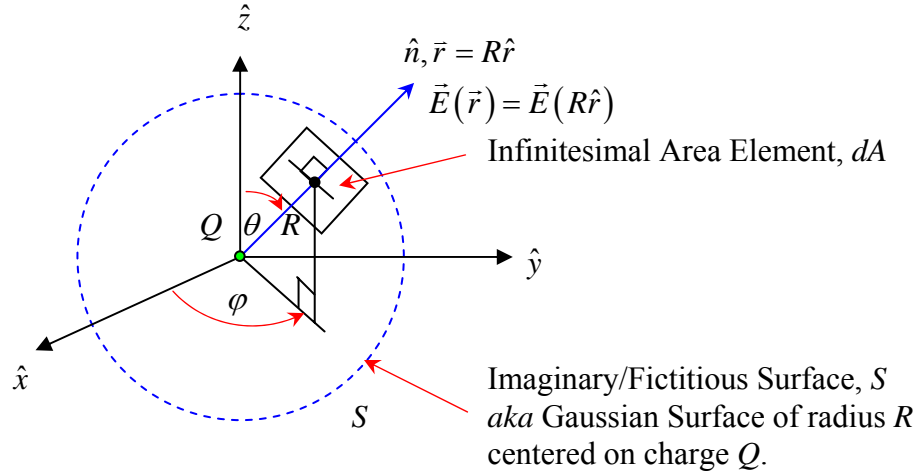


## LECTURE NOTES 2

### Gauss' Law / Divergence Theorem

Consider an imaginary / fictitious surface enclosing / surrounding e.g. a point charge (or a small charged conducting object). For simplicity, use an imaginary sphere of radius  $R$  centered on charge  $Q$  at origin:



Area element  $dA$  is a VECTOR quantity:  $d\vec{A} = dA\hat{n} = dA\hat{r}$ . By convention,  $\hat{n}$  is outward-pointing unit normal vector at area element  $dA$ . In this particular case (because of spherical symmetry of problem):  $\hat{n} = \hat{r}$

FLUX OF ELECTRIC FIELD LINES (through surface  $S$ ):  $\Phi_E \equiv \int_S \vec{E}(\vec{r}) \cdot d\vec{A}$

$\Phi_E$  = “measure” of “number of  $E$ -field “lines” passing through surface  $S$ , (SI Units: Volt-meters).

TOTAL ELECTRIC FLUX ( $\Phi_E^{TOT}$ ) associated with any closed surface  $S$ , is a measure of the (total) charge enclosed by surface  $S$ .

n.b. charge outside of surface  $S$  will contribute nothing to total electric flux  $\Phi_E$  (since  $E$ -field lines pass through one portion of the surface  $S$  and out another – no net flux!)

Consider our point charge  $Q$  at origin. Calculate the flux of  $\vec{E}$  passing through a sphere of radius  $r$ : (see above picture)

$$\Phi_E = \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = r \frac{Q}{4\pi\epsilon_0} \int_S \left( \frac{1}{r^2} \hat{r} \right) \cdot \underbrace{\left( r^2 \sin\theta d\theta d\phi \right)}_{\substack{=d\vec{A} \\ \text{infinitesimal vector} \\ \text{area element for} \\ \text{sphere of radius } r}}$$

n.b. Vector area element of sphere of radius,  $r$  is  $d\vec{A} = dA\hat{r} = (r^2 \sin\theta d\theta d\phi)\hat{r}$  in spherical-polar coordinates.

$$\begin{aligned} \text{Thus: } \Phi_E &= \frac{Q}{4\pi\epsilon_0} \int_{\theta=0}^{\theta=\pi} \int_{\phi=0}^{\phi=2\pi} \sin\theta d\theta d\phi \underbrace{(\hat{r}\cdot\hat{r})}_{=1} = \frac{\cancel{2\pi}Q}{\underbrace{4\pi}_2 \epsilon_0} \int_{\theta=0}^{\theta=\pi} \sin\theta d\theta \\ &= \frac{\cancel{2}Q}{\cancel{2}\epsilon_0} = \frac{Q}{\epsilon_0} \end{aligned}$$

$$\therefore \text{ Gauss' Law (in Integral Form): } \boxed{\Phi_E = \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \frac{Q_{\text{enclosed}}}{\epsilon_0}}$$

Electric flux through closed surface  $S = (\text{electric charge enclosed by surface } S) / \epsilon_0$

---

If  $\exists$  (= there exists) lots of discrete charges  $q_i$  (ALL enclosed by imaginary / fictitious / Gaussian surface  $S$ ), we know from principle of superposition that:

$$\vec{E}_{NET}(\vec{r}) = \sum_{i=1}^N \vec{E}_i(\vec{r})$$

$$\text{Then: } \Phi_E^{NET} = \oint_S \vec{E}_{NET}(\vec{r}) \cdot d\vec{A} = \sum_{i=1}^N \left( \oint_S \vec{E}_i(\vec{r}) \cdot d\vec{A} \right) = \sum_{i=1}^N \frac{q_i}{\epsilon_0} = \frac{1}{\epsilon_0} \sum_{i=1}^N q_i = \frac{Q_{\text{encl}}}{\epsilon_0}$$

If  $\exists$  volume charge density  $\rho(\vec{r}')$ , then:  $Q_{\text{encl}} = \int_V \rho(\vec{r}') d\tau'$

Then using the DIVERGENCE THEOREM:

$$\Phi_E = \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \int_V \overbrace{(\vec{\nabla} \cdot \vec{E}(\vec{r}))} d\tau' = \frac{Q_{\text{encl}}}{\epsilon_0} = \frac{1}{\epsilon_0} \int_V \overbrace{\rho(\vec{r})} d\tau'$$

This relation holds for any volume  $v \Rightarrow$  the integrands of  $\int_V ( ) d\tau'$  must be equal, i.e.:

$$\therefore \text{ Gauss' Law (in Differential Form): } \boxed{\vec{\nabla} \cdot \vec{E}(\vec{r}) = \rho(\vec{r}) / \epsilon_0}$$

The DIVERGENCE OF  $\vec{E}(\vec{r})$ :  $\vec{\nabla} \cdot \vec{E}(\vec{r})$ 

Calculate  $\vec{\nabla} \cdot \vec{E}(\vec{r})$  directly from  $\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_{\substack{v \\ \text{all} \\ \text{space}}} \frac{\hat{r}}{r^2} \rho(\vec{r}') d\tau'$

n.b. now extended over all space!

