$\text{Thus: } \chi_m \approx \mu_o \left(\frac{n_{mol} m_{mol}^2}{3k_B T} \right) > 0 \text{ for } m_{mol} \langle B_{loc} \rangle \ll k_B T$$

$\rightarrow \chi_m \sim 1/T$ for $m_{mol} \langle B_{loc} \rangle \ll k_B T$ (as we found for $\chi_e \sim 1/T$ for $p_{mol} \langle E_{loc} \rangle \ll k_B T$)

In paramagnetic materials note that the magnetization \vec{M}_{para} is parallel to the externally-applied magnetic field \vec{B}_{ext} and \vec{H} -field, since $\vec{M} = \chi_m \vec{H} \Rightarrow \chi_m^{para} > 0$.

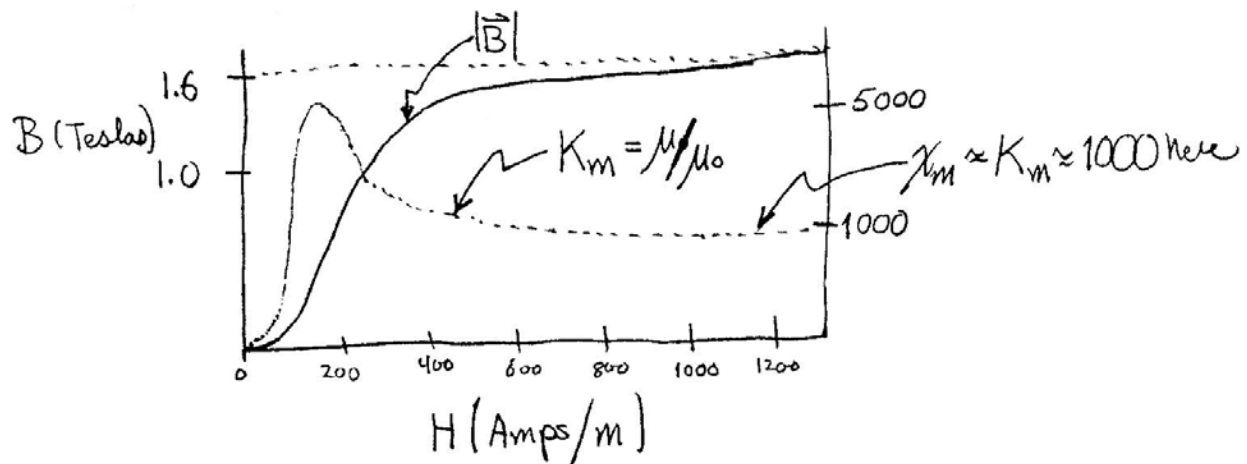
A plot of the Langevin Function $\left[\coth(u) - \frac{1}{u} \right] = \frac{M}{n_{mol} m_{mol}}$ versus $u = \frac{m_{mol} \langle B_{loc} \rangle}{k_B T}$ is shown below:



Ferromagnetic Materials

Ferromagnetic materials are “hard” magnetic materials – i.e. magnetic materials with permanent magnetic polarization $\vec{M}(\vec{r})$, analogous to the permanent electric polarization $\vec{P}(\vec{r})$ associated e.g. with bar electrets. Like bar electrets, where the constitutive relation $\vec{D}(\vec{r}) = \epsilon_0 \vec{E}(\vec{r}) + \vec{P}(\vec{r})$ is valid, and where the relation $\vec{D}(\vec{r}) = \epsilon \vec{E}(\vec{r})$ ($\epsilon = \text{constant}$) is not valid (it is valid only for linear/Class-A dielectric materials), for “hard” magnetic materials (such as ferro-magnets), the constitutive relation $\vec{H}(\vec{r}) = \vec{B}(\vec{r})/\mu_0 - \vec{M}(\vec{r})$ is valid, however the relation $\vec{H}(\vec{r}) = \vec{B}(\vec{r})/\mu$ ($\mu = \text{constant}$) is not valid – it is valid only for “soft”(i.e. linear) magnetic dielectric materials, because $\mu = \mu(H)$ and is dependent on the past history of the ferromagnetic material! The relations $\vec{D}(\vec{r}) = \epsilon \vec{E}(\vec{r})$ and $\vec{H}(\vec{r}) = \vec{B}(\vec{r})/\mu$ can be used for permanently polarized materials, however one must realize that ϵ and μ are not constants in such materials.

The Magnetization Curve and Relative Magnetic Permeability $K_m \equiv \mu/\mu_0$ of Annealed Iron:



K_m = relative (a.k.a. differential) magnetic permeability:

$$K_m(H) \equiv \mu(H)/\mu_0 = \frac{1}{\mu_0} \frac{dB}{dH}$$

K_m is also known as the differential magnetic permeability

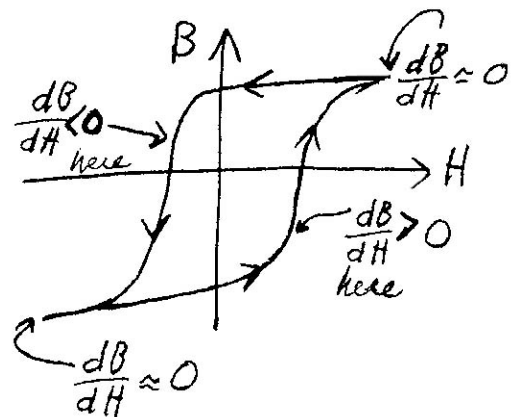
because (here) $B = \mu(H)H$ i.e. the magnetic

permeability $\mu(H)$ is not a constant: $\mu(H) = K_m(H)\mu_0$,

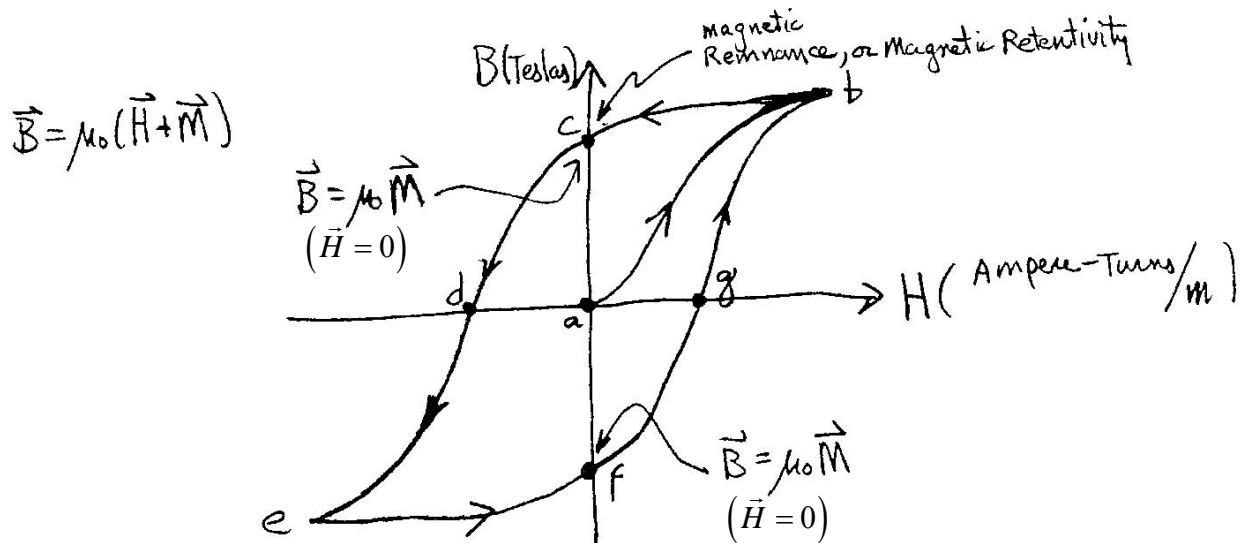
and thus $K_m(H)$ is also not a constant because:

$$\frac{dB(H)}{dH} = \mu(H) = K_m(H)\mu_0 \Rightarrow K_m(H) = \frac{1}{\mu_0} \frac{dB(H)}{dH}$$

$\frac{dB(H)}{dH}$ is the (local) slope of the B - H hysteresis curve at a given point on the B - H curve.



Magnetic Hysteresis of Annealed Iron (Analog of Electro-Hysteresis for Bar Electret):



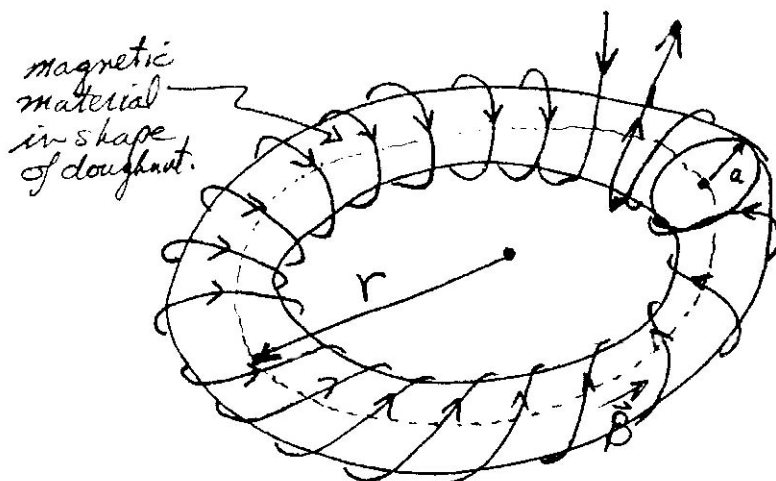
For a ferromagnetic material with a non-linear B - H hysteresis relation as shown in the above graph of B vs. H for the material, the present state of its magnetization (magnetic dipole moment per unit volume) \vec{M} depends on the past history of the material's magnetization.

The B - H curve for a ferromagnetic material can be mapped out directly by simultaneously measuring B and H over one complete hysteresis cycle, making a series of infinitesimal increments in dH (which by Ampere's law (in integral form) is proportional to the free current I_{free} flowing e.g. in a solenoid coil in which the sample of ferromagnetic material is placed), and measuring the resulting B -field of the ferromagnetic material at that value of the applied H -field.

One can also compute the resulting infinitesimal increment in the magnetic field dB for each infinitesimal increment in dH . Then at each such measurement, the differential magnetic permeability $K_m \equiv \mu/\mu_o = \frac{1}{\mu_o} \frac{dB}{dH}$ (= local slope of the B - H curve at a given point (H, B) on the B - H curve) can be calculated. Note that in order to know where one is at any point on the B - H curve for a ferromagnetic material that is being mapped out in this manner, (at a minimum, at least) the initial/starting values of B and H must be known: (H_{start}, B_{start}) . If the sample of material has never been magnetized before, then $(H_{start}, B_{start}) = (0, 0)$ - this is point a on the above graph. If the sample of ferromagnetic material has instead e.g. been previously fully magnetically-charged, then e.g. if $H_{start} = 0$, the sample of ferromagnetic material will either be at point c or point f on the above B - H curve. Thus, a measurement of B_{start} with $H_{start} = 0$ will unambiguously determine which one of these two points the sample of ferromagnetic material is presently at. Thus from the starting point (H_{start}, B_{start}) the B -field at any desired ending point (H_{end}, B_{end}) on the B vs. H curve then can be computed from:

$$B_{end} = B_{start} + \int_{start}^{end} \left(\frac{dB(H)}{dH} \right) dH = B_{start} + \int_{start}^{end} \mu(H) dH = B_{start} + \mu_o \int_{start}^{end} K_m(H) dH$$

The Rowland Ring (= Toroid with Core of Ferromagnetic Material):



Winding #1 (Primary) has N_1 turns, carrying current I_1

Winding #2 (secondary) not shown.

Ampere's Circuital Law for H : $\oint_C \vec{H}(\vec{r}) \cdot d\vec{\ell} = I_{free}^{encl}$

$$\text{Inside the ring: } H = \frac{N_1 I_1}{2\pi r} = \left(\frac{N_1}{2\pi r} \right) I_1$$

$$B = \Phi_m / A \text{ where } A = \text{cross-sectional area of core} = \pi a^2$$

$$\text{Magnetic flux through Rowland Ring } \Phi_m = BA$$

Energy Dissipated in a Hysteresis Cycle

The extra power provided by a source (i.e. a battery) in causing the magnetic material of the Rowland Ring's core to (slowly) go around the hysteresis loop (e.g. for one cycle) is:

$$\begin{aligned} \text{Power, } P &= \frac{dW}{dt} = I_1 \left(N_1 \frac{d\Phi_m}{dt} \right) = I_1 N_1 A \frac{dB}{dt} \text{ where } A = \pi a^2 = \text{cross-sectional area} \\ &= \frac{N_1 I_1 A (2\pi r)}{(2\pi r)} \frac{dB}{dt} \text{ (mean) circumference of Rowland Ring: } = 2\pi r \\ &= \frac{N_1 I_1 V_{RR}}{(2\pi r)} \frac{dB}{dt} \text{ the volume of the Rowland Ring: } V_{RR} = 2\pi r A = 2\pi r (\pi a^2) \\ &= HV \frac{dB}{dt} \text{ since: } H = \frac{N_1 I_1}{2\pi r} \end{aligned}$$