Remember that  $\vec{r}$  is NOT a constant!

$$\vec{r} \equiv \vec{r} - \vec{r}'$$

↑ field point  $P$   
↑ source point  $S$

$$\vec{\nabla} \cdot \vec{E}(\vec{r}) = \vec{\nabla} \cdot \left[ \frac{1}{4\pi\epsilon_0} \int_{\substack{v \\ \text{all} \\ \text{space}}} \left( \frac{\hat{r}}{r^2} \right) \rho(\vec{r}') d\tau' \right] = \frac{1}{4\pi\epsilon_0} \int_{\substack{v \\ \text{all} \\ \text{space}}} \vec{\nabla} \cdot \left( \frac{\hat{r}}{r^2} \right) \rho(\vec{r}') d\tau'$$

Now:  $\vec{\nabla} \cdot \left( \frac{\hat{r}}{r^2} \right) = 4\pi \underbrace{\delta^3(\vec{r})}_{\substack{3-D \\ \text{Dirac} \\ \delta\text{-fcn.}}}$  (see equation 1.100, Griffiths p. 50)

Thus:  $\vec{\nabla} \cdot \left( \frac{\hat{r}}{r^2} \right) = 4\pi\delta^3(\vec{r})$  or:  $\vec{\nabla} \cdot \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) = 4\pi\delta^3(\vec{r} - \vec{r}')$

$$\therefore \vec{\nabla} \cdot \vec{E}(\vec{r}) = \frac{1}{\cancel{4\pi}\epsilon_0} \int_{\substack{v \\ \text{all} \\ \text{space}}} \cancel{4\pi}\delta^3(\vec{r} - \vec{r}') \rho(\vec{r}') d\tau' = \frac{\rho(\vec{r})}{\epsilon_0}$$

Gauss' Law in Differential Form:

$$\vec{\nabla} \cdot \vec{E}(\vec{r}) = \frac{\rho(\vec{r})}{\epsilon_0}$$

Gauss' Law in Integral Form:

$$\vec{\nabla} \cdot \vec{E}(\vec{r}) = \frac{\rho(\vec{r})}{\epsilon_0}, \text{ thus: } \int_v (\vec{\nabla} \cdot \vec{E}(\vec{r}')) d\tau' = \int_v \left( \frac{\rho(\vec{r}')}{\epsilon_0} \right) d\tau' = \frac{1}{\epsilon_0} \int_v \rho(\vec{r}') d\tau' = \frac{1}{\epsilon_0} Q_{encl}$$

Now apply/use the Divergence Theorem on the volume integral associated with  $\vec{\nabla} \cdot \vec{E}(\vec{r}')$ :

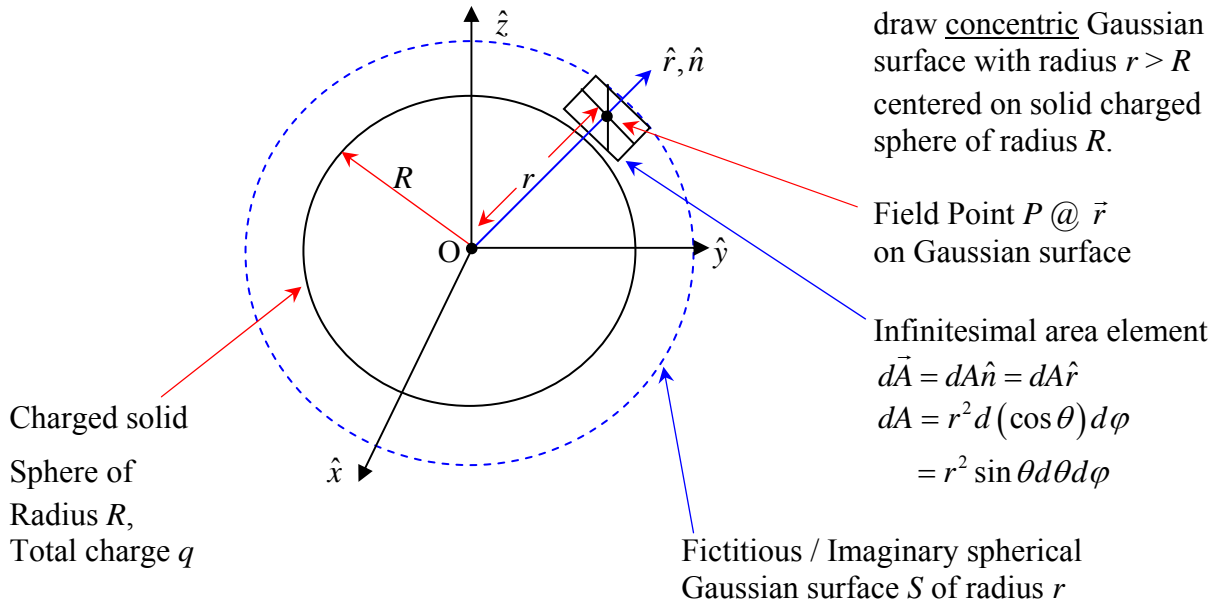
$$\int_v (\vec{\nabla} \cdot \vec{E}(\vec{r}')) d\tau' = \oint_S \vec{E}(\vec{r}') \cdot d\vec{A}' = \frac{1}{\epsilon_0} \int_v \rho(\vec{r}') d\tau' = \frac{1}{\epsilon_0} Q_{encl}$$

Thus we obtain:  $\oint_S \vec{E}(\vec{r}') \cdot d\vec{A}' = \frac{Q_{encl}}{\epsilon_0}$  Gauss' Law in Integral Form

APPLICATIONS OF GAUSS' LAW

- very explicit, detailed derivation -

Griffiths Example 2.2: Find / determine the electric field intensity  $\vec{E}(\vec{r})$  outside a uniformly charged solid sphere of radius  $R$  and total charge  $q$ :



**Gauss' Law:**  $\oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{encl} = \frac{1}{\epsilon_0} q = \frac{q}{\epsilon_0}$

$\vec{E}(\vec{r}) = E(\vec{r}) \hat{r}$

$d\vec{A} = dA \hat{n} = dA \hat{r}$   
(for Gaussian sphere)

n.b. by symmetry of sphere:  
 $\vec{E}_{sphere}(r > R) = E(r) \hat{r}$   
i.e.  $E$  must be radial!!

$\therefore \vec{E}(\vec{r}) \cdot d\vec{A} = (E(\vec{r}) \hat{r}) \cdot (dA \hat{r}) = E(\vec{r}) dA (\hat{r} \cdot \hat{r}) = E(\vec{r}) dA$   
=1

n.b. Here again, by symmetry,

NOTE:  $E(\vec{r}) = |\vec{E}(\vec{r})| \Leftarrow$  the magnitude of  $\vec{E}$  is constant  $\forall$  (for all)/for any fixed  $r$ !!!  
(on the Gaussian spherical surface).

$\therefore \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \oint_S E(\vec{r}) dA = \frac{q}{\epsilon_0}$   
 $= E(\vec{r}) \oint_S dA = E(\vec{r}) (4\pi r^2) = \frac{q}{\epsilon_0}$

$\therefore E(\vec{r}) = \frac{q}{4\pi\epsilon_0 r^2} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2}$  or:  $\vec{E}(\vec{r}) = \frac{q}{4\pi\epsilon_0 r^2} \hat{r} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$

= Electric field outside a charged sphere of radius  $R$  at radial distance  $r > R$  from center of sphere.

n.b. the electric field (for  $r > R$ ) for charged sphere is equivalent / identical to that of a point charge  $q$  located at the origin!!!

## GAUSS' LAW AND SYMMETRY

Use of (Geometrical / Reflection) symmetry (and any / all kinds of symmetry arguments in general) can be extremely powerful in terms of simplifying seemingly complicated problems!!

⇒ Learn skill of recognizing symmetries and applying symmetry arguments to solve problems!

### **Examples of use of Geometrical Symmetries and Gauss' Law**

- a) Charged sphere – use concentric Gaussian sphere and spherical coordinates
  - b) Charged cylinder – use coaxial Gaussian cylinder and cylindrical coordinates
  - c) Charged box / Charged plane – use appropriately co-located Gaussian “pillbox” (rectangular box) and rectangular coordinates
  - d) Charged ellipse – use concentric Gaussian ellipse and elliptical coordinates
  - e) Charged planar equilateral triangle
  - f) Charged pyramid
- }      Think about  
   these!!
- 

APPLICATIONS OF GAUSS' LAW (CONTINUED)      - very explicit detailed derivation

Griffiths Example 2.3 Consider a long cylinder (e.g. plastic rod) of length  $L$  and radius  $S$  that carries a volume charge density  $\rho$  that is proportional to the distance from the axis  $s$  of the cylinder / rod – i.e.

$$\rho(s) = ks \left( \frac{\text{coulombs}}{(\text{meter})^3} \right)$$

$$k = \text{proportionality constant} \left( \frac{\text{coulombs}}{(\text{meter})^4} \right)$$

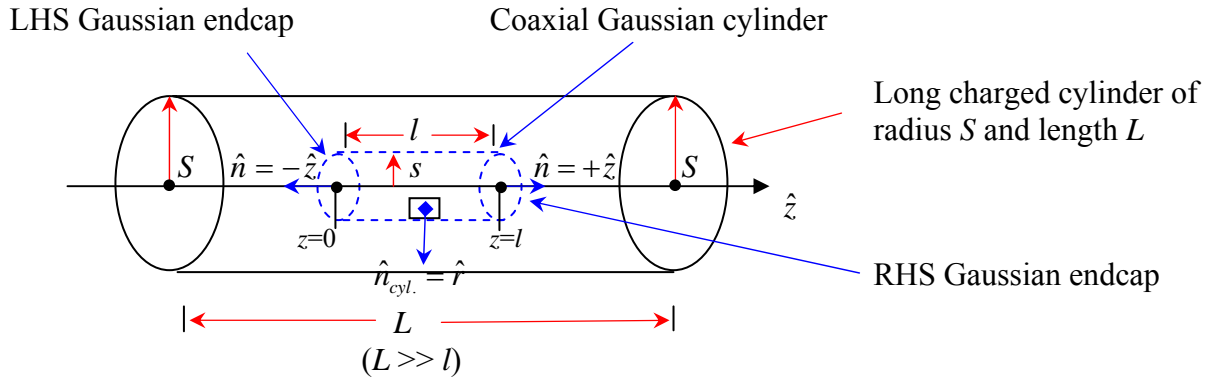
- a) Determine the electric field  $\vec{E}(\vec{r})$  inside this long cylinder / charged plastic rod  
 - Use a coaxial Gaussian cylinder of length  $l$  and radius  $s$ : (with  $l \ll L$ )

$$\text{Gauss' Law} \quad \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \frac{Q_{encl}}{\epsilon_0}$$

Enclosed charge:  $Q_{encl} = \int_V \rho(s') d\tau' = \int_V (ks')(s' ds' d\phi dz) \Leftarrow$  integral over Gaussian surface

$$Q_{encl} = \int_{s'=0}^{s'=s} \int_{\phi=0}^{\phi=2\pi} \int_{z=0}^{z=l} (ks')(s' ds' d\phi dz) = 2\pi kl \int_{s'=0}^{s'=s} s'^2 ds'$$

$$Q_{encl} = \frac{2}{3} \pi k l s^3$$



Cylindrical Symmetry  $\Rightarrow \vec{E}(\vec{r}) = E(\vec{r})\hat{r}$  (i.e.  $\vec{E}$  points radially outward,  $\perp$  to  $z$ -axis.)

$$\oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \int_{\text{cylindrical portion of Gaussian surface}} \vec{E}(\vec{r}) \cdot d\vec{A}_{\text{cyl.}} + \int_{\text{LHS endcap portion of Gaussian surface}} \vec{E}(\vec{r}) \cdot d\vec{A}_{\text{LHS endcap}} + \int_{\text{RHS endcap portion of Gaussian surface}} \vec{E}(\vec{r}) \cdot d\vec{A}_{\text{RHS endcap}}$$

Again, from cylindrical symmetry (here):

$$E(\vec{r}) = |\vec{E}(\vec{r})| = \underline{\text{constant}} \text{ on cylindrical Gaussian surface - i.e. fixed } r = |\vec{r}| = s$$

What are  $d\vec{A}_{\text{cyl.}}$ ,  $d\vec{A}_{\text{LHS endcap}}$ , and  $d\vec{A}_{\text{RHS endcap}}$  ???

$$d\vec{A}_{\text{cyl.}} = \underbrace{s dl d\phi}_{\text{infinitesimal surface area element of Gaussian cylinder}} \hat{r} \leftarrow (\hat{n}_{\text{cyl.}} = \hat{r}) \qquad d\vec{A}_{\text{LHS endcap}} = s ds d\phi (-\hat{z}) = -s ds d\phi \hat{z} \leftarrow (\hat{n}_{\text{LHS endcap}} = -\hat{z})$$

infinitesimal surface area

element of Gaussian cylinder

$$d\vec{A}_{\text{RHS endcap}} = s ds d\phi (+\hat{z}) = +s ds d\phi \hat{z} \leftarrow (\hat{n}_{\text{RHS endcap}} = +\hat{z})$$

$$\therefore \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \int_{\text{Cyl. Gaussian surface}} \underbrace{(E(\vec{r})\hat{r}) \cdot (s dl d\phi \hat{r})}_{\hat{r} \cdot \hat{r} = 1} + \int_{\text{LHS Gaussian endcap}} \underbrace{(E(\vec{r})\hat{r}) \cdot (-s ds d\phi \hat{z})}_{\hat{r} \cdot \hat{z} = 0} + \int_{\text{RHS Gaussian endcap}} \underbrace{(E(\vec{r})\hat{r}) \cdot (+s ds d\phi \hat{z})}_{\hat{r} \cdot \hat{z} = 0}$$

Note(s):

$$E(\vec{r}) = |\vec{E}(\vec{r})| = \text{constant on cylindrical Gaussian surface (fixed } r = s)$$

$$\vec{E}(\vec{r}) = E(\vec{r})\hat{r} \text{ by symmetry of charged cylinder}$$

On LHS and RHS endcaps  $\vec{E}(\vec{r})$  is not constant, because  $r$  is changing there - (but  $\vec{E}$  still points in  $\hat{r}$  direction! However, note that  $\hat{r} \cdot \hat{r} = 1$  and  $\hat{r} \cdot (\pm \hat{z}) \equiv 0 \Rightarrow$  Gaussian endcap terms do not contribute!!!