The instantaneous power dissipated is $P = \frac{dW}{dt} = HV_{RR} \frac{dB}{dt}$ and thus the infinitesimal

work/energy increment at a given point on the hysteresis loop is: $dW = HV_{RR} dB = (HdB)V_{RR}$ and therefore the work done (= energy dissipated in the ferromagnetic core of the Rowland Ring) in

one hysteresis cycle is $W = \oint_{\text{cycle}} dW = V_{RR} \oint_{\text{cycle}} HdB$

$$\text{Then: } W = V_{RR} \oint_{\text{cycle}} H dB = V_{RR} \oint_{\text{cycle}} \vec{H} \cdot d\vec{B}$$

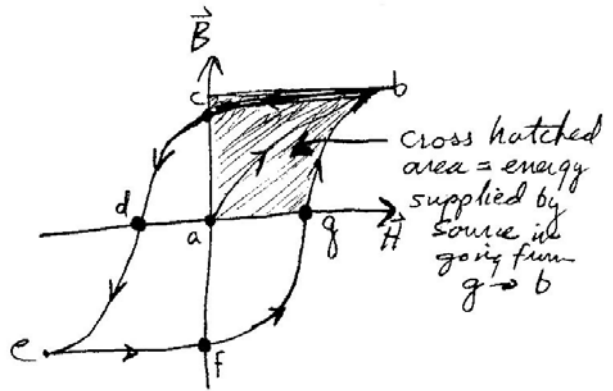
$$W = W_{b \rightarrow c} + W_{c \rightarrow d} + W_{d \rightarrow e} + W_{e \rightarrow f} + W_{f \rightarrow g} + W_{g \rightarrow b}$$

$$W = V_{RR} \left[\int_b^c \vec{H} \cdot d\vec{B} + \int_c^d \vec{H} \cdot d\vec{B} + \int_d^e \vec{H} \cdot d\vec{B} \right. \\ \left. + \int_e^f \vec{H} \cdot d\vec{B} + \int_f^g \vec{H} \cdot d\vec{B} + \int_g^b \vec{H} \cdot d\vec{B} \right]$$

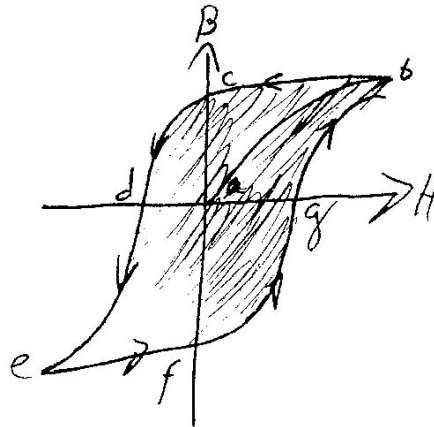
$$W = V_{RR} \times (\text{Area enclosed by the hysteresis loop in the } B-H \text{ plane})$$

$$W = \text{energy dissipated / hysteresis cycle}$$

Going from point g to point b in the B-H plane:



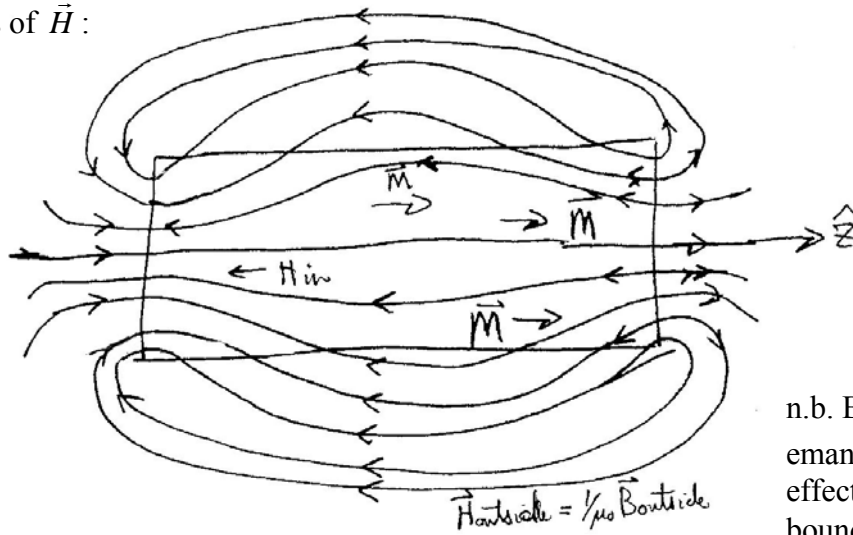
Going around entire hysteresis loop for 1 cycle:



Please see/read the UIUC Physics 401 Lab Handout on the Rowland Ring for more information
 It is available at the following URL: <http://online.physics.uiuc.edu/courses/phys401/>

\vec{B} and \vec{H} Fields of a Bar Magnet (Permanent Magnet) with Uniform Magnetization \vec{M}

Lines of \vec{H} :



$$\vec{B} = \mu_0 \vec{H} + \mu_0 \vec{M}$$

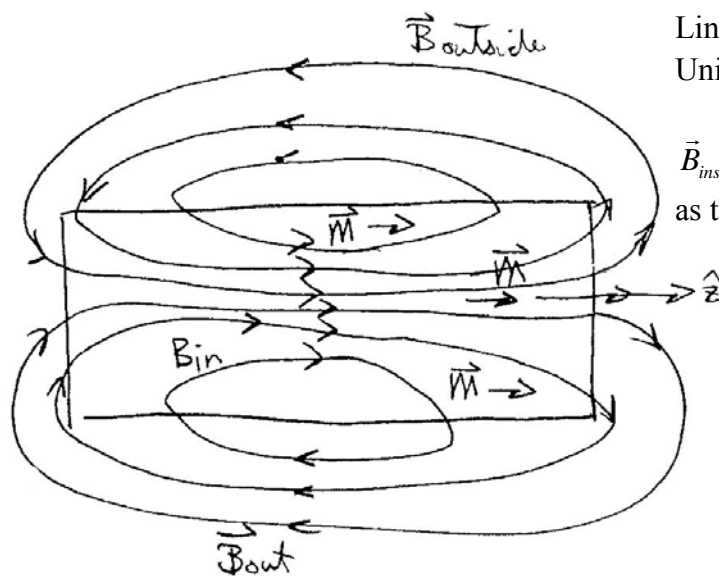
$$\vec{M} = M_o \hat{z}$$

\vec{H}_{inside} is in opposite direction to \vec{M} !!!

n.b. Both \vec{M} and \vec{H}_{inside} emanates from/terminate on effective surface magnetic bound charge σ_m on the ends the bar magnet!

$$H_{outside} = \frac{1}{\mu_0} B_{outside}$$

Lines of \vec{B} :



Lines of \vec{M} are constant:
Uniform $\vec{M} = M_o \hat{z}$ inside

\vec{B}_{inside} is in the same direction as the magnetization \vec{M}

Compare these pictures for bar magnet to that for bar electret (P435 Lecture Notes 10, page 33)