Constant here

$$\therefore \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \int_{\text{cylindrical Gaussian surface}} \underbrace{E(\vec{r})}_{\text{constant here}} s dl d\phi = E(\vec{r}) s \int_{z=0}^{z=l} \int_{\phi=0}^{\phi=2\pi} dl d\phi = E(\vec{r}) sl (2\pi) = 2\pi sl E(\vec{r})$$

Putting this all together now:  $\oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \frac{Q_{\text{encl}}}{\epsilon_0}$  where (here):  $Q_{\text{encl}} = \frac{2}{3} \pi k l s^3$

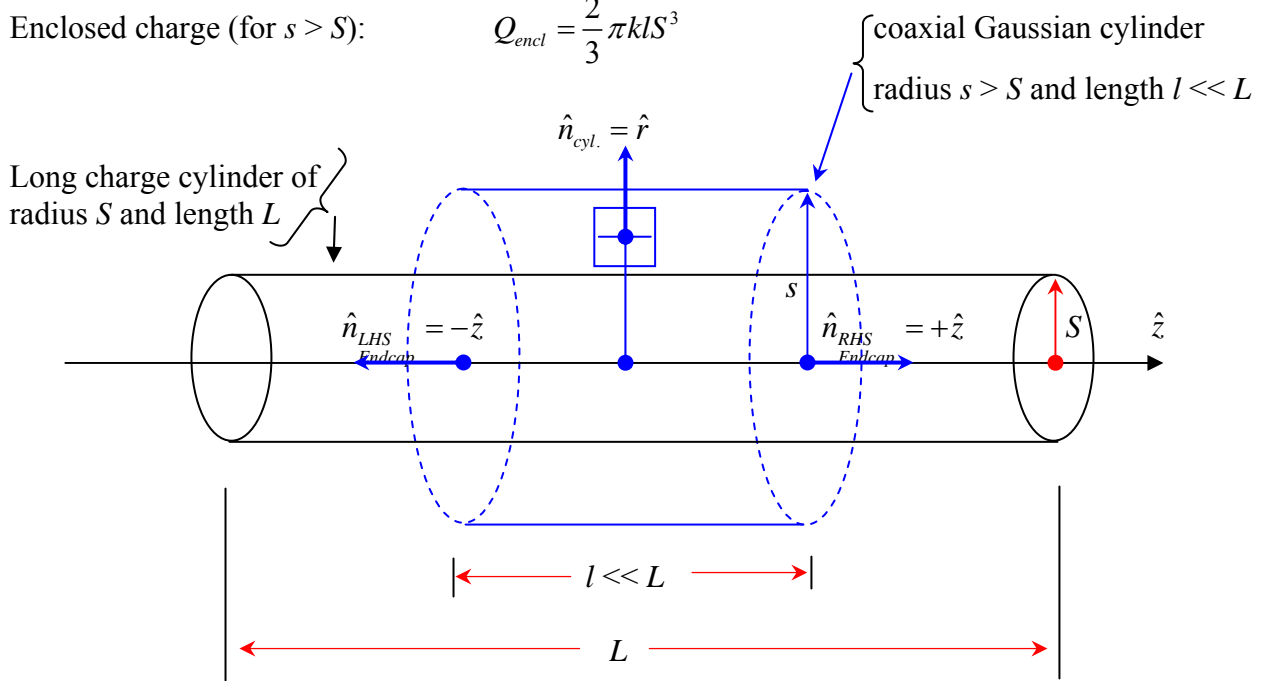
$$\cancel{2\pi s} / E(\vec{r}) = \frac{\cancel{2\pi ks^3} /}{3\epsilon_o} \quad \text{or:} \quad \boxed{\begin{array}{l} \text{inside} \\ \vec{E}_{in}(\vec{r}) = \frac{ks^2}{3\epsilon_o} \hat{r} \\ (s = r < S) \end{array}} \quad \text{n.b. } (\hat{r} \equiv \hat{s}) \leftarrow \text{as used in Griffith's book, page 73}$$

b) Find ELECTRIC FIELD  $\vec{E}(\vec{r})$  outside of this long cylinder / charged plastic rod  
 Again, use Coaxial Gaussian cylinder of length  $l \ll L$  and radius  $s (> S)$ :

**Gauss' Law:**  $\oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \frac{Q_{encl}}{\epsilon_o}$

Enclosed charge (for  $s > S$ ):

$$Q_{encl} = \frac{2}{3} \pi k l S^3$$



Again, from symmetry of long cylinder  $\vec{E}(\vec{r}) = E(\vec{r}) \hat{r} = \text{constant (radial) direction!!}$   
 $r = s$  (fixed radius)

$$\oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \int_{\text{cylindrical Gaussian surface}} \vec{E}(\vec{r}) \cdot d\vec{A}_{cyl} + \int_{\text{LHS Gaussian endcap}} \vec{E}(\vec{r}) \cdot d\vec{A}_{LHS} + \int_{\text{RHS Gaussian endcap}} \vec{E}(\vec{r}) \cdot d\vec{A}_{RHS}$$

$$\begin{aligned} d\vec{A}_{cyl} &= s dl d\varphi \hat{r} \\ &= |d\vec{A}_{cyl}| \hat{r} = dA_{cyl} \hat{r} \\ d\vec{A}_{LHS} &= s ds d\varphi (-\hat{z}) = -s ds d\varphi \hat{z} = \left| d\vec{A}_{LHS} \right| (-\hat{z}) \\ d\vec{A}_{RHS} &= s ds d\varphi (+\hat{z}) = +s ds d\varphi \hat{z} = \left| d\vec{A}_{RHS} \right| (+\hat{z}) \end{aligned}$$

Now:  $\hat{r} \cdot \hat{r} = 1$  and  $\hat{r} \cdot (\pm \hat{z}) \equiv 0$

Then:

$$\oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \int_{\text{cylindrical Gaussian surface}} (E(\vec{r}) \hat{r}) \cdot (dA_{\text{cyl}} \hat{r}) + \int_{\text{LHS Gaussian endcap}} (E(\vec{r}) \hat{r}) \cdot (-dA_{\text{LHS}} \hat{z}) + \int_{\text{RHS Gaussian endcap}} (E(\vec{r}) \hat{r}) \cdot (dA_{\text{RHS}} \hat{z})$$

$$= E(\vec{r}) \int_{z=0}^{z=l} \int_{\phi=0}^{\phi=2\pi} s dl d\phi = 2\pi s l E(\vec{r})$$

∴ Electric field outside charged rod ( $s = r > S$ ):  $E_{\text{out}}(\vec{r}) = \frac{2\pi k \lambda S^3}{3 \cdot 2\pi s \lambda \epsilon_0} \hat{r} = \frac{kS^3}{3s\epsilon_0} \hat{r}$

ELECTRIC FIELD (INSIDE/OUTSIDE) vs. radial distance $s$	LONG CHARGED CYLINDER (radius $S$ , $\rho(s) = ks$ )
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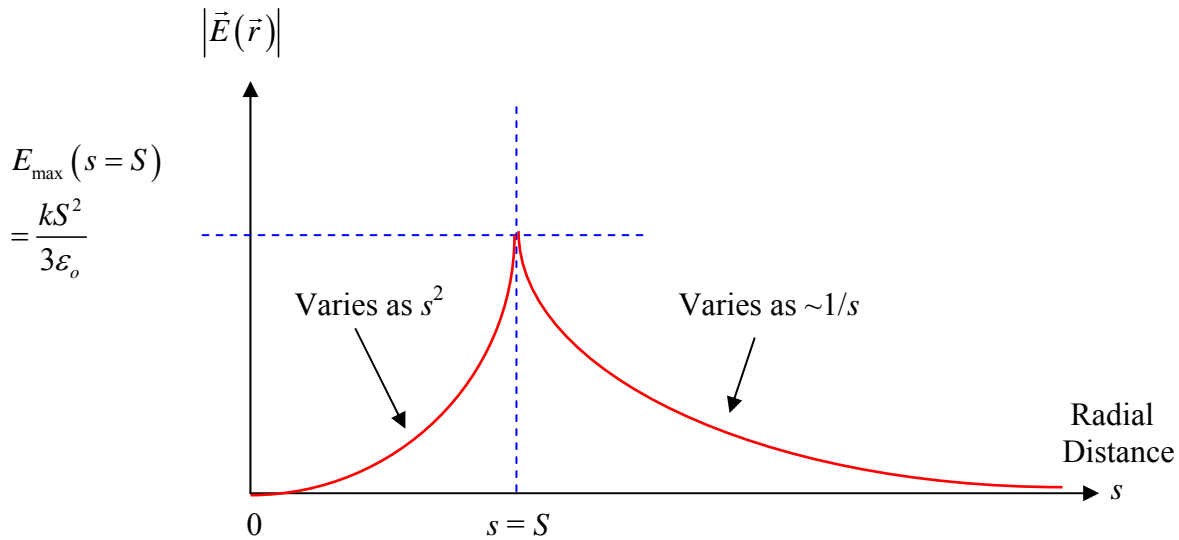
Inside ( $s < S$ ):

$$\vec{E}_{\text{in}}(\vec{r}) = \frac{ks^2}{3\epsilon_0} \hat{s}$$

Outside ( $s > S$ ):

$$\vec{E}_{\text{out}}(\vec{r}) = \frac{kS^3}{3\epsilon_0} \left(\frac{1}{s}\right) \hat{s} \quad (\hat{s} = \hat{r})$$

Make a plot of  $|\vec{E}(\vec{r})|$  vs. radial distance  $s$ :

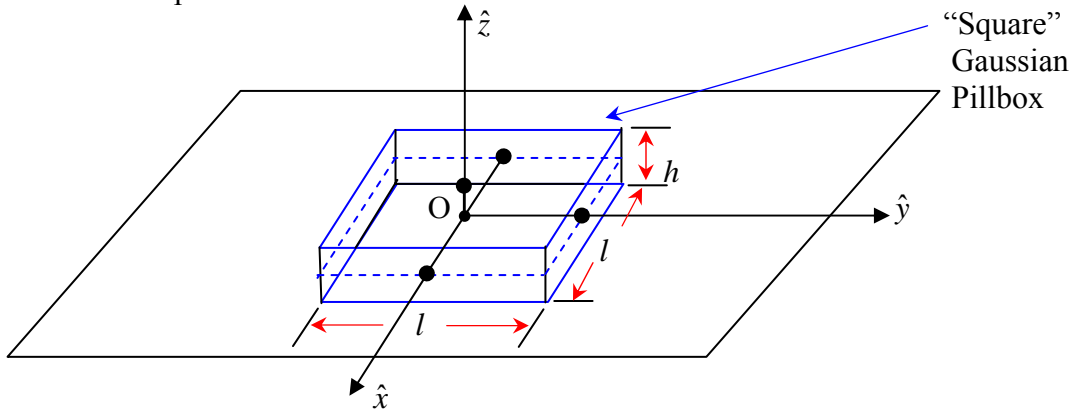




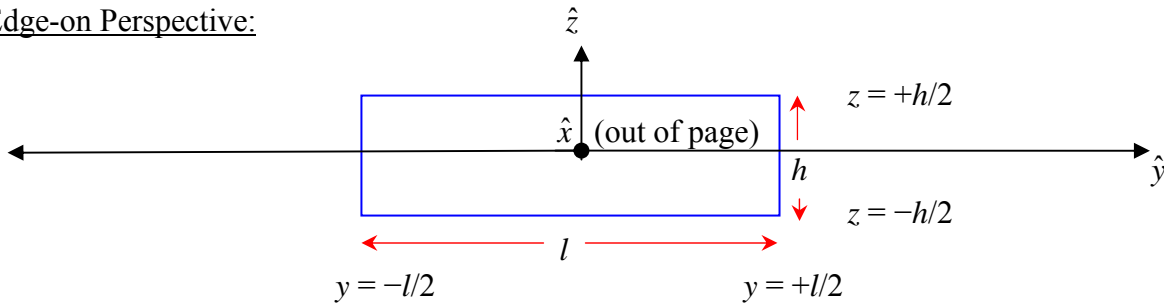
APPLICATIONS OF GAUSS' LAW - very explicit / detailed derivation –

**Griffiths Example 2.4:** An infinite plane carries uniform charge  $\sigma$  (coulombs / meter<sup>2</sup>). Find the electric field a distance  $z = z_0$  above (or below) the plane.

Use Gaussian Pillbox centered on  $\infty$ -plane:



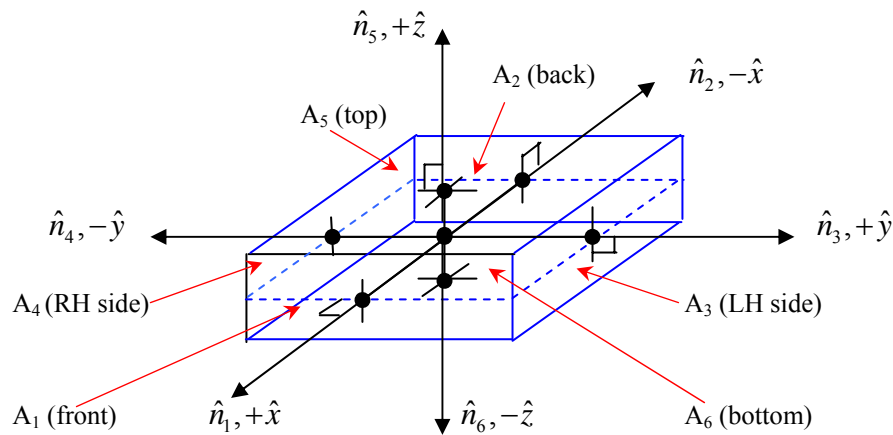
Edge-on Perspective:



Again, from the symmetry associated with  $\infty$ -plane,

$$\vec{E}(\vec{r}) = E(\vec{r})\hat{z} = E(z)\hat{z} \text{ (above plane), } = -E(z)\hat{z} \text{ (below plane)}$$

The Gaussian Pillbox has 6 sides – and thus has six outward unit normal vectors: :