Outside the magnet: $\vec{M} = 0$

Inside the magnet:
$$\vec{H}_{inside} = \frac{1}{\mu_0} \vec{B}_{inside} - \vec{M}$$

$$\therefore \vec{B}_{outside} = \mu_0 \vec{H}_{outside}$$

Near the center of bar magnet, $\vec{H}_{inside}^{center} \approx 0$

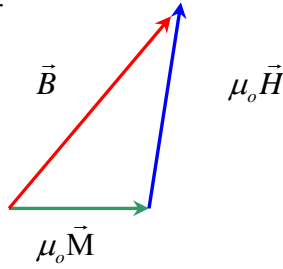
$\vec{B}_{outside}$ is in same direction as $\vec{H}_{outside}$

$$\therefore \vec{B}_{inside}^{center} \approx \mu_0 \vec{M}$$

Note: $\vec{B} = \mu \vec{H}$ where $\mu = \text{constant}$ is valid only in “soft” magnet materials that are linear and isotropic (i.e. Class “A”)

Vector relationship for \vec{B} , \vec{H} and \vec{M} :

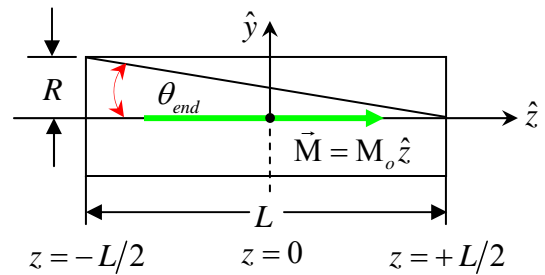
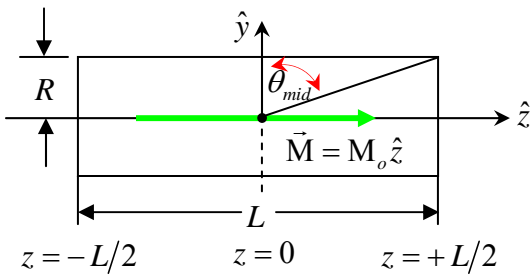
$$\vec{B} = \mu_0 \vec{H} + \mu_0 \vec{M}$$



Inside a bar magnet, \vec{B}_{inside} and \vec{H}_{inside} point in \approx opposite directions.

Magnetic field of a cylindrical bar magnet with $\vec{M} = M_o \hat{z}$ is analogous to that for short solenoid!

Arbitrary point on the z-axis: $B_z^{solenoid}(z_o) = \left(\frac{\mu_o}{2}\right) nI (\sin \theta'_2 - \sin \theta'_1)$ Just replace: $nI \rightarrow M$!!!



On the symmetry axis:

At the center of the cylindrical bar magnet:

$$\vec{B}_{short\ solenoid}(z=0) = \mu_o nI \sin \theta'_m \hat{z}$$

$$\vec{B}_{CBM}(z=0) = \mu_o \vec{M} \sin \theta_{mid}$$

$$\vec{H}_{CBM}(z=0) = -\vec{M}(1 - \sin \theta_{mid})$$

At one end of the cylindrical bar magnet:

$$\vec{B}_{short\ solenoid}\left(z = +\frac{L}{2}\right) = \left(\frac{\mu_o}{2}\right) nI \sin \theta_{end} \hat{z}$$

$$\vec{B}_{CBM}\left(z = +\frac{L}{2}\right) = \mu_o \vec{M} \frac{\sin \theta_{end}}{2}$$

$$\vec{H}_{CBM}\left(z = +\frac{L}{2}\right) = -\vec{M}\left(1 - \frac{\sin \theta_{end}}{2}\right)$$

$$\vec{B}(\vec{r}) = \mu_o (\vec{H}(\vec{r}) + \vec{M}(\vec{r}))$$

$$\vec{\nabla} \times \vec{B}(\vec{r}) = \mu_o \left(\underbrace{\vec{\nabla} \times \vec{H}(\vec{r})}_{=0} + \underbrace{\vec{\nabla} \times \vec{M}(\vec{r})}_{=0} \right)$$

Since $J_f = 0$ (Ampere's Law)

Because $\vec{M} = M_o \hat{z}$ is uniform

\therefore Lines of \vec{H} are not refracted (i.e. bent) at the cylindrical surface of magnet.

Example(s) of Calculating \vec{B} , \vec{M} and \vec{H} Inside & Outside Magnetized Materials

Consider a long cylinder of length L and radius R such that $L \gg R$ (analogous to long solenoid) made of magnetizable material (not yet specified if diamagnetic, paramagnetic or ferromagnetic). However, we will assume that the type of material (and/or its magnetic history, in the case of ferromagnetic material) is known; thus the magnetic permeability μ of the material is known, or equivalently the magnetic susceptibility χ_m of the material is known.

$$\mu \equiv \mu_o (1 + \chi_m) \qquad K_m \equiv \frac{\mu}{\mu_o} = (1 + \chi_m)$$

The following table lists the magnetic susceptibilities of various types of linear diamagnetic and linear paramagnetic materials (most at \approx room temperature, $T = 20^\circ \text{C}$):

Material	Susceptibility	Material	Susceptibility
<i>Diamagnetic:</i>		<i>Paramagnetic:</i>	
Bismuth	-1.6×10^{-4}	Oxygen	1.9×10^{-6}
Gold	-3.4×10^{-5}	Sodium	8.5×10^{-6}
Silver	-2.4×10^{-5}	Aluminum	2.1×10^{-5}
Copper	-9.7×10^{-6}	Tungsten	7.8×10^{-5}
Water	-9.0×10^{-6}	Platinum	2.8×10^{-4}
Carbon Dioxide	-1.2×10^{-8}	Liquid Oxygen (-200°C)	3.9×10^{-3}
Hydrogen	-2.2×10^{-9}	Gadolinium	4.8×10^{-1}

Magnetic Susceptibilities (unless otherwise specified, values are for 1 atm, 20°C). Source: Handbook of Chemistry and Physics, 67th ed. (Boca Raton: CRC Press, Inc., 1986)

For these linear magnetic materials, the magnetization (magnetic dipole moment per unit volume) \vec{M} is related to the \vec{H} field via: $\vec{M} = \chi_m \vec{H}_{inside}$.