Then:

$$\oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \int_{A_1} \vec{E}(\vec{r}) \cdot d\vec{A}_1 + \int_{A_2} \vec{E}(\vec{r}) \cdot d\vec{A}_2 + \int_{A_3} \vec{E}(\vec{r}) \cdot d\vec{A}_3 \\ + \int_{A_4} \vec{E}(\vec{r}) \cdot d\vec{A}_4 + \int_{A_5} \vec{E}(\vec{r}) \cdot d\vec{A}_5 + \int_{A_6} \vec{E}(\vec{r}) \cdot d\vec{A}_6$$

$$\begin{aligned} d\vec{A}_1 &= +dydz \hat{x} & d\vec{A}_2 &= dydz(-\hat{x}) = -dydz \hat{x} \\ d\vec{A}_3 &= +dxdz \hat{y} & d\vec{A}_4 &= dxdz(-\hat{y}) = -dxdz \hat{y} \\ d\vec{A}_5 &= +dxdy \hat{z} & d\vec{A}_6 &= dxdy(-\hat{z}) = -dxdy \hat{z} \end{aligned}$$

$$\begin{aligned} \text{for } z > 0: & \quad \vec{E}(\vec{r}) = +E(z) \hat{z} \\ \text{for } z < 0: & \quad \vec{E}(\vec{r}) = E(z)(-\hat{z}) = -E(z) \hat{z} \end{aligned} \quad \left. \vphantom{\begin{aligned} \text{for } z > 0: \\ \text{for } z < 0: \end{aligned}} \right\} \begin{array}{l} \text{Again, by symmetry (of plane)} \\ \text{n.b. } E(z) = \text{constant (at least for} \\ \text{fixed } z). \end{array}$$

Now because  $\vec{E}(\vec{r}) = \pm E(z) \hat{z}$  for  $\begin{cases} z > 0 \\ z < 0 \end{cases}$  respectively, we must break up integrals over  $z$  into two separate regions:  $\int_{z=-h/2}^{z=+h/2} dz = \int_{z=-h/2}^{z=0} dz + \int_{z=0}^{z=+h/2} dz$

Then:

$$\begin{aligned} \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} &= \int_{y=-1/2}^{y=+1/2} \int_{z=-h/2}^{z=+h/2} \vec{E}(\vec{r}) \cdot (dydz \hat{x}) + \int_{y=-1/2}^{y=+1/2} \int_{z=-h/2}^{z=+h/2} \vec{E}(\vec{r}) \cdot (-dydz \hat{x}) \\ &+ \int_{x=-1/2}^{x=+1/2} \int_{z=-h/2}^{z=+h/2} \vec{E}(\vec{r}) \cdot (dxdz \hat{y}) + \int_{x=-1/2}^{x=+1/2} \int_{z=-h/2}^{z=+h/2} \vec{E}(\vec{r}) \cdot (-dxdz \hat{y}) \\ &+ \int_{x=-1/2}^{x=+1/2} \int_{y=-1/2}^{y=+1/2} \vec{E}(\vec{r}) \cdot (dxdy \hat{z}) + \int_{x=-1/2}^{x=+1/2} \int_{y=-1/2}^{y=+1/2} \vec{E}(\vec{r}) \cdot (-dxdy \hat{z}) \end{aligned}$$

$$\begin{aligned} \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} &= \int_{y=-1/2}^{y=+1/2} \left[ \int_{z=-h/2}^{z=0} (-E(z) \hat{z} \cdot \hat{x}) dydz + \int_{z=0}^{z=+h/2} (+E(z) \hat{z} \cdot \hat{x}) dydz \right] \leftarrow \text{side } A_1 \text{ (front)} \\ &+ \int_{y=-1/2}^{y=+1/2} \left[ \int_{z=-h/2}^{z=0} (-E(z) \hat{z} \cdot (-\hat{x})) dydz + \int_{z=0}^{z=+h/2} (+E(z) \hat{z} \cdot (-\hat{x})) dydz \right] \leftarrow \text{side } A_2 \text{ (back)} \\ &+ \int_{x=-1/2}^{x=+1/2} \left[ \int_{z=-h/2}^{z=0} (-E(z) \hat{z} \cdot \hat{y}) dxdz + \int_{z=0}^{z=+h/2} (+E(z) \hat{z} \cdot \hat{y}) dxdz \right] \leftarrow \text{side } A_3 \text{ (RHS)} \\ &+ \int_{x=-1/2}^{x=+1/2} \left[ \int_{z=-h/2}^{z=0} (-E(z) \hat{z} \cdot (-\hat{y})) dxdz + \int_{z=0}^{z=+h/2} (+E(z) \hat{z} \cdot (-\hat{y})) dxdz \right] \leftarrow \text{side } A_4 \text{ (LHS)} \\ &+ \underbrace{\int_{x=-1/2}^{x=+1/2} \int_{y=-1/2}^{y=+1/2} (-E(z) \hat{z} \cdot (-\hat{z})) dxdy}_{\text{side } A_6 \text{ (bottom)}} + \underbrace{\int_{x=-1/2}^{x=+1/2} \int_{y=-1/2}^{y=+1/2} (+E(z) \hat{z} \cdot \hat{z}) dxdy}_{\text{side } A_5 \text{ (top)}} \end{aligned}$$

$$\text{Now: } (\hat{z} \cdot \hat{x}) = 0 \quad (\hat{z} \cdot \hat{y}) = 0 \quad (\hat{x} \cdot \hat{z}) = 0 \quad (\hat{y} \cdot \hat{z}) = 0 \quad \text{etc.}$$

$$\text{And: } (\hat{x} \cdot \hat{x}) = 1 \quad (\hat{y} \cdot \hat{y}) = 1 \quad (\hat{z} \cdot \hat{z}) = 1$$

∴ Because  $\hat{x} \perp \hat{y} \perp \hat{z}$ , no contributions to  $\oint_S \vec{E} \cdot d\vec{A}$  (here) from 4 sides of Gaussian Pillbox  
(i.e.  $A_1, A_2, A_3$  and  $A_4$ )

⇒ Only remaining / non-zero contributions are from bottom and top surfaces of Gaussian Pillbox because  $\hat{n}_5 = -\hat{z}$  and  $\hat{n}_6 = +\hat{z}$  which are || (or anti-parallel) to  $E(z)\hat{z}$

Thus, we only have (here):

$$\begin{aligned} \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} &= \int_{x=-l/2}^{x=+l/2} \int_{y=-l/2}^{y=+l/2} (-E(z)\hat{z} \cdot (-\hat{z})) dx dy && \leftarrow \text{side } A_6 \text{ (bottom)} \\ &+ \int_{x=-l/2}^{x=+l/2} \int_{y=-l/2}^{y=+l/2} (+E(z)\hat{z} \cdot \hat{z}) dx dy && \leftarrow \text{side } A_5 \text{ (top)} \end{aligned}$$

These integrals are not over  $z$ , and  $E(z) = \text{constant}$  for  $z = \text{fixed} = z_0$

∴ can pull  $E(z)$  outside integral,  $\hat{z} \cdot \hat{z} = 1$        $-\hat{z} \cdot \hat{z} = -1$       etc.

$$\begin{aligned} \therefore \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} &= +E(z) \int_{x=-l/2}^{x=+l/2} \int_{y=-l/2}^{y=+l/2} dx dy && \leftarrow \text{side } A_6 \text{ (bottom)} \\ &+ E(z) \int_{x=-l/2}^{x=+l/2} \int_{y=-l/2}^{y=+l/2} dx dy && \leftarrow \text{side } A_5 \text{ (top)} \\ &= E(z)l^2 + E(z)l^2 = 2E(z)l^2 \end{aligned}$$

But:  $l^2 = l \times l \equiv A = \text{surface area of top and bottom surfaces of Gaussian Pillbox}$

Now:  $\oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \frac{Q_{encl}}{\epsilon_0}$       What is  $Q_{encl}$  (by Gaussian Pillbox)?

$$Q_{encl} = \sigma \left( \frac{\text{Coulombs}}{\text{meter}^2} \right) \times A (\text{meters}^2) = \sigma l^2 (\text{Coulombs})$$

$$\therefore \oint_S \vec{E}(\vec{r}) \cdot d\vec{A} = \frac{Q_{encl}}{\epsilon_0} \Rightarrow 2E(z)l^2 = \sigma l^2 / \epsilon_0 \quad \text{or:} \quad \boxed{E(z) = \left( \frac{1}{2} \right) \sigma / \epsilon_0 = \frac{\sigma}{2\epsilon_0}}$$

Vectorially:  $\boxed{\vec{E}(z) = \left( \frac{\sigma}{2\epsilon_0} \right) \begin{cases} +\hat{z}, \text{ for } z > 0 \\ -\hat{z}, \text{ for } z < 0 \end{cases}}$       NOTE:  $|\vec{E}(z)| = \text{constant!!}$

No  $z$  - dependence for charged  $\infty$  plane!

$$\vec{E}(\vec{r}) \text{ from } \infty\text{-plane (slight return)}$$

**Note** that in the initial process of setting up the Gaussian Pillbox, if we'd shrunk the height  $h$  of the Pillbox to be infinitesimally small, i.e.  $h \rightarrow \delta h$  and then took the limit  $\delta h \rightarrow 0$ , the contributions to  $\oint_S \vec{E}(\vec{r}) \cdot d\vec{A}$  from (infinitesimally small) sides of ( $A_1, A_2, A_3$  and  $A_4$ ) Gaussian Pillbox would (formally) have vanished (i.e. = 0) independently of whether integrand ( $\vec{E}(\vec{r}) \cdot d\vec{A}$ ) vanished on these sides (or not). Only top and bottom surfaces contribute to  $\oint_S \vec{E}(\vec{r}) \cdot d\vec{A}$  then (here).

So using this “trick” of the shrinking Pillbox at a surface / boundary very often can be useful, to simplify doing the problem.

This explicitly shows that (sometimes) there is more than one way to correctly do / solve a problem – equivalent methods may exist.

→ It is very important, conceptually-speaking to have a (very) clear / good understanding of how to do these Gauss' Law-type problems the “long” way and the “short” way!

The Curl of  $\vec{E}(\vec{r})$ :  $(\vec{\nabla} \times \vec{E}(\vec{r}))$ 

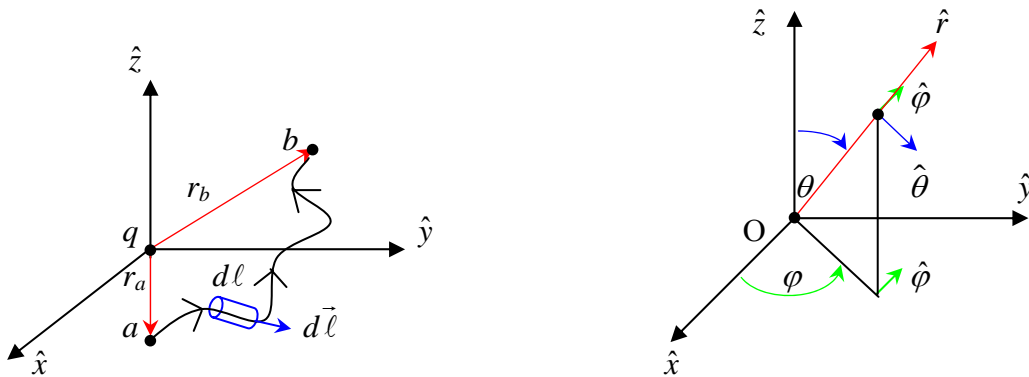
First, study / consider simplest possible situation: point charge at origin:  $\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left( \frac{q}{r^2} \right) \hat{r}$

(note:  $\vec{r} \equiv \vec{r} - \vec{r}' = \vec{r}$  here because  $\vec{r}' = 0$  - charge  $q$  located at origin!!!)

Thus (here),  $\vec{E}(\vec{r})$  is radial (i.e. in  $\hat{r}$  - direction) due to spherical symmetry of problem (rotational invariance), thus static  $\vec{E}$ -field has no rotation/swirl/whirl  $\Rightarrow$  no curl! (Read Griffith's Ch. 1 on curl)  
 $\Rightarrow \vec{\nabla} \times \vec{E}(\vec{r}) = 0$  (must = 0)

Let's calculate:

Line integral  $\int_a^b \vec{E}(\vec{r}) \cdot d\vec{\ell}$  as shown in figure below:



In spherical coordinates:  $d\vec{\ell} = dr\hat{r} + rd\theta\hat{\theta} + r\sin\theta d\phi\hat{\phi}$

$$\vec{E}(\vec{r}) \cdot d\vec{\ell} = \frac{1}{4\pi\epsilon_0} \left( \frac{q}{r^2} \right) \hat{r} \cdot \left\{ dr\hat{r} + rd\theta\hat{\theta} + r\sin\theta d\phi\hat{\phi} \right\}$$

<u>Again:</u>	$\hat{r} \cdot \hat{r} = 1$	$\hat{r} \cdot \hat{\theta} = 0$	$\hat{r} \cdot \hat{\phi} = 0$	}	$\hat{r}, \hat{\theta}, \text{ and } \hat{\phi}$ are mutually orthogonal basis vectors (form <u>ortho-normal</u> basis)
	$\hat{\theta} \cdot \hat{\theta} = 1$	$\hat{\theta} \cdot \hat{r} = 0$	$\hat{\theta} \cdot \hat{\phi} = 0$		
	$\hat{\phi} \cdot \hat{\phi} = 1$	$\hat{\phi} \cdot \hat{r} = 0$	$\hat{\phi} \cdot \hat{\theta} = 0$		

$$\therefore \vec{E}(\vec{r}) \cdot d\vec{\ell} = \frac{1}{4\pi\epsilon_0} \left( \frac{q}{r^2} \right) dr$$

$$\text{Thus: } \int_a^b \vec{E}(\vec{r}) \cdot d\vec{\ell} = \frac{1}{4\pi\epsilon_0} \int_a^b \frac{q}{r^2} dr = \frac{-1}{4\pi\epsilon_0} \left( \frac{q}{r} \right) \Big|_{r_a}^{r_b} = \frac{1}{4\pi\epsilon_0} \left( \frac{q}{r_a} - \frac{q}{r_b} \right) = \frac{q}{4\pi\epsilon_0} \left( \frac{1}{r_a} - \frac{1}{r_b} \right)$$

$r_a$  = distance from origin O to point a.  $r_b$  = distance from origin O to point b.