But we also have: $\vec{H}_{inside} = \frac{1}{\mu_o} \vec{B}_{inside} - \vec{M}$

then: $\vec{M} = \chi_m \vec{H}_{inside} = \chi_m \left(\frac{1}{\mu_o} \vec{B}_{inside} - \vec{M} \right) = \frac{\chi_m}{\mu_o} \vec{B}_{inside} - \chi_m \vec{M}$

or: $\vec{M} + \chi_m \vec{M} = \frac{\chi_m}{\mu_o} \vec{B}_{inside}$ or: $(1 + \chi_m) \vec{M} = \frac{\chi_m}{\mu_o} \vec{B}_{inside}$

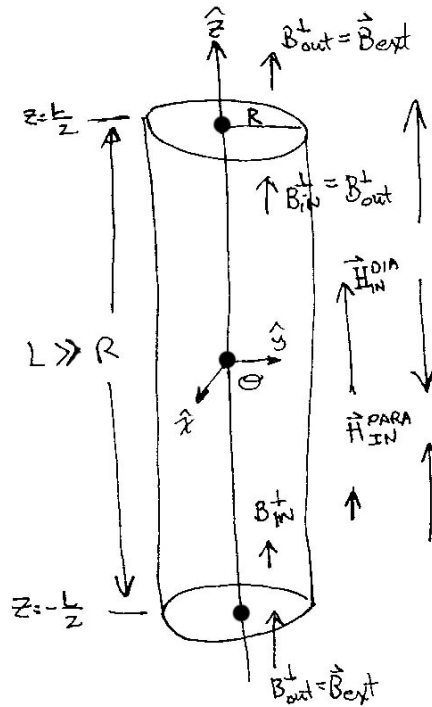
or: $\vec{M} = \frac{\chi_m}{\mu_o (1 + \chi_m)} \vec{B}_{inside} = \frac{\chi_m}{\mu} \vec{B}_{inside}$ where $\mu = \mu_o (1 + \chi_m)$

Suppose we place a sample of magnetic material in a uniform external applied magnetic field $\vec{B}_{ext} = B_o \hat{z} = 1 \text{ Tesla } \hat{z}$

Then if $L \gg R$,
the resulting magnetization is
(ideally) uniform:

$$\vec{M} \approx \pm M_o \hat{z}$$

(Simplifying assumption!)



$$\vec{B}_{ext} = B_o \hat{z} = 1 \text{ Tesla } \hat{z}$$

For diamagnetic materials:

$$\vec{M}_{dia} = - \frac{|\chi_m^{dia}|}{\mu_{dia}} \vec{B}_{inside}$$

$$\chi_m^{dia} < 0$$

For paramagnetic materials:

$$\vec{M}_{para} = + \frac{|\chi_m^{para}|}{\mu_{para}} \vec{B}_{inside}$$

$$\chi_m^{para} > 0$$

Use boundary condition on interface:

$$B_2^\perp = B_1^\perp \Rightarrow B_{in}^\perp = B_{out}^\perp = \vec{B}_{ext} = B_o \hat{z}$$

1) If the magnetic material is diamagnetic ($\chi_m^{dia} < 0$) and $|\chi_m^{dia}| \ll 1$ then:

$$\vec{M}_{dia} = - \frac{|\chi_m^{dia}|}{\mu_{dia}} \vec{B}_{inside}$$

But since $\chi_m^{dia} < 0$ and $|\chi_m^{dia}| \ll 1$ then:
$$\vec{M}_{dia} \approx - \frac{|\chi_m^{dia}|}{\mu_o} \vec{B}_{ext}$$

\vec{M}_{dia} is antiparallel to \vec{B}_{ext} , i.e. $\vec{M}_{dia} = -M_o \hat{z}$ for $\vec{B}_{ext} = B_o \hat{z}$, then $|M_o^{dia}| = (|\chi_m^{dia}| / \mu^{dia}) B_o$

Inside a diamagnetic material $\vec{H}_{inside}^{dia} \parallel \vec{B}_{ext}$

$$\vec{H}_{inside}^{dia} \approx \frac{1}{\mu_o} \vec{B}_{ext} - \vec{M}_{dia} = \frac{1}{\mu_o} \vec{B}_{ext} + \frac{|\chi_m^{dia}|}{\mu_o} \vec{B}_{ext} = \frac{1 + |\chi_m^{dia}|}{\mu_o} \vec{B}_{ext}$$

2) If the magnetic material is paramagnetic ($\chi_m^{para} > 0$) and $|\chi_m^{para}| \ll 1$ then:

$$\vec{M}_{para} = \frac{|\chi_m^{para}|}{\mu_{para}} \vec{B}_{inside}$$

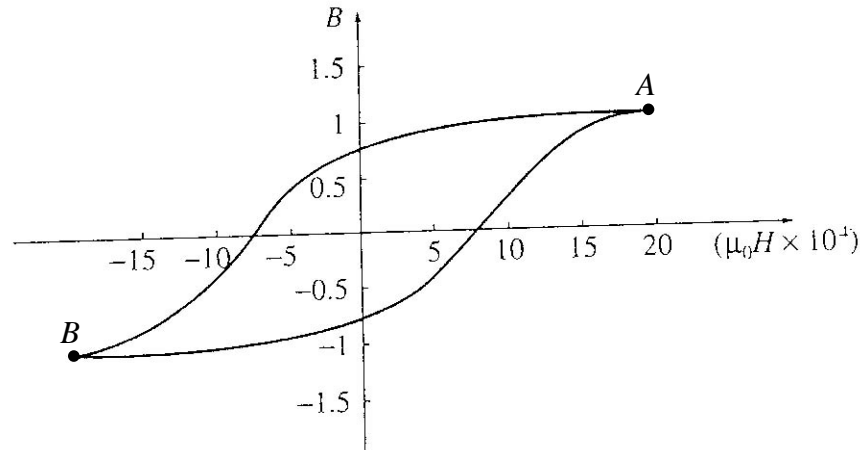
But since $\chi_m^{para} > 0$ and $|\chi_m^{para}| \ll 1$ then:
$$\vec{M}_{para} \approx + \frac{|\chi_m^{para}|}{\mu_o} \vec{B}_{ext}$$

\vec{M}_{para} is parallel to \vec{B}_{ext} , i.e. $\vec{M}_{para} = +M_o \hat{z}$ for $\vec{B}_{ext} = B_o \hat{z}$, then $|M_o^{para}| = (|\chi_m^{para}| / \mu^{para}) B_o$

Inside a paramagnetic material $\vec{H}_{inside}^{para} \parallel \vec{B}_{ext}$

$$\vec{H}_{inside}^{para} \approx \frac{1}{\mu_o} \vec{B}_{ext} - \vec{M}_{para} = \frac{1}{\mu_o} \vec{B}_{ext} - \frac{|\chi_m^{para}|}{\mu_o} \vec{B}_{ext} = \frac{1 - |\chi_m^{para}|}{\mu_o} \vec{B}_{ext}$$

If the magnetic material is ferromagnetic then \exists a non-linear relation between the magnetization \vec{M} and \vec{H}_{inside} , and also between \vec{B}_{inside} and \vec{H}_{inside}
 \rightarrow need to know \vec{B}_{inside} vs. $\mu_0 \vec{H}_{inside}$ (or \vec{M} vs. \vec{H}_{inside}) hysteresis curve, e.g. for iron:



For $\vec{B}_{ext} = B_o \hat{z} = 1 \text{ Tesla } \hat{z}$ (point A or B in figure above), this hysteresis curve says two things:

- 1) $\vec{H}_{inside} \parallel \vec{B}_{ext}$ and
- 2) $\mu_o \vec{H}_{inside}^{ferro} \approx 10 \times 10^{-4} = 10^{-3} \text{ Tesla } \hat{z}$ ($\mu_o \vec{H}$ has same units (Tesla) as \vec{B})

But: $\mu_o = 4\pi \times 10^{-7} \text{ Newtons/Ampere}^2$ $1 \text{ Tesla} = 1 \frac{\text{Newton}}{\text{Amp-meter}}$

$$\rightarrow \vec{H}_{inside}^{ferro} \approx \frac{1}{\mu_o} 10^{-3} T = \frac{1}{4\pi \times 10^{-7} \text{ N/A}^2} 10^{-3} \hat{z} \frac{\text{N}}{\text{A-m}} = \frac{1}{4\pi} 10^4 \hat{z} \text{ Amps/meter}$$

(Actually, SI Units of \vec{H} are Ampere-turns/meter – e.g. for long solenoid $H = nI = NI/L$)

$\vec{H}_{inside}^{ferro} \approx 795.8 \text{ Amps/meter} \approx 800 \text{ Amps/meter } \hat{z}$	very small!
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Then: $\vec{M}^{ferro} = \chi_m^{ferro} \vec{H}_{inside}^{ferro} = \frac{1}{\mu_o} \vec{B}_{ext} - \vec{H}_{inside}^{ferro}$

$$\vec{M}^{ferro} \approx \frac{1}{4\pi \times 10^{-7} \left(\frac{\text{N}}{\text{A}^2} \right)} 1 \left(\frac{\text{N}}{\text{A-m}} \right) \hat{z} - 800 \left(\frac{\text{A}}{\text{m}} \right) \hat{z} \approx \frac{1}{4\pi} \times 10^1 \hat{z} \left(\frac{\text{A}}{\text{m}} \right) - 800 \left(\frac{\text{A}}{\text{m}} \right) \hat{z}$$

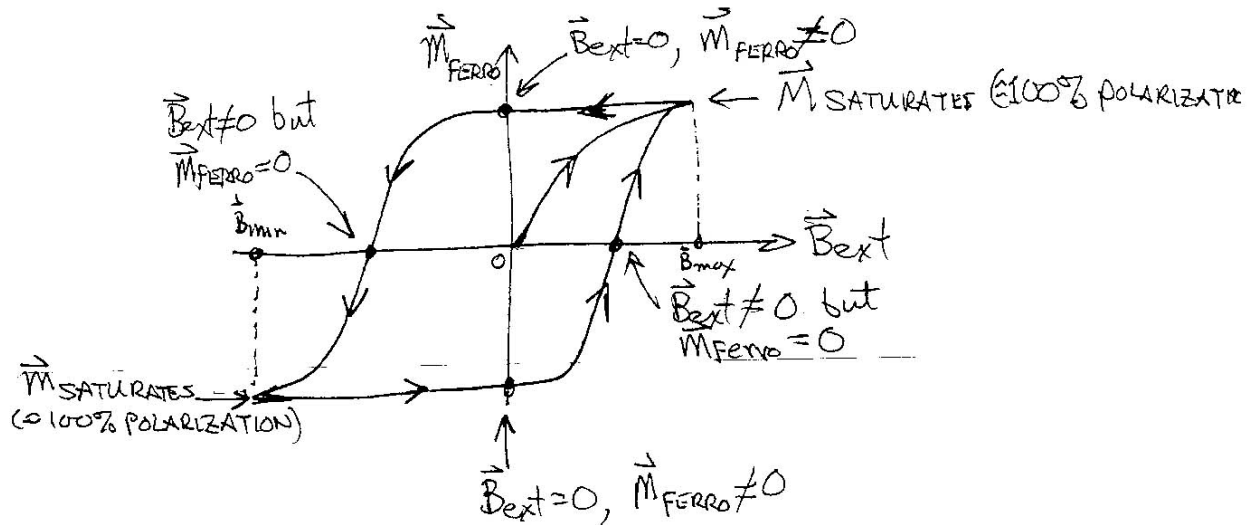
$$\approx 800,000 - 800 \left(\frac{\text{A}}{\text{m}} \right) \hat{z}$$

$$\chi_m^{ferro} = \frac{|\vec{M}^{ferro}|}{|\vec{H}_{inside}^{ferro}|} \approx 1000!!!$$

$\vec{M}^{ferro} \approx 8 \times 10^5 \hat{z} \left(\frac{\text{A}}{\text{m}} \right)$	$\vec{H}_{inside}^{ferro} \parallel \vec{B}_{ext}$	$\vec{M}^{ferro} \parallel \vec{B}_{ext}$	$\vec{M}^{ferro} \parallel \vec{H}_{inside}^{ferro}$
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After the magnetizing field \vec{B}_{ext} is turned off / removed, then if

$\vec{M}_{ferro} (\vec{B}_{ext} = \text{off}) \approx \vec{M}_{ferro} (\vec{B}_{ext} = \text{on})$ (i.e. the magnetization changes very little when the ferromagnetic material is fully-charged):

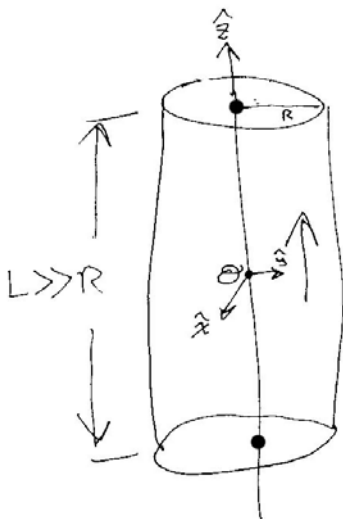


Then: $\vec{B}^{inside} = \left(\frac{\mu_{ferro}}{\chi_m^{ferro}} \right) \vec{M}_{ferro}$ where $\mu_{ferro} = \mu_o (1 + \chi_m^{ferro})$ and $\chi_m^{ferro} \approx 1000 \gg 1$

$$\vec{B}^{inside} = \frac{\mu_o (1 + \chi_m^{ferro})}{\chi_m^{ferro}} \vec{M}_{ferro} \approx \mu_o \vec{M}_{ferro} \text{ but } \vec{M}_{ferro} \approx 8 \times 10^5 \hat{z} \left(\frac{A}{m} \right)$$

Thus: $\vec{B}^{inside} \approx 4\pi \times 10^{-7} \left(\frac{N}{A^2} \right) \cdot 8 \times 10^5 \left(\frac{A}{m} \right) \hat{z} \approx 1 \left(\frac{N}{A-m} \right) \hat{z} = 1 \text{ Tesla } \hat{z}$