The line integral  $\int \vec{E}(\vec{r}) \cdot d\vec{\ell}$  around a closed contour  $C$  is zero!

i.e.  $\oint_C \vec{E}(\vec{r}) \cdot d\vec{\ell} = 0$  This is not a trivial result! (Not true  $\forall$  vectors!!)  
 (But *is* true for static  $\vec{E}$ -fields)

Use Stokes' Theorem (See Griffiths, Ch. 1.3.5, p. 34 and Appendix A-5)

$$\boxed{\int_S (\vec{\nabla} \times \vec{E}(\vec{r})) \cdot d\vec{A} = \oint_C \vec{E}(\vec{r}) \cdot d\vec{\ell} = 0}$$

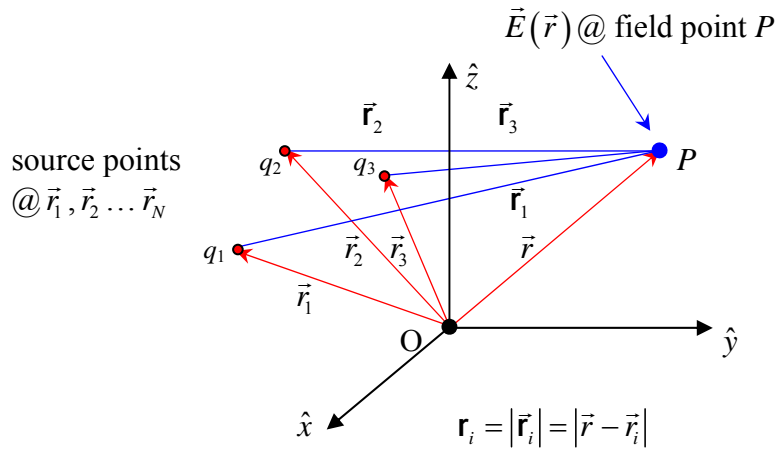
↑ arbitrary closed surface  $S$       ↑ arbitrary closed contour  $C$  (on  $S$ )

Since  $\int_S (\vec{\nabla} \times \vec{E}(\vec{r})) \cdot d\vec{A} = 0$  must be / is true for arbitrary closed surface  $S$ ,

this can only be true for all  $\forall$  closed surfaces  $S$  IFF (if and only if):  $\boxed{\vec{\nabla} \times \vec{E}(\vec{r}) = 0}$

Can use the Principle of Superposition to show that:

$$\begin{aligned} \vec{E}_{TOT}(\vec{r}) &= \sum_{i=1}^N \vec{E}_i(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^N \frac{q_i}{r_i^2} \hat{r}_i \quad \leftarrow i = 1, 2, 3, \dots, N \text{ discrete charges, and } \vec{r}_i = (\vec{r} - \vec{r}_i) \\ &= \vec{E}_1(\vec{r}) + \vec{E}_2(\vec{r}) + \vec{E}_3(\vec{r}) + \dots + \vec{E}_N(\vec{r}) \end{aligned}$$



$$\begin{aligned} \text{Then: } \vec{\nabla} \times \vec{E}_{TOT}(\vec{r}) &= \vec{\nabla} \times \sum_{i=1}^N \vec{E}_i(\vec{r}) = \sum_{i=1}^N (\vec{\nabla} \times \vec{E}_i(\vec{r})) \\ &= \sum_{i=1}^N \vec{\nabla} \times \left( \frac{1}{4\pi\epsilon_0} \left( \frac{q_i}{r_i^2} \right) \hat{r}_i \right) = 0 \quad \leftarrow \text{n.b. all individual terms} = 0 \text{ !!!} \end{aligned}$$

$$\text{or: } \vec{\nabla} \times \vec{E}_{TOT}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^N q_i \vec{\nabla} \times \left( \frac{1}{r_i^2} \right) \hat{r}_i = 0$$

It can be shown that  $\boxed{\vec{\nabla} \times \vec{E}(\vec{r}) = 0}$  FOR ANY STATIC CHARGE DISTRIBUTION  
 STATIC = NO TIME DEPENDENCE / VARIATION

$\vec{\nabla} \times \vec{E}(\vec{r}) = 0$  HOLDS FOR:

- Static Discrete/Point Charges       $q(\vec{r})$
  - Static Line Charges                       $\lambda(\vec{r})$
  - Static Surface Charges                   $\sigma(\vec{r})$
  - Static Volume Charges                   $\rho(\vec{r})$
- All Static Charge Distributions

Again, this not trivial (we'll see why, soon. . .)

One other (very important) point about the mathematical & geometrical nature of vector fields:

The nature of a (physically-realizable) vector field  $\vec{A}(\vec{r})$  is fully specified if both its divergence  $\vec{\nabla} \cdot \vec{A}(\vec{r})$  and its curl  $\vec{\nabla} \times \vec{A}(\vec{r})$  are known.

This is a consequence of the so-called Helmholtz theorem – see/read Appendix B of Griffiths book.

The Helmholtz theorem also has an important corollary:

Any differentiable vector function  $\vec{A}(\vec{r})$  that goes to zero faster than  $1/r$  as  $r \rightarrow \infty$  can be expressed as the gradient of a scalar plus the curl of a vector:

$$\vec{A}(\vec{r}) = \vec{\nabla} \left( -\frac{1}{4\pi} \int_{v'} \frac{\vec{\nabla}' \cdot \vec{A}(\vec{r}')}{r} d\tau' \right) + \vec{\nabla} \times \left( \frac{1}{4\pi} \int_{v'} \frac{\vec{\nabla}' \times \vec{A}(\vec{r}')}{r} d\tau' \right)$$

For the case of electrostatics:  $\vec{\nabla} \cdot \vec{E}(\vec{r}) = \rho(\vec{r})/\epsilon_0$  and  $\vec{\nabla} \times \vec{E}(\vec{r}) = 0$

Thus:

$$\vec{E}(\vec{r}) = \vec{\nabla} \left( -\frac{1}{4\pi} \int_{v'} \frac{\vec{\nabla}' \cdot \vec{E}(\vec{r}')}{r} d\tau' \right) + \vec{\nabla} \times \left( \frac{1}{4\pi} \int_{v'} \frac{\vec{\nabla}' \times \vec{E}(\vec{r}')}{r} d\tau' \right)$$

$$= -\frac{1}{4\pi\epsilon_0} \vec{\nabla} \left( \int_{v'} \frac{\rho(\vec{r}')}{r} d\tau' \right) = -\vec{\nabla} V(\vec{r})$$

i.e.  $\vec{E}(\vec{r}) = -\vec{\nabla} V(\vec{r})$  with  $V(\vec{r}) \equiv \frac{1}{4\pi\epsilon_0} \int_{v'} \frac{\rho(\vec{r}')}{r} d\tau' =$  Electrostatic Potential SI Units:  
Volts

This result is valid e.g. in electrostatics for localized (i.e. finite spatial extent) charge distributions.

For infinite-expanse charge distributions (n.b. these are unphysical/artificial!), we must appeal to (more sophisticated) mathematical formalisms than the Helmholtz theorem...