Since $B_{inside}^\perp = B_{outside}^\perp$ at the interface/boundary of a ferromagnetic material, a measurement of the normal component of the magnetic field at the center of one of the end surfaces of the magnetic material (e.g. using a {transverse} Hall Probe) will give $B_{outside}^{surface} = B_{outside}^\perp = B_{inside}^\perp \approx 1 \text{ Tesla } \hat{z}$ for a fully-charged ferromagnetic material.



$$\vec{M}_{ferro} \approx 9 \times 10^5 \hat{z} \left(\frac{A}{m} \right)$$

$$\Rightarrow \vec{B}_{inside} = \vec{B}_{outside} \left(z = \pm \frac{L}{2} \right) \approx 1 \text{ Tesla } \hat{z}$$

(for $L \gg R$, "ideal" magnet assumed)

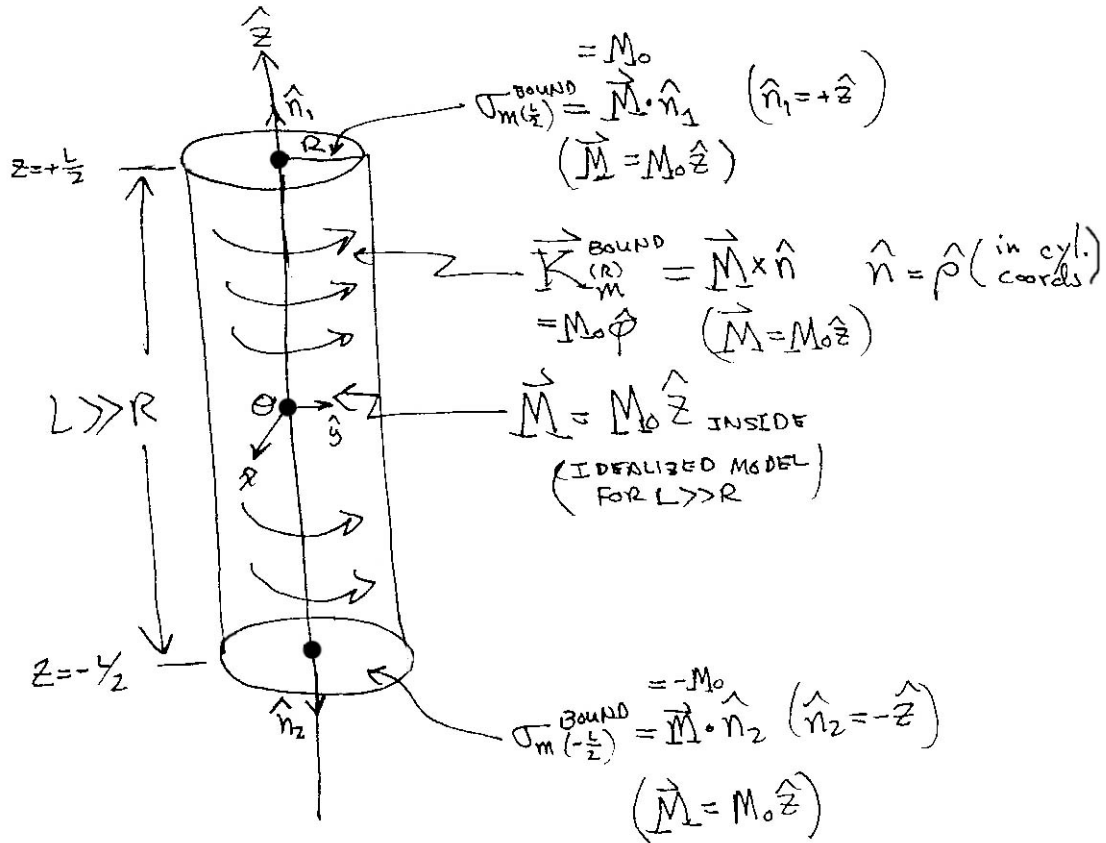
Then the H -field inside the magnetic material is:

$$\vec{H}_{inside} = \frac{1}{\mu_o} \vec{B}_{inside} - \vec{M}_{ferro} = \frac{\mu_o}{\mu_o} \left(\frac{1 + \chi_m^{ferro}}{\chi_m^{ferro}} \right) \vec{M}_{ferro} - \vec{M}_{ferro}$$

$$\vec{H}_{inside} = \frac{1}{\chi_m^{ferro}} \vec{M}_{ferro} \approx \frac{1}{1000} 8 \times 10^5 \hat{z} \left(\frac{A}{m} \right) \approx 800 \left(\frac{A}{m} \right) \hat{z}$$

Once the magnetization, \vec{M} of the ferromagnetic material has been determined, then e.g. the equivalent bound current densities: $\vec{K}_m^{bound} = \vec{M} \times \hat{n}|_{surface}$ ($= M_o \hat{z} \times \hat{n}$ here) and $\vec{J}_m^{bound} = \vec{\nabla} \times \vec{M}$ ($= 0$ here in our idealized $\vec{M} = M_o \hat{z}$ model) can be determined.

Alternatively, the equivalent pole densities of magnetic strength can be determined from $\sigma_m^{bound}(\vec{r}) = \vec{M}(\vec{r}) \cdot \hat{n}|_{surface}$ ($= M_o \hat{z} \cdot \hat{n}$ here) and $\rho_m^{bound}(\vec{r}) = -\vec{\nabla} \cdot \vec{M}(\vec{r})$ ($= 0$ here in our idealized $\vec{M} = M_o \hat{z}$ model).



We can then determine the magnetic field $\vec{B}(\vec{r})$, valid for any observation/field point $P(\vec{r})$ via two equivalent methods:

Method #1: Equivalent surface and volume current densities $\vec{K}_m^{bound} = \vec{M} \times \hat{n}|_{surface}$, $\vec{J}_m^{bound} = \vec{\nabla} \times \vec{M}$

First, determine the magnetic vector potential $\vec{A}(\vec{r})$ and then the magnetic field $\vec{B}(\vec{r}) = \vec{\nabla} \times \vec{A}(\vec{r})$:

$$\vec{A}_K(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{S'} \frac{\vec{K}_m^{bound}(\vec{r}')}{r} da'$$

$$\vec{B}_K(\vec{r}) = \vec{\nabla} \times \vec{A}_K(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{S'} \frac{\vec{K}_m^{bound}(\vec{r}') \times \hat{r}}{r^2} da'$$

$$\vec{A}_J(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{V'} \frac{\vec{J}_m^{bound}(\vec{r}')}{r} d\tau'$$

$$\vec{B}_J(\vec{r}) = \vec{\nabla} \times \vec{A}_J(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{V'} \frac{\vec{J}_m^{bound}(\vec{r}') \times \hat{r}}{r^2} d\tau'$$

$$\vec{A}_{Tot}(\vec{r}) = \vec{A}_K(\vec{r}) + \vec{A}_J(\vec{r})$$

$$\vec{B}_{Tot}(\vec{r}) = \vec{B}_K(\vec{r}) + \vec{B}_J(\vec{r})$$

Method #2: Equivalent pole densities of magnetic strength $\sigma_m^{Bound} \equiv \vec{M} \cdot \hat{n} |_{surface}$, $\rho_m^{Bound} \equiv -\vec{\nabla} \cdot \vec{M}$

First, determine the magnetic scalar potential $V_m(\vec{r})$ and then the magnetic field $\vec{B}(\vec{r})$ using the relations $\vec{B}_{inside}(\vec{r}) = \mu_o \vec{M}(\vec{r}) - \vec{\nabla} V_m(\vec{r})$ and $\vec{B}_{outside}(\vec{r}) = -\vec{\nabla} V_m(\vec{r})$:

$$V_m^{\sigma_m^{Bound}}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{S'} \frac{\sigma_m^{Bound}(\vec{r}')}{r} da'$$

$$V_m^{\rho_m^{Bound}}(\vec{r}) = \left(\frac{\mu_o}{4\pi} \right) \int_{V'} \frac{\rho_m^{Bound}(\vec{r}')}{r} d\tau'$$

$$V_m^{Tot}(\vec{r}) = V_m^{\sigma_m^{Bound}}(\vec{r}) + V_m^{\rho_m^{Bound}}(\vec{r})$$

$$\vec{B}(\vec{r}) \equiv \mu_o \vec{M}(\vec{r}) - \vec{\nabla} V_m(\vec{r})$$

$$\vec{B}(\vec{r}) = \mu_o \vec{M}(\vec{r}) + \left(\frac{\mu_o}{4\pi} \right) \int_{S'} \frac{\sigma_m^{Bound}(\vec{r}') \hat{r}}{r^2} da' + \left(\frac{\mu_o}{4\pi} \right) \int_{V'} \frac{\rho_m^{Bound}(\vec{r}') \hat{r}}{r^2} d\tau'$$

Once $\vec{B}_{inside}(\vec{r})$ and $\vec{B}_{outside}(\vec{r})$ have been determined (using either method) then $\vec{H}_{inside}(\vec{r})$ and $\vec{H}_{outside}(\vec{r})$ can be obtained from:

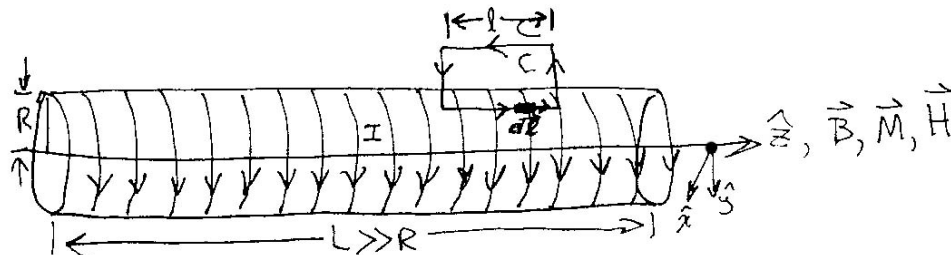
$$\vec{H}_{inside}(\vec{r}) = \frac{1}{\mu_o} \vec{B}_{inside}(\vec{r}) - \vec{M}(\vec{r})$$

$$\text{and } \vec{H}_{outside}(\vec{r}) = \frac{1}{\mu_o} \vec{B}_{outside}(\vec{r}) \quad (\text{outside, } \vec{M}(\vec{r}) \equiv 0)$$

Comparison of Magnetic Field Strengths $|\vec{B}|$ for a Long Solenoid With and Without a Magnetic Core

$$n \equiv \frac{\# \text{ turns}}{\text{meter}} \equiv \frac{N}{L}$$

$N = \text{total \# turns}$



Consider a long “ideal” solenoid of radius R and length $L \gg R$ has n turns/meter, carrying a steady current $\vec{I} = I \hat{\phi}$ (i.e. ideal solenoid – for simplicity’s sake neglect pitch angle here).

If solenoid has “soft” annealed iron magnetic core of magnetic permeability

$$\mu = \mu_o (1 + \chi_m) \approx 1001 \mu_o \text{ i.e. a magnetic susceptibility } \chi_m = 1000, \text{ then } \vec{H}_{inside} = \frac{1}{\mu_o} \vec{B}_{inside} - \vec{M} \text{ or}$$

$$\vec{H}_{inside} = \frac{1}{\mu} \vec{B}_{inside} \text{ with } \vec{M} = \chi_m \vec{H}_{inside}.$$

Ampere's Circuital Law for \vec{H} (integral form) $\oint_C \vec{H}(\vec{r}) \cdot d\vec{\ell} = I_{free}^{enclosed}$ with contour of integration, C indicated in the picture above.

$$\oint_C \vec{H}(\vec{r}) \cdot d\vec{\ell} = I_{free}^{enclosed} \Rightarrow H_{inside} \parallel \hat{z} \text{ by axial rotational invariance/axial symmetry of solenoid.}$$

Shrink contour C to ε above/below windings, then get: $H_{inside} \ell = n\ell I \Rightarrow \vec{H}_{inside}(\vec{r}) = nI\hat{z}$.

Then: $\vec{B}_{inside}(\vec{r}) = \mu \vec{H}_{inside}(\vec{r}) = \mu nI\hat{z}$ and $\vec{M}(\vec{r}) = \chi_m \vec{H}_{inside}(\vec{r}) = 1000nI\hat{z}$

Note that $\vec{B}_{inside}(\vec{r}) \parallel \vec{H}_{inside}(\vec{r}) \parallel \vec{M}(\vec{r}) \parallel \hat{z}$ for long "ideal" solenoid with "soft" annealed iron core.

Now compare these results to that for a long ideal solenoid without a magnetic core (for the same steady current I):

$$\vec{H}_{inside}^{no\ core}(\vec{r}) = \vec{H}_{inside}^{w/core}(\vec{r}) = nI\hat{z}$$

$$\vec{B}_{inside}^{no\ core}(\vec{r}) = \mu_o \vec{H}_{inside}^{no\ core}(\vec{r}) = \mu_o nI\hat{z}$$

Thus: $\frac{|\vec{B}_{inside}^{w/core}(\vec{r})|}{|\vec{B}_{inside}^{no\ core}(\vec{r})|} = \frac{\mu |\vec{H}_{inside}^{w/core}(\vec{r})|}{\mu_o |\vec{H}_{inside}^{no\ core}(\vec{r})|} = \frac{\mu}{\mu_o} = 1001$

Another way to look at / view this: If one wants $|\vec{B}_{inside}^{w/core}| = |\vec{B}_{inside}^{no\ core}|$, then one can reduce the current in the solenoid that has e.g. a "soft" annealed iron magnetic core by a factor of $\mu_o/\mu \approx 1/1001$ for same \vec{B} -field!!!